# REPRESENTATION OF $L^{1}$-VALUED CONTROLLER ON BESOV SPACES 

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Abstract. This paper will show that the relation

$$
\begin{equation*}
L^{1}(\Omega) \subset C_{0}(\bar{\Omega}) \subset H_{p, q} \tag{1.1}
\end{equation*}
$$

If $1 / p^{\prime}-1 / n\left(1-2 / q^{\prime}\right)<0$ where $p^{\prime}=p /(p-1)$ and $q^{t}=$ $q /(q-1)$ where $H_{p, q}=\left(W_{0}^{1, p}, W^{-1, p}\right)_{1 / q, q}$ We also intend to investigate the control problems for the retarded systems with $L^{1}(\Omega)$-valued controller in $H_{p, q}$

## 1. Introduction

Let $\Omega$ be a bounded domain in $\mathcal{R}^{n}$ with smooth boundary $\partial \Omega$. Let $\mathcal{A}\left(x, D_{x}\right)$ be an elliptic differential operator of second order as follows.

$$
\mathcal{A}\left(x, D_{x}\right)=-\sum_{\imath, j=1}^{n} \frac{\partial}{\partial x_{j}}\left(a_{\imath, j}(x) \frac{\partial}{\partial x_{\imath}}\right)+\sum_{\imath=1}^{n} b_{\imath}(x) \frac{\partial}{\partial x_{\imath}}+c(x)
$$

where $\left\{a_{2, j}(x)\right\}$ is a positive definte symmetric matrix for each $x \in$ $\Omega, b_{2} \in C^{1}(\bar{\Omega})$ and $c \in L^{\infty}(\Omega)$

If we put that $A_{0} u=-\mathcal{A}\left(x, D_{x}\right) u$ then it is known that $A_{0}$ generates an analytic semigroup in $W^{-1, p}(\Omega)$ where $W^{-1, p}(\Omega)$ is the dual

[^0]space of $W_{0}^{1, p^{\prime}}(\Omega), p^{\prime}=p /(p-1)$ as is seen in [5]. Therefore, from the interpolation theory it is easily seen that the operator $A_{0}$ generates an analytic semigroup in $H_{p, q}=\left(W_{0}^{1, p}, W^{-1, p}\right)_{1 / q, q}$. In the section 4, we will show that the relation
\[

$$
\begin{equation*}
L^{1}(\Omega) \subset C_{0}(\bar{\Omega}) \subset H_{p, q} \tag{1.1}
\end{equation*}
$$

\]

if $1 / p^{\prime}-1 / n\left(1-2 / q^{\prime}\right)<0$ where $p^{\prime}=p /(p-1)$ and $q^{\prime}=q /(q-1)$. Hence we intend to investigate the control problem for the following retarded system with $L^{1}(\Omega)$-valued controller:

$$
\begin{align*}
\frac{d}{d t} u(t)= & A_{0} u(t)+A_{1} u(t-h) \\
& +\int_{-h}^{0} a(s) A_{2} u(t+s) d s+\Phi_{0} w(t), \quad t \in(0, T] \\
u(0)= & g^{0}, \quad u(s)=g^{1}(s) \quad s \in[-h, 0) \tag{1.3}
\end{align*}
$$

in the space $H_{p, q}$. Here, $A_{\iota} u=-\mathcal{A}_{\iota}\left(x, D_{x}\right) u, \iota=1$, 2, where $\mathcal{A}_{\iota}\left(x, D_{x}\right)$ are second order linear differential operators with real coefficients. The kernel $a(\cdot)$ belongs to $L^{q^{\prime}}(-h, 0)$ where $h$ is a fixed positive number and the controller $\Phi_{0}$ is a bounded linear operator from some Banach space $U$ to $L^{1}(\Omega)$. The initial data $g^{0}, g^{1}$ are given functions so that needed for the construction of solution semigroup for (1.2) and (1.3) and of $L^{1}(\Omega)$ - valued controller. From the relation (1.1) we shall deal with approximate controllability and observability for the system (1.2) and (1.3) in the space $H_{p, q}$ choosing $p$ and $q$ such that $1 / p^{\prime}-1 / n\left(1-2 / q^{\prime}\right)<0$.

In view of Sobolev's embedding theorem we may also consider $L^{1}(\Omega) \subset W^{-1, p}(\Omega)$ if $1<p<n /(n-1)$ as is seen in [5]. Hence, we can investigate the system (1.2) and (1.3) in the space $W^{-1, p}(\Omega)$ considering $\Phi_{0}$ as an operator into $W^{-1, p}(\Omega)$. Furthermore, it is known that $W^{-1, p}(\Omega)$ is $\zeta$-convex and the initial value problem

$$
\begin{align*}
\frac{d}{d t} & =A_{0} u(t)+f(t), \quad t \in(0, T]  \tag{1.4}\\
u(0) & =u_{0}
\end{align*}
$$

has a unique solution $u \in L^{q}\left(0, T ; W_{0}^{1, p}(\Omega) \cap W^{1, q}\left(0, T ; W^{-1, p}(\Omega)\right)\right.$ for any $u_{0} \in H_{p, q}$ and $f \in L^{q}\left(0, T ; W^{-1, p}(\Omega)\right)$ (see Theorem 3.1 in [5]). Thereafter, we can apply the method of G. D. Blasio, K. kunisch and E. Sinestrari [3] to the system (1.2) and (1.3) to show the existence and uniqueness of the solution

$$
u \in L^{q}\left(0, T ; W_{0}^{1, p}(\Omega) \cap W^{1, q}\left(0, T ; W^{-1, p}(\Omega)\right) \subset C\left([0, T] ; H_{p, q}\right)\right.
$$

Since $\Phi_{0}$ is a mapping into $W^{-1, p}(\Omega)$ not into $H_{p, q}$, we cannot express the solution $u\left(t ; 0, \Phi_{0} w\right)$ of system of (1.2) and (1.3) with $g=0$ using the solution semigroup $S(t)$. Here, the solution semigroup for the system (1.2) and (1.3) is defined by

$$
S(t) g=\left(u(t ; g, 0), u_{t}(\cdot ; g, 0)\right)
$$

where $g=\left(g^{0}, g^{1}\right) \in Z_{p, q}=H_{p, q} \times L^{q}\left(-h, 0 ; W_{0}^{1, p}(\Omega)\right), u(t ; g, 0)$ is the solution of (1.2) and (1.3) with $\Phi_{0}=0$ and $u_{t}(\cdot, g, 0)$ is the function $u_{t}(s ; g, 0)=u(t+s ; g, 0)$ defined in $[-h, 0]$. Therefore, we have to define the approximate controllability and observability in $W^{-1, p}(\Omega)$ using the fundamental solution as is seen in definition 5.1 in [5]. Here, we note that in order to existing of fundamental solution of system (1.2) and (1.3), we must need the assumption that $a(\cdot)$ is Hölder continuous.

