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## Computational Flow Analysis Around Forward-Wing Small Aircraft

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### Abstract

Flow computations around forward sweep wing small aircraft have been conducted in this study. The main-wing of the forward-wing small aircraft is composed of two planforms: the inboard wing section with backward sweep angle which is known as strake and the outboard wing section with forward sweep angle. The geometrical discontinuity or kink generated by the combination of these two different planforms requires detailed flow analysis around wing. Four different solvers were used to calculate aerodynamic data and the accuracy of each method is examined. For the convenience of grid generation over the aircraft geometry, the overset grid method was applied. Through this calculation, the basic aerodynamic data of the forward-wing aircraft were provided and the aerodynamic characteristics of the wing is expounded.

가 (outboard) 가 (strake) (inboard) ,  
 (kink)  
 ,  
 4가  
 (Chimera grid)  
 : (forward wing), (small aircraft), (computational fluid  
 dynamics), (chimera or overset grid), (strake), (kink)

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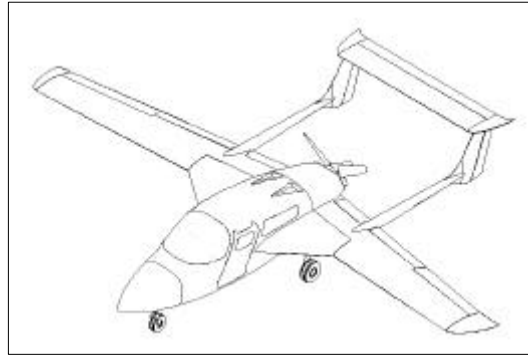
1.

(strake) (inboard) ,  
 가 (outboard) 가  
 (kink) ,

- 가  
 (1)  
 (2) +  
 (3) + +  
 (4) + 가  
 (V.3) 1  
 가  
 2 (V.4)

4가

DATCOM	: Empirical Code
CMARC	: Low-Order Panel Code
XM3D(i)	: 3-D Euler Code
XM3D(v)	: 3-D Navier-Stokes Code



3 XM3D[1]  
 (Chimera grid)

2.

(XM3D) 1

( , , )

3가

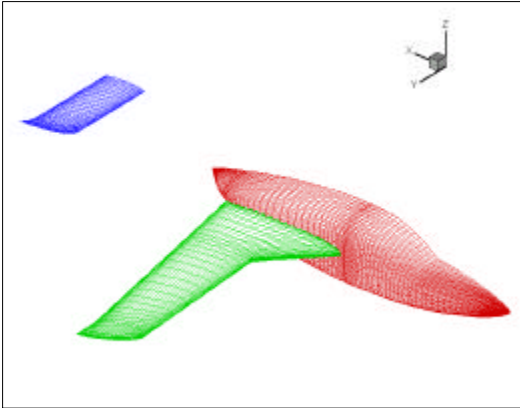
- (1) 1 :  $M_\infty=0.15, Re=1.2 \times 10^6$   
 (2) 2 :  $M_\infty=0.09, Re=3.0 \times 10^6$   
 (3) 3 :  $M_\infty=0.28, Re=9.0 \times 10^6$

(longitudinal)

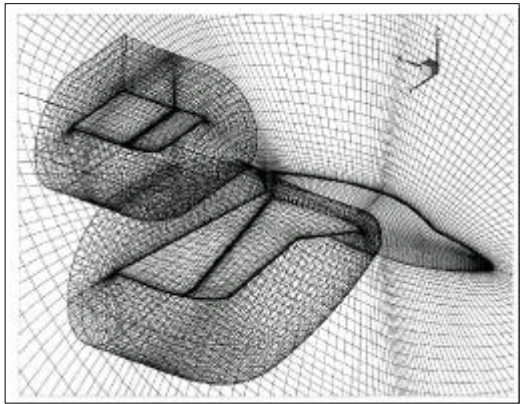
가가

3가

Chimera



2.



3. Chimera

CATIA

CAD (IGES)  
Gridgen [2]

가 Gridgen  
3  
1

Solver Geom	For XM3D(i) (Euler)	For XM3D(v) (Navier-Stokes)
Body	102x53x51=275,705	102x53x71=383,826
Wing	111x41x21=95,591	111x51x31=175,491
H-Tail	101x32x21=67,872	101x32x31=100,192
Total	439,168	659,509

3.

