# QUATERNIONIC HEISENBERG GROUP 

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#### Abstract

We shall study the automorphism group of the quaternionic Heisenberg group $\mathcal{H}_{7}(\mathbb{H})=\mathbb{R}^{3} \tilde{\times} \mathbb{H}$ which is important to investigate an almost Bieberbach group of a 7-dimensinal infra-nilmanifold and show that $\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \cong \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)$.


## 1. Introduction

The complex Heisenberg group $\mathcal{H}_{2 n+1}(\mathbb{C})=\mathbb{R} \tilde{x} \mathbb{C}^{n}$ with group operation given by

$$
(s, z)\left(t, z^{\prime}\right)=\left(s+t+2 \operatorname{Im}\left\{z \bar{z}^{\prime}\right\}, z+z^{\prime}\right)
$$

for $z=\left(z_{1}, z_{2}, \cdots, z_{n}\right), z^{\prime}=\left(z_{1}^{\prime}, z_{2}^{\prime}, \cdots, z_{n}^{\prime}\right) \in \mathbb{C}^{n}$, where $\operatorname{Im}\left\{z \bar{z}^{\prime}\right\}$ is the imaginary part of the complex number $z_{1} \bar{z}_{1}^{\prime}+z_{2} \bar{z}_{2}^{\prime}+\cdots+z_{n} \bar{z}_{n}^{\prime}$ is a simply connected 2-step nilpotent Lie group with the center $\mathcal{Z}\left(\mathcal{H}_{2 n+1}(\mathbb{C})\right)=\mathbb{R}$. Let $M$ be an infra-nilmanifold with $\mathcal{H}_{2 n+1}(\mathbb{C})$ geometry. It is well known (see for example [4]) that an almost Bieberbach group contains a cocompact lattice of $\mathcal{H}_{2 n+1}(\mathbb{C})$ with index bounded above by a universal constant $I$. That is, $I$ is the maximal order of the holonomy groups. It is shown in [7] that when $n=2, I=24$.

For the case of the quaternionic Heisenberg group $\mathcal{H}_{4 n+3}(\mathbb{H})=$ $\mathbb{R}^{3} \tilde{\times} \mathbb{H}^{n}$ with group operation given by

$$
(s, q)\left(t, q^{\prime}\right)=\left(s+t+2 \operatorname{Im}\left\{q \bar{q}^{\prime}\right\}, q+q^{\prime}\right)
$$

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for $q=\left(q_{1}, q_{2}, \cdots, q_{n}\right), q^{\prime}=\left(q_{1}^{\prime}, q_{2}^{\prime}, \cdots, q_{n}^{\prime}\right) \in \mathbb{H}^{n}$, where $\operatorname{Im}\left\{q \bar{q}^{\prime}\right\}$ is the imaginary part of the quaternion number $q_{1} \bar{q}_{1}^{\prime}+q_{2} \bar{q}_{2}^{\prime}+\cdots+q_{n} \bar{q}_{n}^{\prime}$ seen as an element of $\mathbb{R}^{3}$, it is shown in [3] that when $n=1, I_{2}=48$. The number $I_{2}$ is significant in its own right. According to a recent work ( see [5, Corollary 5.3]), it is related to the minimum volume of a quaternionic hyperbolic orbifolds.

For $q=x_{1}+i x_{2}+j x_{3}+k x_{4} \in \mathbb{H}$, write

$$
q(1)=x_{1}, q(i)=x_{2}, q(j)=x_{3}, q(k)=x_{4} .
$$

Also we define

$$
\begin{gathered}
\bar{q}=x_{1}-i x_{2}-j x_{3}-k x_{4} \\
\breve{q}=-x_{1}+i x_{2}-j x_{3}-k x_{4} .
\end{gathered}
$$

For $q, q^{\prime} \in \mathbb{H}$, we define $q \odot q^{\prime}$ as follows:

$$
q \odot q^{\prime}=q \bar{q}^{\prime}(1)+q \breve{q^{\prime}}(i)+q \overline{q^{\prime}}(j)+q \overline{q^{\prime}}(k)
$$