In this paper, assuming that $a(\cdot)$ has only to belong to $L^{q^{\prime}}(-h, 0)$, with the aid of the relation (1.1) we can define the approximate controllability and observability in $H_{p, q}$ without using the fundamental solution. We define the set of attainability by

$$
R=\left\{\int_{0}^{t} S(t-\tau) \Phi w(t) d \tau: w \in L^{q}(0, t ; U), \quad t>0\right\}
$$

where $\Phi w=\left(\Phi_{0} w, 0\right)$. We say that the system (1.2) and (1.3) is approximately controllable if $R$ is dense in $Z_{p, q}$ and the adjoint system is observability if $\phi \in Z_{p^{\prime}, q^{\prime}}, \Phi_{0}^{*} v(t ; \phi) \equiv 0$ implies $\phi=0$. where $v(t ; \phi)$ is a solution the following adjoint system of (1.2) and (1.3).

$$
\begin{align*}
\frac{d}{d t} v(t) & =A_{0}^{*} v(t)+A_{1}^{*} v(t-h)+\int_{-h}^{0} a(s) A_{2} u(t+s) d s,  \tag{1.4}\\
v(0) & =\phi^{0}, \quad v(s)=\phi^{1}(s), \quad s \in[-h, 0), \tag{1.5}
\end{align*}
$$

where $\phi=\left(\phi^{0}, \phi^{1}\right) \in Z_{p^{\prime}, q^{\prime}}$. The structural operator $F: Z_{p, q} \longrightarrow$ $Z_{p^{\prime}, q^{\prime}}^{*}$ is defined by

$$
F g=\left(g^{0}, A_{1} g^{1}(-h-s)+\int_{-h}^{0} a(\tau) A_{2} g^{1}(\tau-s) d \tau\right)
$$

We will show that if $F$ is an isomorphism, then the approximate controllability of (1.2) and (1.3) is equivalent to the observability of (1.4) and (1.5). Finally, we remark that in the space $W^{-1, p}(\Omega)$ we can not define the attainability set using solution semigroup $S(t)$ and it is said that the system (1.4) and (1.5) is observable if $\phi \in Z_{p^{\prime}, q^{\prime}}$, $\Phi_{0}^{*} v(t ; \phi) \equiv 0$ almost everywhere implies $\phi=0$.

## 2. Notations

Let $\Omega$ be a region in an $n$-dimensional Euclidean space $\mathcal{R}^{n}$ and closure $\bar{\Omega} . C^{m}(\Omega)$ is the set of all $m$-times contmuously differential functions on $\Omega$. $C_{0}^{m}(\Omega)$ will denote the subspace of $C^{m}(\Omega)$ consisting of these functions which have compact support in $\Omega . W^{m, p}(\Omega)$ is the set of all functions $f=f(x)$ whose derivative $D^{\alpha} f$ up to degree $m$ in distribution sense belong to $L^{p}(\Omega)$. As usual, the norm is then given by

$$
\begin{aligned}
& \|f\|_{m, p, \Omega}=\left(\sum_{\alpha \leq m}\left\|D^{\alpha} f\right\|_{p, \Omega}^{p}\right)^{\frac{1}{p}}, \quad 1 \leq p<\infty \\
& \|f\|_{m, \infty, \Omega}=\max _{\alpha \leq m}\left\|D^{\alpha} u\right\|_{\infty, \Omega},
\end{aligned}
$$

where $D^{0} f=f$. In particular, $W^{0, p}(\Omega)=L^{p}(\Omega)$ with the norm $\|\cdot\|_{p, \Omega}$. Let $p^{\prime}=p /(p-1), 1<p<\infty . W^{-1, p}(\Omega)$ stands for the dual space $W_{0}^{1, p^{\prime}}(\Omega)^{*}$ of $W_{0}^{1, p^{\prime}}(\Omega)$ whose norm is denoted by $\|\cdot\|-1, p, \infty$.

If $X$ is a Banach space and $1<p<\infty, L^{p}(0, T ; X)$ is the collection of all strongly measurable functions from $(0, T)$ into $X$ the $p$-th powers of norms are integrable. $C^{m}([0, T] ; X)$ will denote the set of all $m$-times continuously differentiable functions from $[0, T]$ into $X$.

If $X$ and $Y$ are two Banach spaces, $B(X, Y)$ is the collection of all bounded linear operators from $X$ into $Y$, and $B(X, X)$ is simply written as $B(X)$. For an interpolation couple of Banach spaces $X_{0}$ and $X_{1},\left(X_{0}, X_{1}\right)_{\theta, p}$ and $\left[X_{0}, X_{1}\right]_{\theta}$ denote the real and complex interpolation spaces between $X_{0}$ and $X_{1}$, respectively. Let $B_{p, q}^{s}(\Omega)$ denote the Besov space and $B_{p, q}^{s}(\Omega)$ will be denote the subspace of $B_{p, q}^{s}(\Omega)$ consisting of those functions which have compact support in $\Omega$.

