

On Lorentzian α -Sasakian Manifolds

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ABSTRACT. The present paper deals with Lorentzian α -Sasakian manifolds with conformally flat and quasi conformally flat curvature tensor. It is shown that in both cases, the manifold is locally isometric with a sphere $S^{2^n+1}(c)$. Further it is shown that an Lorentzian α -Sasakian manifold with $R(X, Y).C = 0$ is locally isometric with a sphere $S^{2^n+1}(c)$, where $c = \alpha^2$.

0. Introduction

In [9], S. Tanno classified connected almost contact metric manifolds whose automorphism groups possess the maximum dimension. For such a manifold, the sectional curvature of plane sections containing ξ is a constant, say c . He showed that they can be divided into three classes:

- (1) homogeneous normal contact Riemannian manifolds with $c > 0$,
- (2) global Riemannian products of a line or a circle with a Kaehler manifold of constant holomorphic sectional curvature if $c = 0$ and
- (3) a warped product space $\mathbb{R} \times_f \mathbb{C}$ if $c < 0$.

It is known that the manifolds of class (1) are characterized by admitting a Sasakian structure. Kenmotsu ([18]) characterized the differential geometric properties of the manifolds of class (3); the structure so obtained is now known as Kenmotsu structure. In general, these structures are not Sasakian ([18]).

In the Gray-Hervella classification of almost Hermitian manifolds ([13]), there appears a class, W_4 , of Hermitian manifolds which are closely related to locally

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conformal Kaehler manifolds ([20]). An almost contact metric structure on a manifold M is called a trans-Sasakian structure ([11]) if the product manifold $M \times \mathbb{R}$ belongs to the class W_4 . The class $C_6 \oplus C_5$ ([16], [18]) coincides with the class of the trans-Sasakian structures of type (α, β) . In fact, in [18], local nature of the two subclasses, namely, C_5 and C_6 structures, of trans-Sasakian structures are characterized completely.

We note that trans-Sasakian structures of type $(0, 0)$, $(0, \beta)$ and $(\alpha, 0)$ are cosymplectic ([1]), β -Kenmotsu ([19]) and α -Sasakian ([19]) respectively. In ([12]) it is proved that trans-Sasakian structures are generalized quasi-Sasakian ([17]). Thus, trans-Sasakian structures also provide a large class of generalized quasi-Sasakian structures.

An almost contact metric structure (ϕ, ξ, η, g) on M is called a *trans-Sasakian structure* ([11]) if $(M \times \mathbb{R}, J, G)$ belongs to the class W_4 ([13]), where J is the almost complex structure on $M \times \mathbb{R}$ defined by

$$J(X, fd/dt) = (\phi X - f\xi, \eta(X)fd/dt)$$

for all vector fields X on M and smooth functions f on $M \times \mathbb{R}$, and G is the product metric on $M \times \mathbb{R}$. This may be expressed by the condition ([21])

$$(\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X) + \beta(g(\phi X, Y)\xi - \eta(Y)\phi X)$$

for some smooth functions α and β on M , and we say that the trans-Sasakian structure is of type (α, β) .

Let (x, y, z) be Cartesian coordinates in \mathbb{R}^3 , then (ϕ, ξ, η, g) given by

$$\xi = \partial/\partial z, \quad \eta = dz - ydx, \quad \phi = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & -y & 0 \end{pmatrix}, \quad g = \begin{pmatrix} e^z + y^2 & 0 & -y \\ 0 & e^z & 0 \\ -y & 0 & 1 \end{pmatrix}$$

is a trans-Sasakian structure of type $(-1/(2e^z), 1/2)$ in \mathbb{R}^3 ([21]). In general, in a 3-dimensional K -contact manifold with structures tensors (ϕ, ξ, η, g) for a non-constant function f , if we define $g' = fg + (1 - f)\eta \otimes \eta$; then (ϕ, ξ, η, g') is a trans-Sasakian structure of type $(1/f, (1/2)\xi(\ln f))$ ([14], [15], [16]).

Corollary 1 ([7]). *A trans-Sasakian structure of type (α, β) with α a nonzero constant is always α -Sasakian.*

In this case α becomes a constant. If $\alpha = 1$, then α -Sasakian manifold is Sasakian.