The main concern of this paper is the quaternionic Heisenberg group $\mathcal{H}_{4 n+3}(\mathbb{H})=\mathbb{R}^{3} \tilde{\times} \mathbb{H}^{n}$ with group operation given by

$$
(s, q)\left(t, q^{\prime}\right)=\left(s+t+2 \operatorname{Im}\left\{q \odot q^{\prime}\right\}, q+q^{\prime}\right)
$$

for $q=\left(q_{1}, q_{2}, \cdots, q_{n}\right), q^{\prime}=\left(q_{1}^{\prime}, q_{2}^{\prime}, \cdots, q_{n}^{\prime}\right) \in \mathbb{H}^{n}$, where $\operatorname{Im}\left\{q \odot q^{\prime}\right\}$ is the imaginary part of the quaternion number $q_{1} \odot q_{1}^{\prime}+q_{2} \odot q_{2}^{\prime}+\cdots+q_{n} \odot$ $q_{n}^{\prime}$ seen as an element of $\mathbb{R}^{3}$. Then $\mathcal{H}_{4 n+3}(\mathbb{H})$ is a simply connected 2-step nilpotent Lie group with the center $\mathcal{Z}\left(\mathcal{H}_{4 n+3}(\mathbb{H})\right)=\mathbb{R}^{3}$.

Let $M$ be an infra-nilmanifold with $\mathcal{H}_{4 n+3}(\mathbb{H})$-geometry; that is, $M=\Pi \backslash \mathcal{H}_{4 n+3}(\mathbb{H})$, where $\Pi \subset \mathcal{H}_{4 n+3}(\mathbb{H}) \rtimes C$ is a torsion free, discrete subgroup with compact quotient, where $C$ is a compact subgroup of $\operatorname{Aut}\left(\mathcal{H}_{4 n+3}(\mathbb{H})\right)$. Such a group $\Pi$ is called an almost Bieberbach group (=AB-group). Since

$$
\Pi \cap \mathcal{Z}\left(\mathcal{H}_{4 n+3}(\mathbb{H})\right) \cong \mathbb{Z}^{3}
$$

is a lattice of $\mathcal{Z}\left(\mathcal{H}_{4 n+3}(\mathbb{H})\right), M$ fits

$$
T^{3} \rightarrow M \rightarrow N
$$

a Seifert 3 -torus "bundle" over a $4 n$-dimensional flat orbitfold. When there is no singular point, it is a genuine bundle over the base space $N$ which is a flat Riemannian $4 n$-manifold.

In this paper, we shall study the automorphism group of $\mathcal{H}_{7}(\mathbb{H})=$ $\mathbb{R}^{3} \tilde{\times} \mathbb{H}$ and show that $\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \cong \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)$.

## 2. The Quaternionic Heisenberg Group

From now on, we shall use $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ rather than $\mathbb{R}^{3} \tilde{\times} \mathbb{H}$. We identify $\mathbb{R}^{3} \tilde{\times} \mathbb{H}$ with $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ by

$$
\left(s, q=x_{1}+i x_{2}+j x_{3}+k x_{4}\right) \longleftrightarrow\left(s, x=\left[x_{1}, x_{2}, x_{3}, x_{4}\right]^{t}\right)
$$

Accordingly, we introduce a new notation for $\operatorname{Im}\left\{q \odot q^{\prime}\right\}$. For

$$
x=\left[\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3} \\
x_{4}
\end{array}\right], y=\left[\begin{array}{l}
y_{1} \\
y_{2} \\
y_{3} \\
y_{4}
\end{array}\right]
$$

define
$\mathcal{I}(x, y)$
$=\left(\left|\begin{array}{ll}x_{1} & y_{1} \\ x_{2} & y_{2}\end{array}\right|-\left|\begin{array}{ll}x_{3} & y_{3} \\ x_{4} & y_{4}\end{array}\right|,-\left|\begin{array}{ll}x_{1} & y_{1} \\ x_{3} & y_{3}\end{array}\right|-\left|\begin{array}{ll}x_{4} & y_{4} \\ x_{2} & y_{2}\end{array}\right|,-\left|\begin{array}{ll}x_{1} & y_{1} \\ x_{4} & y_{4}\end{array}\right|-\left|\begin{array}{ll}x_{2} & y_{2} \\ x_{3} & y_{3}\end{array}\right|\right)^{t}$
$=\left(x^{t} J_{1} y, x^{t} J_{2} y, x^{t} J_{3} y\right)^{t}$,
where ()$^{t}$ denotes the transpose of a matrix, and