3 Thin-Layer Navier-Stokes

$$\partial_\tau \hat{Q} + \partial_\xi \hat{E} + \partial_\eta \hat{F} + \partial_\zeta \hat{G} = Re^{-1} \delta_\xi \hat{S} \quad (1)$$

(1) Beam & Warming[3], Steger  
[4] AF(Approximate Factorization)  
delta-form

$$\begin{aligned} & (I + h \delta_\xi \hat{A}^n + D_\xi^{(2)}) \\ & (I + h \delta_\eta \hat{B}^n + D_\eta^{(2)}) \\ & (I + h \delta_\zeta \hat{C}^n + D_\zeta^{(2)}) \Delta \hat{Q}^n = \\ & - \Delta t (\delta_\xi \hat{E} + \delta_\eta \hat{F} + \delta_\zeta \hat{G}) + D_e^{(4)} = \hat{R}^n \end{aligned} \quad (2)$$

(2) Jacobian A, B, C  
Pulliam &  
Chaussee[5]

$$T_{\xi}^n(I + h \delta_{\xi} A_{\xi} + D_{\xi}^{(2)}) \hat{N}(I + h \delta_{\eta} A_{\eta} + D_{\eta}^{(2)}) \hat{P} \quad \text{Euler}$$

$$(I + h \delta_{\xi} A_{\xi} + D_{\xi}^{(2)}) (T_{\xi}^{-1})^n \Delta \hat{Q}^n = \hat{R}^n \quad (3)$$

(3) Chimera  
hole point flag<sub>ib</sub>

trilinear interpolation

$$T_{\xi}^n(I + i_b h \delta_{\xi} A_{\xi} + i_b D_{\xi}^{(2)})$$

$$\hat{N}(I + i_b h \delta_{\eta} A_{\eta} + i_b D_{\eta}^{(2)}) \quad (4)$$

$$\hat{P}(I + i_b h \delta_{\xi} A_{\xi} + i_b D_{\xi}^{(2)})$$

$$(T_{\xi}^{-1})^n \Delta \hat{Q}^n = -i_b \hat{R}^n$$

Chimera

(hole-map)

[6] , trilinear interpolation  
stencil-walk [7]

Chimera

(pre-processing)

#### 4.

##### 4.1.1 (V.3)

Euler Navier-Stokes

$8.7 \times 10^6$

$1.1 \times 10^6$

16

2

CMARC

0

2

4

4

DATCOM, CMARC, Euler,

Navier-Stokes

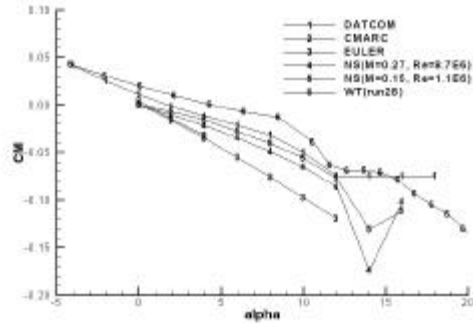
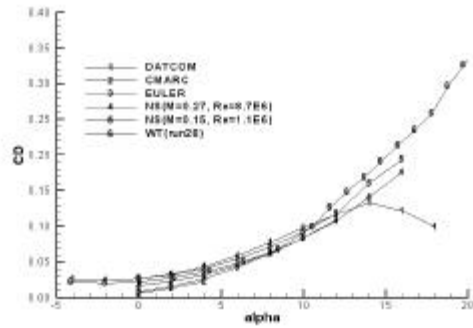
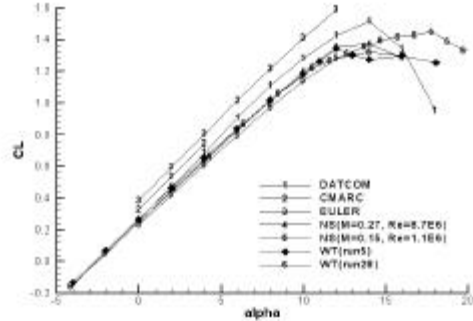
x=150inch

CMARC

solver

14°

가



4.

DATCOM

CMARC Euler

DATCOM

가 , run5  
 CMARC Euler DATCOM

, CMARC Euler  
 가

0.27

0.15

5

2°

12°

가 16°

가

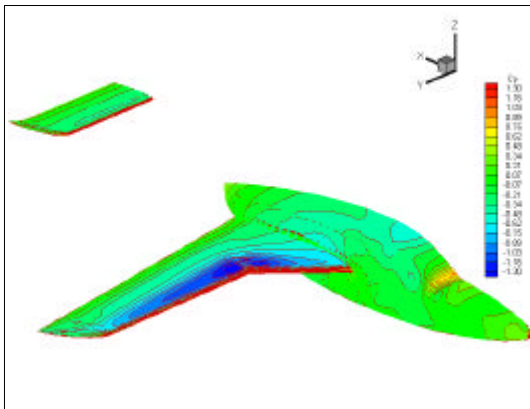
가

16°

가

가

, 가 ,  
 가



5.