In this paper, we investigate Lorentzian α -Sasakian manifolds in which

$$(1) \quad C = 0$$

where C is the Weyl conformal curvature tensor. Then we study Lorentzian α -Sasakian manifolds in which

$$(2) \quad \tilde{C} = 0$$

where \tilde{C} is the quasi conformal curvature tensor. In the both cases, it is shown that an Lorentzian α -Sasakian manifold is isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$. Finally, an Lorentzian α -Sasakian manifold with

$$(3) \quad R(X, Y).C = 0$$

has been considered, where $R(X, Y)$ is considered as a derivation of the tensor algebra at each point of the manifold of tangent vectors X, Y . It is easy to see that $R(X, Y).R = 0$ implies $R(X, Y).C = 0$. So it is meaningful to undertake the study of manifolds satisfying the condition (3).

1. Preliminaries

A differentiable manifold of dimension $(2n + 1)$ is called Lorentzian α -Sasakian manifold if it admits a $(1, 1)$ -tensor field ϕ , a contravariant vector field ξ , a covariant vector field η and Lorentzian metric g which satisfy ([2], [3], [4], [5], [6], [7])

$$(4) \quad \eta(\xi) = -1,$$

$$(5) \quad \phi^2 = I + \eta \otimes \xi,$$

$$(6) \quad g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y),$$

$$(7) \quad g(X, \xi) = \eta(X),$$

$$(8) \quad \phi\xi = 0, \quad \eta(\phi X) = 0$$

for all $X, Y \in TM$.

Also an Lorentzian α -Sasakian manifold M is satisfying ([8])

$$(9) \quad \nabla_X \xi = -\alpha\phi X,$$

$$(10) \quad (\nabla_X \eta)Y = -\alpha g(\phi X, Y).$$

where ∇ denotes the operator of covariant differentiation with respect to the Lorentzian metric g .

An Lorentzian α -Sasakian manifold M is said to be η -Einstein if its Ricci tensor S is of the form

$$(11) \quad S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y)$$

for any vector fields X, Y , where a, b are functions on M .

Further, on an Lorentzian α -Sasakian manifold M the following relations hold ([7], [10])

$$(12) \quad R(\xi, X)Y = \alpha^2(g(X, Y)\xi - \eta(Y)X),$$

$$(13) \quad R(X, Y)\xi = \alpha^2(\eta(Y)X - \eta(X)Y),$$

$$(14) \quad R(\xi, X)\xi = \alpha^2(\eta(X)\xi + X),$$

$$(15) \quad S(X, \xi) = 2n\alpha^2\eta(X),$$

$$(16) \quad Q\xi = 2n\alpha^2\xi,$$

$$(17) \quad S(\xi, \xi) = -2n\alpha^2,$$

where S is the Ricci curvature and Q is the Ricci operator given by $S(X, Y) = g(QX, Y)$.

2. Lorentzian α -Sasakian manifolds with $C = 0$

The conformal curvature tensor C on M^{2n+1} is defined as

$$(18) \quad C(X, Y)Z = R(X, Y)Z + \frac{1}{2n-1} \left[\begin{array}{l} S(X, Z)Y - S(Y, Z)X \\ +g(X, Z)QY - g(Y, Z)QX \end{array} \right] \\ - \frac{\tau}{2n(2n-1)} [g(X, Z)Y - g(Y, Z)X]$$

where

$$S(X, Y) = g(QX, Y).$$

Using (1) we get from (18)

$$(19) \quad R(X, Y)Z = \frac{1}{2n-1} \left[\begin{array}{l} S(Y, Z)X - S(X, Z)Y \\ +g(Y, Z)QX - g(X, Z)QY \end{array} \right] \\ + \frac{\tau}{2n(2n-1)} [g(X, Z)Y - g(Y, Z)X].$$

Taking $Z = \xi$ in (19) and using (7), (13) and (15), we find

$$\left(\alpha^2 + \frac{\tau}{2n(2n-1)} - \frac{2n\alpha^2}{(2n-1)} \right) (\eta(Y)X - \eta(X)Y) \\ = \frac{1}{2n-1} (\eta(Y)QX - \eta(X)QY).$$

Taking $Y = \xi$ and using (4) we get

$$(20) \quad QX = \left(\frac{\tau}{2n} - \alpha^2 \right) X + \left(\frac{\tau}{2n} - \alpha^2 - 2n\alpha^2 \right) \eta(X)\xi.$$

Thus the manifold is η -Einstein.