$$
\begin{array}{ll}
J_{1} & =\left[\begin{array}{cccc}
0 & 1 & 0 & 0 \\
-1 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0
\end{array}\right], \quad J_{2}=\left[\begin{array}{cccc}
0 & 0 & -1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 0 & 0 & 0 \\
0 & -1 & 0 & 0
\end{array}\right] \\
J_{3} & =\left[\begin{array}{cccc}
0 & 0 & 0 & -1 \\
0 & 0 & -1 & 0 \\
0 & 1 & 0 & 0 \\
1 & 0 & 0 & 0
\end{array}\right] .
\end{array}
$$

Clearly $\mathcal{I}(x, y)=-\mathcal{I}(y, x)$ and $\mathcal{I}(x, y)$ corresponds to $\operatorname{Im}\left\{q \odot q^{\prime}\right\}$. Thus the group operation in $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ becomes

$$
(s, x)(t, y)=(s+t+2 \mathcal{I}(x, y), x+y)
$$

Since $\mathcal{I}(x, \pm x)=0$, we see easily that

$$
(s, x)^{-1}=(-s,-x) .
$$

Thus we have

$$
[(s, x),(t, y)]=(s, x)^{-1}(t, y)^{-1}(s, x)(t, y)=(4 \mathcal{I}(x, y), 0)
$$

Therefore the center of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}, \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ is $\mathbb{R}^{3}$. Thus we have shown the following lemma.

Lemma 2.1. $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ is a simply connected 2-step nilpotent Lie group with the center $\mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)=\mathbb{R}^{3}$.

Let

$$
\sigma=\left[\begin{array}{cccc}
-1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right]
$$

and

$$
K_{i}=\sigma^{-1} J_{i} \sigma, i=1,2,3
$$

Then $J_{1}, J_{2}, J_{3}$ together with $K_{1}, K_{2}, K_{3}$ form a linear basis for the vector space $\mathfrak{s o}(4)$ of the skew-symmetric matrices. Therefore,

$$
\mathfrak{s o}(4)=<J_{1}, J_{2}, J_{3}>\oplus<K_{1}, K_{2}, K_{3}>
$$

as vector spaces. Notice that each subspace fail to be a Lie subalgebra.
In order to understand the automorphism group of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$, we need to study more general setting: For any $C \in \operatorname{GL}(4, \mathbb{R})$ and $V \in \mathfrak{s o}(4)$,

$$
J_{C}(V)=C^{t} V C
$$

defines a linear isomorphism $J_{C}: \mathfrak{s o}(4) \rightarrow \mathfrak{s o}(4)$. In fact, with respect to the basis $\left\{J_{1}, J_{2}, J_{3}, K_{1}, K_{2}, K_{3}\right\}$, it turns out that $\operatorname{det}\left(J_{C}\right)=$ $(\operatorname{det}(C))^{3}$.

Define

$$
O(J ; 2,2)=\left\{C \in \mathrm{GL}(4, \mathbb{R}) \mid C^{t} J_{i} C \in<J_{1}, J_{2}, J_{3}>\right\}
$$

That is, $C \in O(J ; 2,2)$ if and only if the map $J_{C}$ leaves the subspace spanned by $J_{1}, J_{2}, J_{3}$ invariant. Therefore,

$$
C^{t} J_{i} C=\lambda_{i 1} J_{1}+\lambda_{i 2} J_{2}+\lambda_{i 3} J_{3}, \quad \lambda_{i j} \in \mathbb{R},
$$

for $i=1,2,3$. It turns out then, the matrix $\lambda=\left(\lambda_{i j}\right)$ is non-singular.
Now we form the column vector

$$
J=\left[\begin{array}{l}
J_{1} \\
J_{2} \\
J_{3}
\end{array}\right]
$$

with entries the matrices $J_{1}, J_{2}, J_{3}$. With some abuse of notation, we can write

$$
O(J ; 2,2)=\left\{C \in \mathrm{GL}(4, \mathbb{R}) \mid C^{t} J C=\lambda J, \lambda \in \mathrm{GL}(3, \mathbb{R})\right\}
$$