## 3. Preliminaries

Let $\Omega$ be a bounded domain in $\mathcal{R}^{n}$ with smooth boundary $\partial \Omega$. Consider an elliptic differential operator of second order

$$
\mathcal{A}\left(x, D_{x}\right)=-\sum_{\imath, j=1}^{n} \frac{\partial}{\partial x_{j}}\left(a_{\imath, y}(x) \frac{\partial}{\partial x_{\imath}}\right)+\sum_{\imath=1}^{n} b_{\imath}(x) \frac{\partial}{\partial x_{\imath}}+c(x)
$$

where $\left\{a_{\imath, y}(x)\right\}$ is a positive definite symmetric matrix for each $x \in$ $\bar{\Omega}$. The operator

$$
\mathcal{A}^{\prime}\left(x, D_{x}\right)=-\sum_{\imath y=1}^{n} \frac{\partial}{\partial x_{y}}\left(a_{\imath, y}(x) \frac{\partial}{\partial x_{\imath}}\right)-\sum_{\imath z=1}^{n} \frac{\partial}{\partial x_{\imath}}\left(b_{\imath}(x) \cdot\right)+c(x)
$$

is the formal adjoint of $\mathcal{A}$.
For $1<p<\infty$ we denote the realization of $\mathcal{A}$ in $L^{p}(\Omega)$ under the Dirichlet boundary condition by $A_{p}$

$$
\begin{aligned}
& D\left(A_{p}\right)=W^{2, p}(\Omega) \cap W_{0}^{1, p}(\Omega), \\
& A_{p} u=\mathcal{A} u \quad \text { for } \quad u \in D\left(A_{p}\right) .
\end{aligned}
$$

For $p^{\prime}=p /(p-1)$, we can also define the realization $\mathcal{A}^{\prime}$ in $L^{p^{\prime}}(\Omega)$ under Dirichlet boundary condition by $A_{p^{\prime}}^{\prime}$.

$$
\begin{aligned}
& D\left(A_{p^{\prime}}^{\prime}\right)=W^{2, p^{\prime}}(\Omega) \cap W_{0}^{1, p^{\prime}}(\Omega), \\
& A_{p^{\prime}}^{\prime} u=\mathcal{A}^{\prime} u \quad \text { for } \quad u \in D\left(A_{p^{\prime}}^{\prime}\right)
\end{aligned}
$$

It is known that $-A_{p}$ and $-A_{p^{\prime}}^{\prime}$ generate analytic semigroups in $L^{p}(\Omega)$ and $L^{p^{\prime}}(\Omega)$, respectively, and $A_{p}^{*}=A_{p^{\prime}}^{\prime}$. From the result of R. Seeley $[10]$ (see also H. Triebel $[14 ;$ p. 321]) we obtain that

$$
\left[D\left(A_{p}\right), L^{p}(\Omega)\right]_{\frac{1}{2}}=W_{0}^{1, p}(\Omega)
$$

and hence, may consider that

$$
D\left(A_{p}\right) \subset W_{0}^{1, p}(\Omega) \subset L^{p}(\Omega) \subset W^{-1, p}(\Omega) \subset D\left(A_{p^{\prime}}^{\prime}\right)^{*}
$$

Let $\left(A_{p^{\prime}}^{\prime}\right)^{\prime}$ be the adjoint of $A_{p^{\prime}}^{\prime}$ considered as a bounded linear operator from $D\left(A_{p^{\prime}}^{\prime}\right)$ to $L^{p^{\prime}}(\Omega)$. Let $\widetilde{A}$ be the restriction of $\left(A_{p^{\prime}}^{\prime}\right)^{\prime}$ to $W_{0}^{1, p}(\Omega)$. Then by the interpolation theory, the operator $\widetilde{A}$ is an isomorphism from $W_{0}^{1, p}(\Omega)$ to $W^{-1, p}(\Omega)$. Similarly, we consider that the restriction $\widetilde{A^{\prime}}$ of $\left(A_{p}\right)^{\prime} \in B\left(L^{p^{\prime}}(\Omega), D\left(A_{p}\right)^{*}\right)$ to $W_{0}^{1, p^{\prime}}(\Omega)$ is an isomorphism from $W_{0}^{1, p^{\prime}}(\Omega)$ to $W^{-1, p^{\prime}}(\Omega)$. Furthermore, as is seen in proposition 3.1 in J. M. Jeong [5], it is known that $\widetilde{A}$ and $\widetilde{A^{\prime}}$ generate analytic semigroups in $W^{-1, p}(\Omega)$ and $W^{-1, p^{\prime}}(\Omega)$, respectively, and the inequality

$$
\left\|(\tilde{A})^{2 s}\right\|_{B(W-1, p(\Omega))} \leq C e^{\gamma|s|}, \quad-\infty<s<\infty
$$

holds for some constants $C>0$ and $\gamma \in(0, \pi / 2)$. We set

$$
\begin{equation*}
H_{p, q}=\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1}{q}, q} \tag{3.1}
\end{equation*}
$$

for $q \in(1, \infty)$ Since $\tilde{A}$ is an isomorphism from $W_{0}^{1, p}(\Omega)$ onto $W^{-1, p}(\Omega)$ and $W_{0}^{1, p}(\Omega)$ and $W^{-1, p}(\Omega)$ are $\zeta$-convex spaces, it is easily seen that $H_{p, q}$ is also $\zeta$-convex. From the interpolation theory and definitions of the operator $\widetilde{A}$ and the space $H_{p, q}$ we can see the following results.

Proposition 3.1. The operator $\tilde{A}$ and $\widetilde{A^{\prime}}$ generate analytic semigroups in $H_{p, q}$ and $H_{p^{\prime}, q^{\prime}}$, respectively.