Contracting (20) we get

$$(21) \quad \tau = 2n(2n+1)\alpha^2.$$

Using (21) in (20) we find

$$(22) \quad QX = 2n\alpha^2 X.$$

Putting (22) in (19) we get after a few steps

$$(23) \quad R(X, Y)Z = \alpha^2(g(Y, Z)X - g(X, Z)Y).$$

Thus a conformally flat Lorentzian α -Sasakian manifold is of constant curvature. The value of this constant is α^2 . Hence we can state.

Theorem 2. *A conformally flat Lorentzian α -Sasakian manifold is locally isometric to a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.*

3. Lorentzian α -Sasakian manifolds with $\tilde{C} = 0$

The quasi conformal curvature tensor \tilde{C} on M^{2n+1} is defined as

$$(24) \quad \begin{aligned} \tilde{C}(X, Y)Z &= aR(X, Y)Z + b\{S(Y, Z)X - S(X, Z)Y \\ &\quad + g(Y, Z)QX - g(X, Z)QY\} \\ &\quad - \frac{\tau}{(2n+1)}\left(\frac{a}{2n} + 2b\right)\{g(Y, Z)X - g(X, Z)Y\} \end{aligned}$$

where a, b are constants such that $ab \neq 0$ and

$$S(Y, Z) = g(QY, Z).$$

Using (2), we find from (24)

$$(25) \quad \begin{aligned} R(X, Y)Z &= -\frac{b}{a}\{S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY\} \\ &\quad + \left\{\frac{\tau}{(2n+1)a}\left(\frac{a}{2n} + 2b\right)\right\}\{g(Y, Z)X - g(X, Z)Y\}. \end{aligned}$$

Taking $Z = \xi$ in (25) and using (7), (13) and (15), we get

$$(26) \quad \begin{aligned} \alpha^2(\eta(Y)X - \eta(X)Y) &= -\frac{b}{a}\{\eta(Y)QX - \eta(X)QY\} \\ &\quad + \left\{\frac{\tau}{(2n+1)a}\left(\frac{a}{2n} + 2b\right) - \frac{2n\alpha^2 b}{a}\right\}(\eta(Y)X - \eta(X)Y). \end{aligned}$$

Taking $Y = \xi$ and applying (4) we have

$$(27) \quad \begin{aligned} QX &= \left\{\frac{\tau}{(2n+1)b}\left(\frac{a}{2n} + 2b\right) - 2n\alpha^2 - \frac{a}{b}\alpha^2\right\}X \\ &\quad + \left\{\frac{\tau}{(2n+1)b}\left(\frac{a}{2n} + 2b\right) - 4n\alpha^2 - \frac{a}{b}\alpha^2\right\}\eta(X)\xi. \end{aligned}$$

Contracting (27), we get after a few steps

$$(28) \quad \tau = 2n(2n+1)\alpha^2.$$

Using (28) in (27), we get

$$(29) \quad QX = 2n\alpha^2 X.$$

Finally, using (29), we find from (25)

$$R(X, Y)Z = \alpha^2 \{g(Y, Z)X - g(X, Z)Y\}.$$

Thus we can state

Theorem 3. *A quasi conformally flat Lorentzian α -Sasakian manifold is locally isometric to a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.*

4. Lorentzian α -Sasakian manifolds satisfying $R(X, Y).C = 0$

Using (7), (12) and (15) we take $X = \xi$, we find from (18)

$$(30) \quad \eta(C(X, Y)Z) = \frac{1}{2n-1} \left[\left(\frac{\tau}{2n} - \alpha^2 \right) \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\} - \{S(Y, Z)\eta(X) - S(X, Z)\eta(Y)\} \right].$$

Putting $Z = \xi$ in (30) and using (7) and (15), we get

$$(31) \quad \eta(C(X, Y)\xi) = 0.$$

Again $X = \xi$ in (30)

$$(32) \quad \begin{aligned} \eta(C(\xi, Y)Z) &= \left(\alpha^2 - \frac{2n\alpha^2}{2n-1} + \frac{\tau}{2n(2n+1)} \right) g(Y, Z) \\ &\quad - \left(\alpha^2 - \frac{4n\alpha^2}{2n-1} + \frac{\tau}{2n(2n+1)} \right) \eta(Y)\eta(Z) \\ &\quad - \frac{1}{2n-1} S(Y, Z). \end{aligned}$$

Now

$$(33) \quad \begin{aligned} (R(\xi, Y)C)(U, V)W &= R(\xi, Y)C(U, V)W - C(R(\xi, Y)U, V)W \\ &\quad - C(U, R(\xi, Y)V)W - C(U, V)R(\xi, Y)W. \end{aligned}$$