Clearly $C \in O(J ; 2,2)$ is a closed subgroup of $\operatorname{GL}(4, \mathbb{R})$. For $C \in$ $O(J ; 2,2)$, let $\widehat{C} \in \mathrm{GL}(3, \mathbb{R})$ denote the nonsingular $3 \times 3$ matrix $\lambda$ which satisfies $C^{t} J C=\lambda J$. So,

$$
C^{t} J C=\widehat{C} J .
$$

Then a map $C \rightarrow \widehat{C}$ defines a homomorphism ${ }^{\wedge}: O(J ; 2,2) \rightarrow$ $\mathrm{GL}(3, \mathbb{R})$.

Note that as a map $J_{C}: \mathfrak{s o}(4) \rightarrow \mathfrak{s o}(4)$, with respect to the ordered basis $\left\{J_{1}, J_{2}, J_{3}, K_{1}, K_{2}, K_{3}\right\}, J_{C}$ is of the form

$$
J_{C}=\left[\begin{array}{cc}
\widehat{C} & 0 \\
0 & *
\end{array}\right] .
$$

Since the center, $\mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)=\mathbb{R}^{3}$, is a characteristic subgroup of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$, every automorphism of $\mathbb{R}^{3} \tilde{x} \mathbb{R}^{4}$ restricts to an automorphism of $\mathbb{R}^{3}$. Consequently an automorphism of $\mathbb{R}^{3} \tilde{x} \mathbb{R}^{4}$ induces an automorphism on the quotient group $\mathbb{R}^{4}$. Thus there is a natural homomorphism $\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rightarrow \operatorname{Aut}\left(\mathbb{R}^{3}\right) \times \operatorname{Aut}\left(\mathbb{R}^{4}\right)$ defined by $\theta \mapsto(\hat{\theta}, \bar{\theta})$.

Lemma 2.2. $\operatorname{Im}\left\{\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rightarrow \operatorname{Aut}\left(\mathbb{R}^{4}\right)\right\}=O(J ; 2,2)$. Moreover, the exact sequence $\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rightarrow O(J ; 2,2) \rightarrow 1$ splits.

Proof. Let $\theta \in \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$. Then

$$
(\hat{\theta}, \bar{\theta}) \in \operatorname{Aut}\left(\mathbb{R}^{3}\right) \times \operatorname{Aut}\left(\mathbb{R}^{4}\right)
$$

Since $[(s, x),(t, y)]=(4 \mathcal{I}(x, y), 0)$,

$$
\begin{aligned}
\theta[(s, x),(t, y)] & =\theta(4 \mathcal{I}(x, y), 0)=(\hat{\theta}(4 \mathcal{I}(x, y)), \bar{\theta}(0)) \\
& =(4 \hat{\theta}(\mathcal{I}(x, y)), 0)
\end{aligned}
$$

and

$$
[\theta(s, x), \theta(t, y)]=[(*, \bar{\theta}(x)),(*, \bar{\theta}(y)]=(4 \mathcal{I}(\bar{\theta}(x), \bar{\theta}(y)), 0)
$$

yield

$$
\mathcal{I}(\bar{\theta}(x), \bar{\theta}(y))=\hat{\theta}(\mathcal{I}(x, y)),
$$

or, equivalently,

$$
\left(\bar{\theta}(x)^{t} J_{1} \bar{\theta}(y), \bar{\theta}(x)^{t} J_{2} \bar{\theta}(y), \bar{\theta}(x)^{t} J_{3} \bar{\theta}(y)\right)^{t}=\hat{\theta} \cdot\left(x^{t} J_{1} y, x^{t} J_{2} y, x^{t} J_{3} y\right)^{t}
$$

for all $x, y$. This happens if and only if $\bar{\theta}^{t} J \bar{\theta}=\hat{\theta} J$. Therefore, $\bar{\theta} \in$ $O(J ; 2,2)$.