Proof. Since $-A_{p}$ and $-\widetilde{A}$ generate analytic semigroup in $L^{p}(\Omega)$ and $W^{-1, p}(\Omega)$, respectively (see Proposition 3.1 in J. M. Jeong [5]), there exists an angle $\gamma \in\left(0, \frac{\pi}{2}\right)$ such that

$$
\begin{align*}
& \Sigma=\{\lambda: \gamma \leq \arg \lambda \leq 2 \pi-\gamma\} \subset \rho\left(A_{p}\right) \cap \rho(\widetilde{A}),  \tag{3.2}\\
& \left\|\left(\lambda-A_{p}\right)^{-1}\right\|_{B\left(L^{p}(\Omega)\right)} \leq C /|\lambda|, \quad \lambda \in \Sigma,  \tag{3.3}\\
& \left\|(\lambda-\widetilde{A})^{-1}\right\|_{B\left(W^{-1, p}(\Omega)\right)} \leq C /|\lambda|, \quad \lambda \in \Sigma, \tag{3.4}
\end{align*}
$$

where $\rho\left(A_{p}\right)$ is the resolvent set of $A_{p}$. In view of (3.3)

$$
\left\|A_{p}\left(\lambda-A_{p}\right)^{-1} u\right\|_{p, \Omega}=\left\|\left(\lambda-A_{p}\right)^{-1} A_{p} u\right\|_{p, \Omega} \leq \frac{C}{|\lambda|}\left\|A_{p} u\right\|_{p, \Omega},
$$

for any $u \in D\left(A_{p}\right)$, we have

$$
\begin{equation*}
\left\|\left(\lambda-A_{p}\right)^{-1}\right\|_{B\left(D\left(A_{p}\right)\right)} \leq \frac{C}{|\lambda|} . \tag{3.5}
\end{equation*}
$$

From (3.3) and (3.5) it follows that

$$
\begin{equation*}
\left\|(\lambda-\widetilde{A})^{-1}\right\|_{B\left(W_{0}^{1, p}(\Omega)\right)} \leq \frac{C}{|\lambda|} \tag{3.6}
\end{equation*}
$$

and, hence from (3.4), (3.6) and the definition of the space $H_{p, q}$ we have that

$$
\left\|(\lambda-\widetilde{A})^{-1}\right\|_{B\left(H_{p, q}\right)} \leq \frac{C}{|\lambda|} .
$$

Therefore we have shown that $-\widetilde{A}$ generates an analytic semigroup in $H_{p, q}$.

Proposition 3.2. There exists a constant $C>0$ such that

$$
\left\|\widetilde{A}^{2 s}\right\|_{B\left(H_{p, q}\right)} \leq C e^{\gamma|\lambda|}, s \in \mathcal{R},
$$

where $\gamma$ is the constant in (3.2).
Proof. From Theorem 1 of Seeley [9] and Proposition 3.2 of J. M. Jeong [5] there exists a constant $C>0$ such that

$$
\begin{align*}
& \left\|\left(A_{p}\right)^{\epsilon+2 s}\right\|_{B\left(L^{p}(\Omega)\right)} \leq C e^{\gamma|s|},  \tag{3.7}\\
& \left\|\tilde{A}^{\epsilon+2 s}\right\|_{B\left(W^{-1, p}(\Omega)\right)} \leq C e^{\gamma|s|}, \tag{3.8}
\end{align*}
$$

for any $s \in \mathcal{R}$ and $\epsilon>0$. From (3.7) it follows

$$
\begin{equation*}
\left\|\left(A_{p}\right)^{\epsilon+2 s}\right\|_{B\left(D\left(A_{p}\right)\right)} \leq C e^{\gamma|s|} \tag{3.9}
\end{equation*}
$$

and hence, from (3.7) and (3.9) we obtain

$$
\begin{equation*}
\left\|\widetilde{A}^{e+2 s}\right\|_{B\left(W_{0}^{1, p}(\Omega)\right)} \leq C e^{\gamma|s|} . \tag{3.10}
\end{equation*}
$$

Hence from (3.1), (3.8) and (3.10) we have shown that

$$
\left\|\widetilde{A}^{\epsilon+2 s}\right\|_{B\left(H_{p, q}\right)} \leq C e^{\gamma|s|} .
$$

So the proof is complete.
If $1<p<n /(n-1)$, then we see that $L^{1}(\Omega) \subset W^{-1, p}(\Omega)$ from Sobolev's embedding theorem. Furthermore, we will show that $L^{1}(\Omega) \subset H_{p, q}$ in the section 4. Therefore, from Propositions 3.1 and 3.2 we can apply Theorem 31 and Proposition 4.1 of J. M. Jeong [5] to the abstract Cauchy problem in the space $H_{p, q}$. Hence, the following equation may be considered as an equation in both $H_{p, q}$ and $W^{-1, p}(\Omega)$.

$$
\begin{align*}
\frac{d}{d t} u(t)= & A_{0} u(t)+A_{1} u(t-h)  \tag{3.11}\\
& +\int_{-h}^{0} a(s) A_{2} u(t+s) d s+\Phi_{0} w(t), \quad t \in(0, T] \\
u(0)= & g^{0}, \quad u(s)=g^{1}(s) \quad s \in[-h, 0), \tag{3.12}
\end{align*}
$$

where $A_{0}=-\widetilde{A}, A_{\iota} u(\iota=1,2)$ are the restriction $W_{0}^{1, p}(\Omega)$ of the following linear differential operators $-\mathcal{A}_{\imath}(\iota=1,2)$ with real coefficient:

$$
\mathcal{A}\left(x, D_{x}\right)=-\sum_{\imath, j=1}^{n} \frac{\partial}{\partial x_{j}}\left(a_{\imath, j}(x) \frac{\partial}{\partial x_{\imath}}\right)+\sum_{\imath=1}^{n} b_{i}(x) \frac{\partial}{\partial x_{\imath}}+c(x)
$$

where $a_{\imath, \jmath}^{L}=a_{3,2}^{\iota} \in C^{1}(\bar{\Omega}), b_{2}^{L} \in C^{1}(\bar{\Omega}), c^{\iota} \in L^{\infty}(\Omega)$. The kernel $a(\cdot)$ belongs to $L^{a^{\prime}}(-h, 0)$ and the controller $\Phi_{0}$ is a bounded linear operator from some Banach space $U$ to $L^{1}(\Omega)$. For $q \in(1, \infty)$ we set

$$
\begin{equation*}
Z_{p, q}=H_{p, q} \times L^{q}\left(-h, 0 ; W_{0}^{1, p}(\Omega)\right) \tag{3.13}
\end{equation*}
$$