Using (3), we find from above

$$\begin{aligned} &g[R(\xi, Y)C(U, V)W, \xi] - g[C(R(\xi, Y)U, V)W, \xi] \\ &\quad - g[C(R(\xi, Y)UV)W, \xi] - g[C(U, V)R(\xi, Y)W, \xi] = 0. \end{aligned}$$

Using (7) and (12) we get

$$(34) \quad \begin{aligned} & -\alpha^2 g(C(U, V)W, Y) - \alpha^2 \eta(Y)\eta(C(U, V)W) - \alpha^2 g(Y, U)\eta(C(\xi, V)W) \\ & + \alpha^2 \eta(U)\eta(C(Y, V)W) - \alpha^2 g(Y, V)\eta(C(U, \xi)W) + \alpha^2 \eta(V)\eta(C(U, Y)W) \\ & - \alpha^2 g(Y, W)\eta(C(U, V)\xi) + \alpha^2 \eta(W)\eta(C(U, V)Y) = 0. \end{aligned}$$

Putting $U = Y$ in (34)

$$(35) \quad \begin{aligned} & -\alpha^2 g(C(U, V)W, U) - \alpha^2 \eta(U)\eta(C(U, V)W) - \alpha^2 g(U, U)\eta(C(\xi, V)W) \\ & + \alpha^2 \eta(U)\eta(C(U, V)W) - \alpha^2 g(U, V)\eta(C(U, \xi)W) + \alpha^2 \eta(V)\eta(C(U, U)W) \\ & - \alpha^2 g(U, W)\eta(C(U, V)\xi) + \alpha^2 \eta(W)\eta(C(U, V)U) = 0. \end{aligned}$$

Let $\{\tilde{e}_i : i = 1, \dots, 2n+1\}$ be an orthonormal basis of the tangent space at any point, then the sum for $1 \leq i \leq n$ of the relations (35) for $U = \tilde{e}_i$ gives

$$(36) \quad \begin{aligned} -2n\alpha^2 \eta(C(\xi, V)W) &= 0, \\ \eta(C(\xi, V)W) &= 0 \quad \text{as } n > 1. \end{aligned}$$

Using (31) and (36), (34) takes the form

$$(37) \quad \begin{aligned} & -\alpha^2 g(C(U, V)W, Y) - \alpha^2 \eta(Y)\eta(C(U, V)W) + \alpha^2 \eta(U)\eta(C(Y, V)W) \\ & + \alpha^2 \eta(V)\eta(C(U, Y)W) + \alpha^2 \eta(W)\eta(C(U, V)Y) \\ & = 0. \end{aligned}$$

Using (30) in (37), we get

$$(38) \quad \begin{aligned} & -\alpha^2 g(C(U, V)W, Y) \\ & + \alpha^2 \eta(W) \frac{1}{2n-1} \left[\left(\frac{\tau}{2n} - 1 \right) \{ \eta(U)g(Y, V) - \eta(V)g(U, Y) \} \right. \\ & \quad \left. - \{ \eta(U)S(Y, V) - \eta(V)S(U, Y) \} \right] \\ & = 0. \end{aligned}$$

In virtue of (36), (32) reduces to

$$(39) \quad S(Y, Z) = \left(\frac{\tau}{2n} - \alpha^2 \right) g(Y, Z) + \left(\frac{\tau}{2n+1} - (2n+1)\alpha^2 \right) \eta(Y)\eta(Z).$$

Using (39), (37) reduces to

$$(40) \quad -\alpha^2 g(C(U, V)W, Y) = 0,$$

i.e.,

$$(41) \quad C(U, V)W = 0.$$

Hence the manifold is conformally flat. Using the Theorem 1, we state

Theorem 4. *If in an Lorentzian α -Sasakian manifold M^{2n+1} ($n \geq 1$) the relation $R(X, Y).C = 0$ holds, then it is locally isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.*

For a conformally symmetric Riemannian manifold [1], we have $\nabla C = 0$. Hence for such a manifold $R(X, Y).C = 0$ holds. Thus we have the following corollary of the above theorem:

Corollary 5. *A conformally symmetric Lorentzian α -Sasakian manifold M^{2n+1} ($n \geq 1$) is locally isometric with a sphere $S^{2n+1}(c)$, where $c = \alpha^2$.*

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