Conversely, suppose that $\bar{\theta} \in O(J ; 2,2)$, i.e., $\bar{\theta}^{t} J \bar{\theta}=\lambda J$ is satisfied for some $\lambda \in \mathrm{GL}(3, \mathbb{R})$. We define $\theta: \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4} \rightarrow \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ by

$$
\theta(s, x)=(\lambda \cdot s, \bar{\theta}(x))
$$

Then

$$
\begin{aligned}
\theta((s, x) \cdot(t, y)) & =\theta(s+t+2 \mathcal{I}(x, y), x+y) \\
& =(\lambda \cdot(s+t+2 \mathcal{I}(x, y)), \bar{\theta}(x+y)) \\
& =(\lambda \cdot s+\lambda \cdot t+\lambda \cdot 2 \mathcal{I}(x, y), \bar{\theta}(x+y)), \\
\theta(s, x) \cdot \theta(t, y) & =(\lambda \cdot s, \bar{\theta}(x)) \cdot(\lambda \cdot t, \bar{\theta}(y)) \\
& =(\lambda \cdot s+\lambda \cdot t+2 \mathcal{I}(\bar{\theta}(x), \bar{\theta}(y)), \bar{\theta}(x)+\bar{\theta}(y)) .
\end{aligned}
$$

Now the condition $\bar{\theta}^{t} J \bar{\theta}=\lambda J$ guarantees that

$$
\lambda \cdot \mathcal{I}(x, y)=\mathcal{I}(\bar{\theta}(x), \bar{\theta}(y))
$$

Thus $\theta$ is an automorphism of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$. Moreover, this defines a split homomorphism $O(J ; 2,2) \rightarrow \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$.

Proposition 2.3. ( Structure of Aut $\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ )

$$
\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \cong \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)
$$

where an element $(\eta, A) \in \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)$ acts by

$$
(\eta, A)(s, x)=(\hat{A} s+\eta(x), A x)
$$

Proof. Let $\theta \in \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$. Then we have the following commutative diagram of exact sequences


Thus

$$
\theta(s, x)=(\hat{\theta}(s)+\eta(s, x), \bar{\theta}(x))
$$

for $(s, x) \in \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$, where $\eta: \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4} \rightarrow \mathbb{R}^{3}$. Since $\theta$ is a homomorphism, one can show that $\eta$ is a homomorphism, i.e.,

$$
\eta((s, x)(t, y))=\eta(s, x)+\eta(t, y) .
$$

In particular, set $x=0$.

$$
(\hat{\theta}(s), 0)=\theta(s, 0)=(\hat{\theta}(s)+\eta(s, 0), 0)
$$

implies that $\eta(s, 0)=0$ for all $s \in \mathbb{R}^{3}$, and thus

$$
\eta(s, x)=\eta((s, 0)(0, x))=\eta(s, 0)+\eta(0, x)=\eta(0, x) .
$$

Hence $\eta \in \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right)$.
Let us find out the kernel of the surjective homomorphism of Lemma 2.2:

$$
\operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rightarrow O(J ; 2,2), \quad \theta \mapsto \bar{\theta}
$$

Suppose that $\theta \in \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ with $\bar{\theta}=\operatorname{id}_{\mathbb{R}^{4}}$. Then $\hat{\theta}=\mathrm{id}_{\mathbb{R}^{3}}$ and thus

$$
\theta(s, x)=(s+\eta(x), x)
$$

for some $\eta \in \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right)$.
Conversely given $\eta \in \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right)$, define $\theta \in \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ by $\theta(s, x)=(s+\eta(x), x)$. Clearly this $\theta$ lies in the kernel of the homomorphism. Hence we have a short exact sequence

$$
1 \rightarrow \operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rightarrow \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rightarrow O(J ; 2,2) \rightarrow 1
$$

By Lemma 2.2, this sequence splits.
Note that $\operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)$ is sitting inside

$$
\operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes(\mathrm{GL}(3, \mathbb{R}) \times O(J ; 2,2))
$$

as $(\eta,(\hat{A}, A))$, and the action of $O(J ; 2,2)$ on $\operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right)$ is

$$
{ }^{A} \eta(x)=\hat{A} \cdot \eta\left(A^{-1} x\right)
$$

The group operation on $\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \rtimes O(J ; 2,2)$ is given by

$$
\begin{aligned}
& ((s, x), A)((t, y), B)=\left((s, x) \cdot{ }^{A}(t, y), A B\right) \\
& =((s, x) \cdot(\hat{A} t, A y), A B) \\
& =((s+\hat{A} t+2 \mathcal{I}(x, A y), x+A y), A B) .
\end{aligned}
$$