Let $g=\left(g^{0}, g^{1}\right) \in Z_{p, q}$ and $w \in L^{q}(0, T ; U)$. Then as is seen in Proposition 4.1 of J.M. Jeong [5] a solution of the equation (3.11) and (3.12) exists and is unique for each $T>0$, moreover, we have

$$
\begin{aligned}
& \|u\|_{L^{q}\left(0, T, W_{0}^{1, p}(\Omega)\right) \cap W^{1, q}\left(0, T, W^{-1, p}(\Omega)\right)} \leq c\left(\left\|g^{0}\right\|_{H_{P, q}}\right. \\
& \left.\quad+\left\|g^{1}\right\|_{L^{q}\left(-h, 0, W_{0}^{1, p}(\Omega)\right)}+\|w\|_{L^{q}(0, T, U)}\right)
\end{aligned}
$$

where $c$ is a constant. Thus, we can define the solution semigroup for the system (3.11) and (3.12) as follows [3, Theorem 4.1]:

$$
S(t)=\left(u(t ; g, 0), u_{t}(\cdot ; g, 0)\right)
$$

where $g=\left(g^{0}, g^{1}\right) \in Z_{p, q}, u(t ; g, 0)$ is a solution of (3.11), (3.12) with $\Phi_{0}=0$ and $u_{t}(\cdot, g, 0)$ is the function $u_{t}(s ; g, 0)=u(t+s ; g, 0)$ defined in $[-h, 0]$. It is also known that $S(t)$ is a $C_{0}$-semigroup in $Z_{p, q}$.

We introduce the adjoint problem of (311) and (3,12):

$$
\begin{align*}
\frac{d}{d t} v(t)= & A_{0}^{*} v(t)+A_{1}^{*} v(t-h)  \tag{3.14}\\
& +\int_{-h}^{0} a(s) A_{2}^{*} v(t s) d s, \quad t \in(0, T], \\
v(0)= & \phi^{0}, \quad v(s)=\phi^{\mathrm{I}}(s), \quad s \in[-h, 0), \tag{array}
\end{align*}
$$

where $A_{0}^{*}=-\widetilde{A^{\prime}}$ and $A_{\iota}^{*}(\iota=1,2)$ are the adjoint operators of $A_{\iota}$. It is easily seen that $A_{\iota}^{*} \in B\left(W_{0}^{1, p^{\prime}}(\Omega), W^{-1, p^{\prime}}(\Omega)\right)$ for $\iota=0,1,2$ and hence (3.14) and (3.15) is an equation in both $H_{p^{\prime}, q^{\prime}}$ and $W^{-1, p^{\prime}}$. We can also define the solution semigroup $S_{T}(t)$ of (3.14) and (3.15) by

$$
S_{T}(t) \phi=\left\langle v(t ; \phi), v_{t}(\cdot, \phi)\right)
$$

for $\phi=\left(\phi^{0}, \phi^{1}\right) \in Z_{p^{\prime}, q^{\prime}}$, where $v(t ; \phi)$ is the solution of (3.14) and (3.15).

The structural operator $F$ is defined by

$$
\begin{aligned}
& F g=\left([F g]^{0},[F g]^{1}\right), \\
& {[F g]^{0}=g^{0},} \\
& {[F g]^{1}(s)=A_{1} g^{1}(-h-s)+\int_{-h}^{0} a(\tau) A_{2} g^{1}(\tau-s) d \tau}
\end{aligned}
$$

for $g=\left(g^{0}, g^{1}\right) \in Z_{p, q}$. It is easy to see that $F \in B\left(Z_{p, q}, Z_{p^{\prime}, q^{\prime}}\right), F^{*}$ $\in B\left(Z_{p^{\prime}, q^{\prime}}, Z_{p, q}^{*}\right)$. As in $[5,7]$ we have that

$$
\begin{equation*}
F S(t)=S_{T}^{*}(t) F^{*}, \quad F^{*} S_{T}(t)=S^{*}(t) F^{*} \tag{3.16}
\end{equation*}
$$

## 4. Representation of $H_{p, q}$ into Besov spaces

Let $Y_{0}$ and $Y_{1}$ be two Banach spaces contained in a Banach space $\mathcal{Y}$ such that the identity mapping of $Y_{z}(\imath=0,1)$ in $\mathcal{Y}$ is continuous and norms will be denoted by $\|\cdot\|_{2}$. The algebraic sum $Y_{0}+Y_{1}$ of $Y_{0}$ and $Y_{1}$ is the space of all elements $a \in \mathcal{Y}$ of the form $a=a_{0}+a_{1}$, $a_{0} \in Y_{0}$ and $a_{1} \in Y_{1}$. The intersection $Y_{0} \cap Y_{1}$ and the sum $Y_{0}+Y_{1}$ are Banach spaces with the norms

$$
\|a\| Y_{0} \cap Y_{1}=\max \left\{\|a\|_{0},\|a\|_{1}\right\}
$$

and

$$
\|a\| Y_{0}+Y_{1}=\inf _{a}\left\{\left\|a_{0}\right\|_{0}+\left\|a_{1}\right\|_{1}\right\}, \quad a=a_{0}+a_{1}, a_{\imath} \in Y_{2},
$$

respectively.

Definition (Lions-Peetre) 4.1. We say an intermediate space $Y$ of $Y_{0}$ and $Y_{1}$ belongs to
(i) the class $\underline{K}_{\theta}\left(Y_{0}, Y_{1}\right), 0<\theta<1$, if for any $a \in Y_{0} \cap Y_{1}$,

$$
\|a\|_{Y} \leq c\|a\|_{0}^{1-\theta}\left\|_{1}\right\|_{1}^{\theta}
$$

where $c$ is a constant;
(ii) the class $\bar{K}_{\theta}\left(Y_{0}, Y_{1}\right), 0<\theta<1$, if for any $a \in Y$ and $t>0$ there exist $a_{\imath} \in Y_{\imath}(\imath=1,2)$ such that $a=a_{0}+a_{1}$ and

$$
\left\|a_{0}\right\|_{0} \leq c t^{-\theta}\|a\|_{Y}, \quad\left\|a_{1}\right\|_{1} \leq c t^{1-\theta}\left\|_{a}\right\|_{Y}
$$

where c is a constant;
(iii) the class $K_{\theta}\left(A_{0}, A_{1}\right), 0<\theta<1$, if the space $Y$ belongs to both $\underline{K}_{\theta}\left(Y_{0}, Y_{1}\right)$ and $\bar{K}_{\theta}\left(Y_{0}, Y_{1}\right)$.