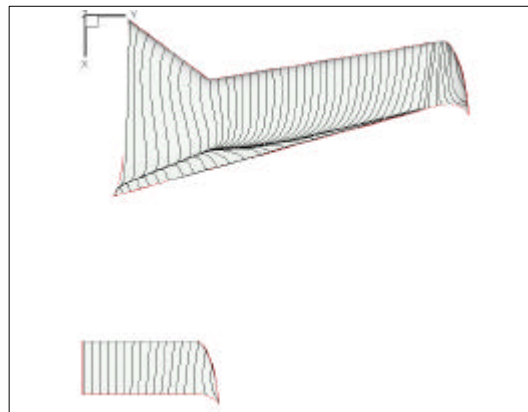
( $M_\infty=0.27$ ,  $Re=8.7 \times 10^6$ ,  $\alpha=2^\circ$ )

4

2

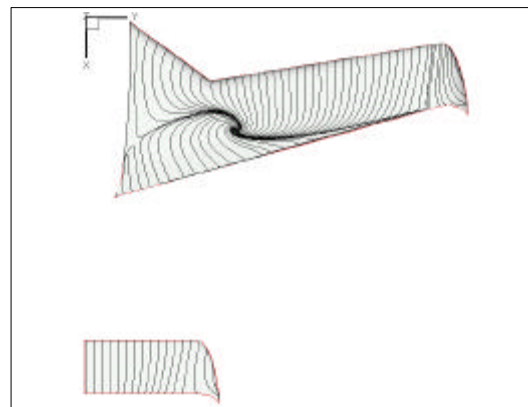
run5

run28



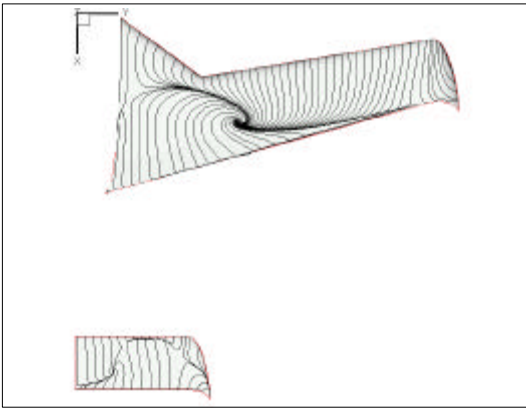
6.

( $M_\infty=0.27$ ,  $Re=8.7 \times 10^6$ ,  $\alpha=12^\circ$ )



7.

( $M_\infty=0.27$ ,  $Re=8.7 \times 10^6$ ,  $\alpha=14^\circ$ )



8. ( $M\infty=0.27, Re=8.7 \times 10^6, \alpha=16^\circ$ )

6, 7, 8  $12^\circ, 14^\circ,$   
 $16^\circ$  . 6  
 $12^\circ$  가 (   
 7, 8) 가 .  
 가  
 (wing root)  
 ,  
 (kink)

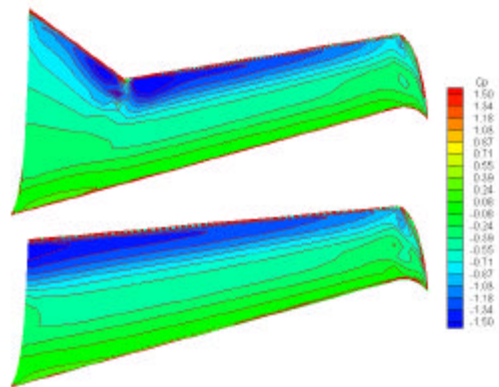
8  $16^\circ$  가 가  
 , 가 4  
 가 .

4.2 1 (V.3) 가

DATCOM

가 .  
 가  
 가

가 . ,  
 , , 가  
 [8]. 가  
 . 가 가  
 + 가  
 , 0.15,  
 $1.2 \times 10^6$  .