## 3. Application

Let $\Pi \subset \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4} \rtimes \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ be an AB-group. Then it is well known that $\Gamma=\Pi \cap\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$, the pure translations in $\Pi$, is the maximal normal nilpotent subgroup, and $\Phi=\Pi / \Gamma$, the holonomy group of $\Pi$, is finite. Since $\Gamma$ is a lattice of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}, \Gamma \cap \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ is a lattice of $\mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)=\mathbb{R}^{3}$, and $\Gamma / \Gamma \cap \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)$ is a lattice of $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4} / \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)=\mathbb{R}^{4}$. Thus

$$
\Gamma \cap \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \cong \mathbb{Z}^{3}
$$

and

$$
\Gamma / \Gamma \cap \mathcal{Z}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right) \cong \mathbb{Z}^{4}
$$

Consider the following natural commutative diagram:


Recall from Proposition 2.3 that an element

$$
(\eta, A) \in \operatorname{Aut}\left(\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}\right)=\operatorname{Hom}\left(\mathbb{R}^{4}, \mathbb{R}^{3}\right) \rtimes O(J ; 2,2)
$$

acts on $(s, x) \in \mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$ by

$$
(\eta, A)(s, x)=(\hat{A} s+\eta(x), A x)
$$

Thus $O(J ; 2,2)$ acts on $\mathbb{R}^{3}$ via the homomorphism

$$
\uparrow: O(J ; 2,2) \rightarrow \operatorname{GL}(3, \mathbb{R})
$$

and $O(J ; 2,2)$ acts on $\mathbb{R}^{4}$ by matrix multiplication $O(J ; 2,2) \times \mathbb{R}^{4} \rightarrow$ $\mathbb{R}^{4}$.

Let $Q=\Pi / \mathbb{Z}^{3}$. Then the above diagram induces the following
commutative diagram:


Here $\Phi \subset O(J ; 2,2)$ acts on $\mathbb{Z}^{4}$ by matrix multiplication, and on $\mathbb{Z}^{3}$ via the homomorphism ${ }^{\wedge}: O(J ; 2,2) \rightarrow \mathrm{GL}(3, \mathbb{R})$.

Recall from [6, Proposition 2] that a virtually free abelian group

$$
1 \rightarrow \mathbb{Z}^{4} \rightarrow Q \rightarrow \Phi \rightarrow 1
$$

is a crystallographic group if and only if the centralizer of $\mathbb{Z}^{4}$ in $Q$ has no torsion elements. Since $\Phi$ acts effectively on $\mathbb{Z}^{4}$, it follows that $Q$ is naturally a 4 -dimensional crystallographic group.

Let $\Pi$ be an AB-group for $\mathbb{R}^{3} \tilde{\times} \mathbb{R}^{4}$. Then $\Pi$ is a torsion free extension of $\mathbb{Z}^{3}$ by a 4-dimensional crystallographic group $Q$ so that

$$
1 \rightarrow \mathbb{Z}^{3} \rightarrow \Pi \rightarrow Q \rightarrow 1
$$

is exact.
Construction from $Q$. For each 4-dimensional crystallographic group $Q$, we shall check if there exists a construction from $Q$; that is, a torsion free $\Pi \subset \mathcal{H}_{7}(\mathbb{H}) \rtimes \operatorname{Aut}\left(\mathcal{H}_{7}(\mathbb{H})\right)$ fitting the short exact sequence

$$
1 \rightarrow \mathbb{Z}^{3} \rightarrow \Pi \rightarrow Q \rightarrow 1
$$

This is the key notion for our arguments and construction. We have a complete classification of 4-dimensional crystallographic groups ( $Q$ 's in the above statement). There are 4783 4-dimensional crystallographic groups up to isomorphism. We shall use the presentations of the 4-dimensional crystallographic groups given in the book [1]:
H. Brown, R. Bülow, J. Neubüser, H. Wondratschek and H. Zassenhaus, Crystallographic Groups of Four-Dimensional Spaces, John Wiley Sons, New York, 1978.

The crystallographic groups will be called $Q$, and every $Q$ has an explicit representation $Q \rightarrow \mathbb{R}^{4} \rtimes \mathrm{GL}(4, \mathbb{Z})$ in this book.

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