Here, we note that by replacing $t$ with $t^{-1}$ the condition in (ii) rewrite as follows:

$$
\left\|a_{0}\right\|_{0} \leq c t^{\theta}\|a\|_{Y}, \quad\left\|a_{1}\right\|_{1} \leq c t^{\theta-1}\|a\|_{Y}
$$

The following resuit is obtained from Lions-Peetre theorem 2.3 in [6].
Proposition 41. For $0<\theta_{0}<\theta<\theta_{1}<1$, if the spaces $X_{0}$ and $X_{1}$ belong to the space $K_{\theta_{0}}\left(Y_{0}, Y_{1}\right)$ and the space $K_{\theta_{1}}\left(Y_{0}, Y_{1}\right)$, respectively, then

$$
\left(X_{0}, X_{1}\right)_{\frac{\theta-\theta_{0}}{\theta_{1}-\theta_{0}, p}}=\left(Y_{0}, Y_{1}\right)_{\theta, p}
$$

In particular, if the space $X_{1}$ belongs to $K_{\theta_{1}}\left(Y_{0}, Y_{1}\right)$ then for $0<$ $\theta<\theta_{1}<1$

$$
\left(Y_{0}, X_{1}\right)_{\frac{\theta}{\theta_{1}, p}}=\left(Y_{0}, Y_{1}\right)_{\theta, p}
$$

If the space $X_{0}$ belongs to $K_{\theta_{0}}\left(Y_{0}, Y_{1}\right)$, then $0<\theta_{0}<\theta<1$

$$
\left(X_{0}, Y_{1}\right)_{\frac{\theta-\theta_{0}}{1-\theta_{0}}, p}=\left(Y_{0}, Y_{1}\right)_{\theta, p}
$$

Let $A=-\mathcal{A}\left(x, D_{x}\right)$ as in section 3. Then the operator $A$ is an isomorphism from $W_{0}^{1, p}(\Omega)$ to $W^{-1, p}(\Omega)$.

Lemma 4.1. For any $t>0$, there exists a constant $C$ such that

$$
\begin{equation*}
\left\|(t+A)^{-1}\right\|_{B\left(W^{-1, p}(\Omega), L^{p}(\Omega)\right)} \leq C t^{-\frac{1}{2}}, \tag{4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|(t+A)^{-1}\right\|_{B\left(L^{P}(\Omega), W_{0}^{1, p}(\Omega)\right)} \leq C t^{-\frac{1}{2}} . \tag{4.2}
\end{equation*}
$$

Proof. For $t>0$ since $\left(t+A_{p^{\prime}}^{\prime}\right)^{-1}$ is an isomorphism from $L^{p^{\prime}}(\Omega)$ to $D\left(A_{p^{\prime}}^{\prime}\right)$, the resolvent $\left(\left(t+A_{p^{\prime}}^{\prime}\right)^{-1}\right)^{\prime}$ is an isomorphism from $D\left(A_{p^{\prime}}^{\prime}\right)^{*}$ onto $L^{P}(\Omega)$. It is not difficult to see that

$$
\left(\left(t+A_{p^{\prime}}^{\prime}\right)^{-1}\right)^{\prime}=\left(t+\left(A_{p^{\prime}}^{\prime}\right)^{\prime}\right)^{-1}
$$

and

$$
\left.\left(t+\left(A_{p^{\prime}}^{\prime}\right)^{\prime}\right)^{-1}\right|_{W^{-1, p}(\Omega)}=(t+A)^{-1} .
$$

Therefore, we have

$$
\begin{equation*}
\left\|(t+A)^{-1}\right\|_{B\left(D\left(A_{p^{\prime}}^{\prime}\right)^{*}, L^{P}(\Omega)\right)} \leq C \tag{4.3}
\end{equation*}
$$

where $C$ is a constant. Combining (3.3) and (4.3) we obtain the inequality of (4.1). The proof of (4.2) is similar.

Theorem 4.1. For $1<p<\infty$, the space $L^{P}(\Omega)$ belongs to the class $K_{1 / 2}\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)$.

Proof. For any $u \in W_{0}^{1, p}(\Omega)$ and $t>0$, from Lemma 4.1 and

$$
u=A(t+A)^{-1} u+t(t+A)^{-1} u=(t+A)^{-1} A u+t(t+A)^{-1} u
$$

it follows

$$
\begin{aligned}
\|u\|_{p, \Omega} \leq & \left\|(t+A)^{-\frac{1}{2}}\right\|_{B\left(W^{-1, p}(\Omega), L^{P}(\Omega)\right)}\|A u\|_{-1, p, \Omega} \\
& +t\left\|(t+A)^{-1}\right\|_{B\left(W^{-1, p}(\Omega), L^{P}(\Omega)\right)}\|u\|_{-1, p, \Omega} \\
\leq & C t^{-\frac{1}{2}}\|u\|_{1, p, \Omega}+C t^{\frac{1}{2}}\|u\|_{-1, p, \Omega} .
\end{aligned}
$$

By choosing $t>0$ such that $t^{-1 / 2}\|u\|_{1, p, \Omega}=t^{1 / 2}\|u\|_{-1, p, \Omega}$, we obtain

$$
\|u\|_{p, \Omega} \leq C\|u\|_{1, p, \Omega}^{\frac{2}{2}}\|u\|_{-1, p, \Omega}^{\frac{1}{2}} .
$$

Therefore, $L^{P}(\Omega)$ belongs to the class $\underline{K}_{1 / 2}\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)$. Put $u_{0}=t(t+A)^{-1} u$ and $u_{1}=A(t+A)^{-1} u$ for any $u \in L^{p}(\Omega)$. Then $u=u_{0}+u_{1}$, and we obtain that

$$
\begin{aligned}
& \left\|u_{0}\right\|_{1, p, \Omega} \leq t\left\|(t+A)^{-1} u\right\|_{B\left(L^{p}(\Omega), W_{0}^{1, p}(\Omega)\right)}\|u\|_{p, \Omega} \leq C t^{\frac{1}{2}}\|u\|_{p, \Omega} \\
& \left\|u_{1}\right\|_{-1, p, \Omega} \leq C\left\|(t+A)^{-1} u\right\|_{1, p, \Omega} \leq C t^{\frac{1}{2}}\|u\|_{p, \Omega} .
\end{aligned}
$$

Therefore $L^{P}(\Omega)$ belongs to the class $\stackrel{\rightharpoonup}{K}_{1 / 2}\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)$, and hence, it belongs to $K_{1 / 2}\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)$.