9. 가  
 ( $M\infty=0.15, Re=1.2 \times 10^6, \alpha=4^\circ$ )

9 0.15,  $4^\circ$   
 가 ,  
 가  
 가  
 가  
 . 10  
 가 가 가 , 가  
 가 가 가 ,  
 가 .  
 가

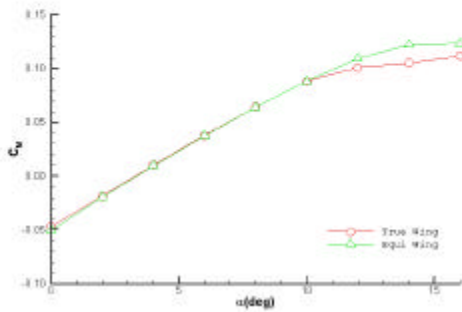
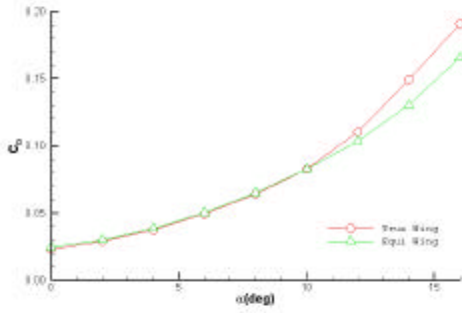
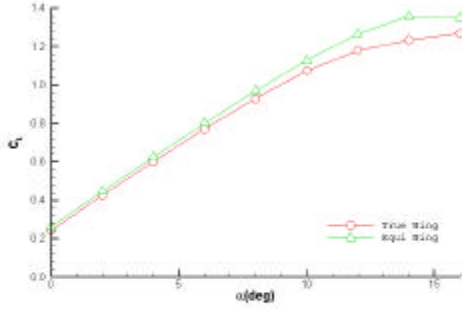
가 가 (out-board)

가 가 가 가

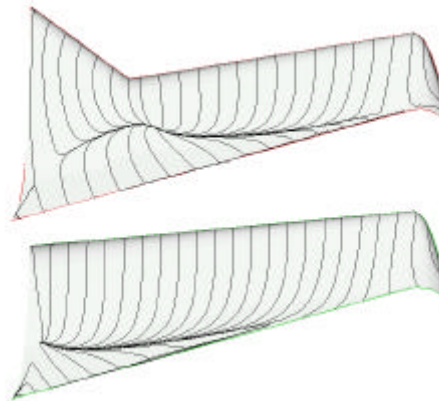
가 ,

가 ( 12)

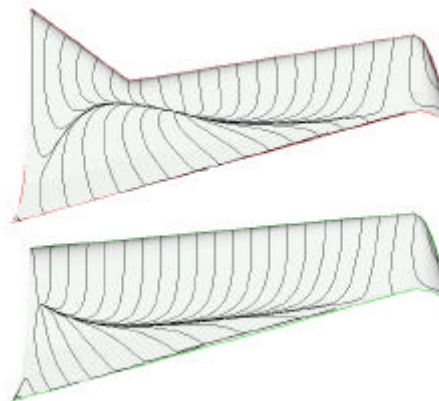
10



10. 가  
( $M_\infty=0.15, Re=1.2 \times 10^6$ )



11. 가  
( $M_\infty=0.15, Re=1.2 \times 10^6, \alpha=12^\circ$ )



12. 가  
( $M_\infty=0.15, Re=1.2 \times 10^6, \alpha=14^\circ$ )

가 11, 12  
12°  
(inboard) 11

1 2

4.3 2 (V.4)

V.4

2 (V.4),

1 (V.3)

2

13

가

2

0.15,

(V.4)

가

가 가

2

$1.2 \times 10^6$

14

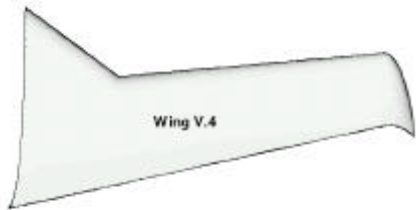
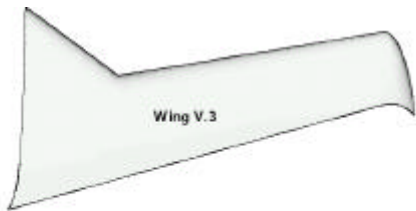
2

4가

가

2

- a. Body + Wing
- b. Body + Wing w/ Fillet
- c. Body + Wing + H-tail
- d. Body + Wing w/ Fillet + H-Ttail