Theorem 4.2. If $1-2 \theta-1 / p \neq 0$ and $2 \theta-2+1 / p \neq 0$ for $0<\theta<1$ and $1<p, q<\infty$, then

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\theta, q}= \begin{cases}B_{p, q}^{1-2 \theta}(\Omega) & \theta<\frac{1}{2}\left(1-\frac{1}{p}\right) \\ B_{p, q}^{1-2 \theta}(\Omega) & \theta>\frac{1}{2}\left(1-\frac{1}{p}\right)\end{cases}
$$

where $B_{p, q}^{1-2 \theta}(\Omega)=\left\{u \in B_{p, q}^{1-2 \theta}(\Omega):\left.u\right|_{\partial \Omega}=0\right\}$. In particular, we obtain that

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1}{2}, q}=B_{p, q}^{0}(\Omega) .
$$

Proof. Let $0<\theta<1 / 2$. Then from Proposition 4.1 we obtain that for any $0<\theta<1 / 2$

$$
\begin{aligned}
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\theta, q} & =\left(W_{0}^{1, p}(\Omega), L^{p}(\Omega)\right)_{2 \theta, q} \\
& =\left(L^{p}(\Omega), W_{0}^{1, p}(\Omega)\right)_{1-2 \theta, q}
\end{aligned}
$$

Therefore, in view of the result of Grisvard theorem in Triebel [14; p. 321],

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\theta, q}= \begin{cases}B_{p, q}^{1-2 \theta}(\Omega) & 1-2 \theta>\frac{1}{p} \\ B_{p, q}^{1-2 \theta}(\Omega) & 1-2 \theta<\frac{1}{p}\end{cases}
$$

Let $1 / 2<\theta<1$. Then from Proposition 4.1 it follows

$$
\begin{aligned}
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\theta, q} & =\left(L^{p}(\Omega), W^{-1, p}(\Omega)\right)_{2 \theta-1, q} \\
& =\left(\left(L^{p^{\prime}}(\Omega), W_{0}^{-1, p^{\prime}}(\Omega)\right)_{2 \theta-1, q^{\prime}}\right)^{*}
\end{aligned}
$$

where $p^{\prime}=p /(p-1)$. In view of Grisvard theorem if $2 \theta-1-1 / p^{\prime} \neq 0$ then

$$
\left(L^{p^{\prime}}(\Omega), W_{0}^{1, p^{\prime}}(\Omega)\right)_{\theta, q}=\left\{\begin{array}{cc}
B_{p^{\prime}, q^{\prime}}^{2 \theta-1}(\Omega) & 2 \theta-1>\frac{1}{p^{\prime}} \\
B_{p^{\prime}, q^{\prime}}^{2 \theta-1}(\Omega) & 2 \theta-1<\frac{1}{p^{\prime}}
\end{array}\right.
$$

From Theorem 4.8.2 in H. Triebel [14; p. 332], we obtain that

$$
\left(B_{p^{\prime}: q^{\prime}}^{2 \theta-1}(\Omega)\right)^{*}=B_{p, q}^{1-2 \theta}(\Omega)
$$

if $2 \theta-1-1 / p^{\prime} \neq 0$. Since $2 \theta-1-1 / p^{\prime} \neq 0$ i.e. $2 \theta-2+1 p \neq 0$, if $1 / 2<\theta<1$ and $2 \theta-2+1 / p \neq 0$ then

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\theta, q}=B_{p, q}^{1-2 \theta}(\Omega)
$$

Consequently, we obtain that

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1-\theta}{2}, q}=B_{p, q}^{\theta}(\Omega), \quad \text { if } \quad 0<\theta<\frac{1}{p}
$$

and

$$
\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1+\theta}{2}, q}=B_{p, q}^{-\theta}(\Omega) \quad \text { if } \quad 0<\theta<1-\frac{1}{p}
$$

Hence, if $0<\theta<\min \{1 / p, 1-1 / p\}$

$$
\begin{aligned}
& \left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1}{2}, q} \\
& \quad=\left(\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1-\theta}{2}, q},\left(W_{0}^{1, p}(\Omega), W^{-1, p}(\Omega)\right)_{\frac{1+\theta}{2}, q}\right)_{\frac{1}{2}, q} \\
& \quad=\left(B_{p, q}^{\theta}(\Omega), B_{p, q}^{-\theta}(\Omega)\right)_{\frac{1}{2}, q}=B_{p, q}^{0}(\Omega)
\end{aligned}
$$

The last equality is obtained from Theorem 1 of section 4.3 .1 in H . Treibel [14; p. 317]. Hence the proof is complete.

Theorem 4.3. Let $1<p, q<\infty$.
(i) If $2 / q-2+1 / p \neq 0$ then

$$
H_{p, q}= \begin{cases}B_{p, q}^{1-\frac{2}{q}}(\Omega) & \text { if } \quad \frac{1}{q}<\frac{1}{2}\left(1-\frac{1}{p}\right), \\ B_{p, q}^{1-\frac{2}{q}}(\Omega) & \text { if } \quad \frac{1}{q}>\frac{1}{2}\left(1-\frac{1}{p}\right) .\end{cases}
$$

(ii) If $\frac{1}{p^{\prime}}<1 / n\left(1-2 / q^{\prime}\right)$ then

$$
H_{p^{\prime}, q^{\prime}} \subset C_{0}(\bar{\Omega}) \subset L^{\infty} .
$$

Proof. The relation (i) follows directly from Theorem 4.2. Let $\frac{1}{p^{\prime}}<1 / n\left(1-2 / q^{\prime}\right)$. Then from (i)

$$
H_{p^{\prime}, q^{\prime}}=\left(W_{0}^{1, p^{\prime}}(\Omega), W^{-1, p^{\prime}}(\Omega)\right)_{\frac{1}{q^{\prime}}, q^{\prime}}=B_{p^{\prime}, q^{\prime}}^{1-\frac{2}{q^{\prime}}}(\Omega)
$$

and from Sobolev-Besov's and Sobolev's embedding theorems we obtain that

$$
B_{p^{\prime}, q^{\prime}}^{1-\frac{2}{q^{\prime}}}(\Omega) \subset W_{p^{\prime}}^{1-\frac{2}{q^{T}}} \subset C_{0}(\bar{\Omega})
$$

Hence, the first inclusion in (ii) follows.

## 5. Control problem for $L^{1}(\Omega)$-valued controller

As is seen in section 4 , if $1 / p^{\prime}-1 / n\left(1-2 / q^{\prime}\right)<0$ then we obtained that

$$
H_{p^{\prime}, q^{\prime}} \subset C_{0}(\bar{\Omega}) \subset L^{\infty}(\Omega) .
$$

Thus, since

$$
H_{p, q}=H_{p^{\prime} q^{\prime}}^{*} \supset C_{0}(\bar{\Omega})^{*} \supset L^{1}(\Omega)
$$

we consider $\Phi_{0}$ as an operator in $B\left(U, H_{p, q}\right)$. Hence it is possible to investigate the control problem for (3.11) and (3.12) in $H_{p, q}$. In what
follows in this section we fix $p$ and $q$ so that $1 / p^{\prime}-1 / n\left(1-2 / q^{\prime}\right)<0$. Then it immediately implies that $1<p<n /(n-1)$. Let $A$ be the infinitesimal generator of $S(t)$ as in section 3 . Then the equation (3.11) and (3.12) can be transformed into an abstract equation as follows

$$
\begin{aligned}
& z(t)=A z(t)+\Phi w(t) \\
& z(0)=g
\end{aligned}
$$

where $g=\left(g^{0}, g^{1}\right) \in Z_{p, q}$ and the controller operator is defined $\Phi w=\left(\Phi_{0} w, 0\right)$. In this case for the solution $u$ of (3.11) and (3.12) the equation satisfied by $\left(u(t), u_{t}(\cdot)\right)$ is an equation in $Z_{p, q}$ since $\Phi_{0}$ is an operator into $H_{p, q}$. Since the dual $\Phi_{0}^{*}$ of $\Phi_{0}$ is the operator from $L^{\infty}(\Omega)$ into $U^{*}$, the operator $\Phi_{0}^{*}$ may be considered as an operator from $H_{p^{\prime}, q^{\prime}}$ into $U^{*}$, Hence with the aid of Theorem 4.3 we remarked that the condition that $\Phi_{0}^{*} \phi=0$ almost everywhere can be rewrite to the fact that $\Phi_{0}^{*} \phi \equiv 0$ for $\phi \in Z_{p, q}$. We define the attainable set by

$$
R=\left\{\int_{0}^{t} S(t-\tau) \Phi w(\tau) d \tau: w \in L^{q}(0, t ; U), \quad t \geq 0\right\}
$$

Definition 5.1. (1) The system (3.11), (3.12) is approximately controllable if $\bar{R}=Z_{p, q}$, where $\bar{R}$ is the closure of $R$ in $Z_{p, q}$
(2) The system (3.14), (3.15) is observable if for $\phi \in Z_{p^{\prime}, q^{\prime}}$, $\Phi_{0}^{*}\left[S_{T}(t) \phi\right]^{0} \equiv 0$ implies $\phi=0$.
'THEOREM 5.1. Let the structural operator $F$ is an isomorphism. Then the system (3.11) and (3.12) is approximately controllable if and only if the system (3.14) and (3.15) is observable.

Proof. Let the system (3.11) and (3.12) is approximately controllabe. Then for $f \in Z_{p, q}^{*}$

$$
\left(f, \int_{0}^{t} S(t-\tau) \Phi w(\tau) d \tau\right)=0
$$

for $w \in L^{g}(0, t ; U)$ and $t>0$ implies $f=0$. By duality theorem it is equivalent to the fact that for any $f \in Z_{p, q}^{*}, \Phi^{*} S^{*}(t) f \equiv 0$ implies
$f=0$. Since the operator $F^{*}$ is an isomorphism by assumption, there exists $\phi \in Z_{p^{\prime}, q^{\prime}}$ such that $f=F^{*} \phi$. From (3.16) we obtain that

$$
\Phi_{0}^{*}\left[S^{*}(t) f\right]^{0}=\Phi_{0}^{*}\left[F S_{T}(t) \phi\right]^{0}=\Phi_{0}^{*}\left[S_{T}(t) \phi\right]^{0}
$$

Hence, the system (3.11) and (3.12) is approximately controllable iff for any $\phi \in Z_{p^{\prime}, q^{\prime}}, \Phi_{0}^{*}\left[S_{T}(t) \phi\right]^{0} \equiv 0$ implies $\phi=0$. Therefore, the statement is equivalent that the system (3.14) and (3.14) is observable.

Remark. When we deal with the control problem of (3.11) and (3.12) in negative space $W^{-1, p}(\Omega)$, we needed a assumption that the kernel $a(\cdot)$ is Hölder continuous for using of the properties of fundamental solution since $\Phi_{0}$ is not operator into $H_{p, q}$. If we assume that $a(\cdot)$ is Holder continuous then the fundamental solution of (3.11) and (3.12) exists (see in [13]). By fixing $p, q$ so that $1<p<n /(n-1)$ and $1 / p^{\prime}<1 / n\left(1-1 / q^{\prime}\right)$, we can obtain the Theorem 5.1 using the solution semigroup without requirement of fundamental solution of (3.11) and (3.12). Hence, the kernel $a(\cdot)$ need not be Holder continuous but has only to belong to $L^{q^{\prime}}(-h, 0)$ for wellposedness and regularity for equation (3.11) and (3.12).

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