13. 2

14 Body+Wing(a, b)

1 (V.3), 2

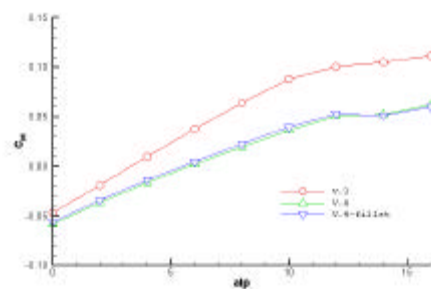
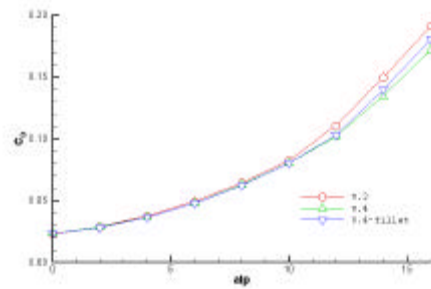
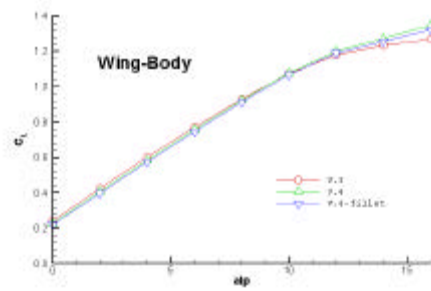
(V.4),

2

(V.4 w/ fillet)

2

(V.4 w/ fillet),



14. 2 (Wing+Body)

( $M_\infty=0.15$ ,  $Re=1.2 \times 10^6$ )



15 Body+Wing+Htail(c, d)

16 4°

가

Body+Wing(a, b)

14

. 1

2 (V.4)

가

가

2

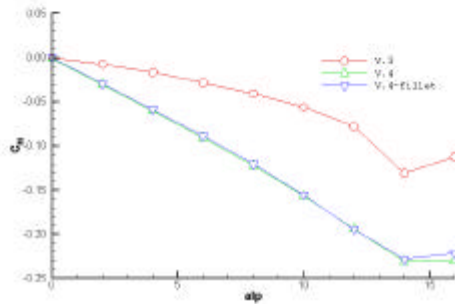
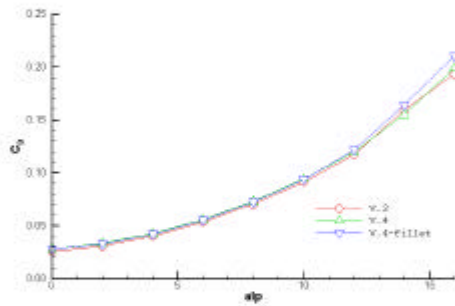
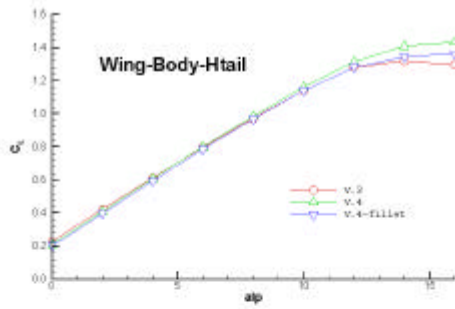
1

가 2 (V.4 w/ fillet)

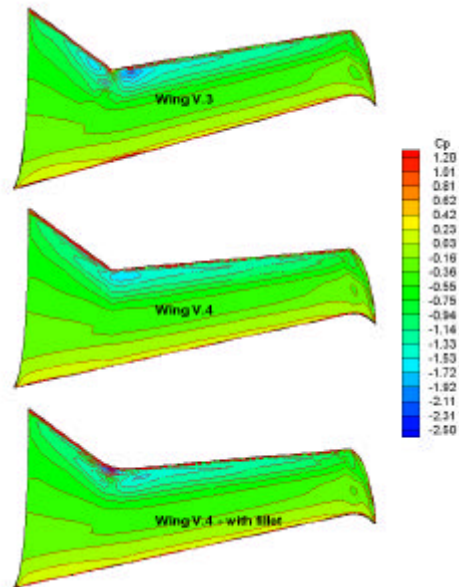
1

(V.4)

2



15. 2 (Wing+Body+Htail)  
(M<sub>∞</sub>=0.15, Re=1.2x10<sup>6</sup>)



16. 2 (M<sub>∞</sub>=0.15, Re=1.2x10<sup>6</sup>, α=4°)

5.

Navier-Stokes  
DATCOM, CMARC,

Euler

4가

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가 , 가

3 가

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