NONEXISTENCE OF GLOBAL SOLUTIONS FOR THE SEMILINEAR PARABOLIC SYSTEM

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1. Introduction

It is well-known that solutions of a semilinear parabolic system

$$u_t - u_{xx} = f(v)$$
 $(-a < x < a, t > 0),$
 $v_t - v_{xx} = g(u)$ $(-a < x < a, t > 0)$ with
 $u(\pm a, t) = 0$ $(t > 0),$ $u(x, 0) = u_0(x)$ $(-a < x < a),$
 $v(\pm a, t) = 0$ $(t > 0),$ $v(x, 0) = v_0(x)$ $(-a < x < a)$

may blow up in finite time if the reaction terms f and g are positive, increasing and superlinear and if initial data u_0 and v_0 satisfy that

$$u_0'(x) \le 0$$
, $v_0'(x) \le 0$, if $0 < x < a$, $u_0(0) > 0$, $v_0(0) > 0$, $u_0(a) = 0 = v_0(a)$

(see Friedman and Giga[1] and the references therein).

More recently Gang and Sleeman [5] and Nam, Ju and Kim [6] established a result concerning the blow-up problem of the more general form than above system.

In this paper, we consider a semilinear parabolic system

(1)
$$u_t - u_{xx} = f(u, v) \qquad (-a \le x \le a, \ t \ge 0) \\ v_t - v_{xx} = g(u, v) \qquad (-a \le x \le a, \ t \ge 0)$$

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with boundary conditions

(2)
$$u(\pm a, t) = 0, v(\pm a, t) = 0, t \ge 0,$$

and initial conditions

(3)
$$u(x,0) = u_0(x), \ v(x,0) = v_0(x), \quad -a \le x \le a.$$

It is well-known that classical solutions of the system (1) may blow up in finite time if f and g satisfy certain conditions (see Gang and Sleeman[5]). We define

$$T^* = \sup\{T > 0 \mid (u, v) \text{ is bounded and solves } (1) \text{ in } [-a, a] \times (0, T)\}.$$

Then T^* is called the *life span* of solutions (u, v). If T is infinite, the solutions are global. If T is finite one has

(4)
$$\lim_{t \to T^*} ||u(x,t)||_{\infty} = \infty \text{ or } \lim_{t \to T^*} ||v(x,t)||_{\infty} = \infty,$$

since otherwise solutions could be extended beyond T. When (4) holds we say that the solution blows up in finite time.

Here we are interested in the question of global existence and nonexistence or life span of the solutions of (1).

In section 2 we shall establish a blow-up for solutions (u, v) of (1) satisfying (2) and (3). The main idea is based on the method of Gang and Sleeman[5].

In section 3 for given special reaction terms in (1) we obtain the life span such that solutions blow up in finite time.

2. Preliminaries

In this section we give a general theorem concerning the nonexistence of global solutions to the system (1) satisfying the initial-boundary conditions.

Suppose that u(x,t) and v(x,t) are local solutions to the system (1). From the standard theorem of PDE(see Smoller [7]), the existence of such solutions are guaranteed on $[-a,a] \times [0,T)$ for some T>0.

Nonexistence of Global Solutions for the Semilinear Parabolic System 69

Let

(5)
$$g_1(t) = \int_{-a}^{a} \phi(x) u(x,t) dx, \ 0 \le t < T, \\ g_2(t) = \int_{-a}^{a} \phi(x) v(x,t) dx, \ 0 \le t < T$$

where $\phi(x)$ is the first normalized eigenfunction which solves the eigenvalue problem

(6)
$$\phi_{xx} + r\phi = 0, \quad x \in (-a, a)$$
$$\phi(\pm a) = 0.$$

Then

$$g_1'(t) = \int_{-a}^a \phi(x) u_t(x,t) dx$$

= $\int_{-a}^a \phi(x) u_{xx}(x,t) dx + \int_{-a}^a \phi(x) f(u,v) dx$.

An integration by parts and (6) shows that

(7)
$$g_1'(t) = -rg_1(t) + \int_{-a}^{a} \phi(x)f(u,v)dx.$$

Similarly,

(8)
$$g_2'(t) = -rg_2(t) + \int_{-a}^a \phi(x)g(u,v)dx.$$

Suppose that there exists a function $G_i: \mathbb{R}^2 \to \mathbb{R}$ (i = 1, 2) such that the inequality

(9)
$$\int_{-a}^{a} \phi(x) f(u,v) dx \ge G_1(g_1(t),g_2(t)),$$

$$\int_{-a}^{a} \phi(x) g(u,v) dx \ge G_2(g_1(t),g_2(t)).$$

holds. If such a function G_i can be suitably determined, then from (7) and (8) we have the following differential inequalities

(10)
$$g_1'(t) \ge -rg_1(t) + G_1(g_1(t), g_2(t)), \\ g_2'(t) \ge -rg_2(t) + G_2(g_1(t), g_2(t))$$

with initial conditions

(11)
$$g_1(0) = \int_{-a}^{a} \phi(x)u(x,0)dx, \\ g_2(0) = \int_{-a}^{a} \phi(x)v(x,0)dx.$$

Now we consider the system of the following ordinary differential equations associated with (10) and (11);

(12)
$$y_1'(t) = -ry_1(t) + G_1(y_1(t), y_2(t)), y_2'(t) = -ry_2(t) + G_2(y_1(t), y_2(t))$$

with initial conditions

(13)
$$y_1(0) = g_1(0), \\ y_2(0) = g_2(0).$$

Notice that blow-up behavior of solutions to the differential inequality (10) satisfying (11) associated with the system (12) is achived if the functions G_i can be chosen to be quasimonotone in the following definition.

DEFINITION 2.1. A function $G: D \subset \mathbb{R}^2 \to \mathbb{R}^2$ is said to be quasimonotone nondecreasing if $\frac{\partial G_i}{\partial y_j} \geq 0$ for $i \neq j$ where $G = (G_1, G_2), y = (y_1, y_2)$.

The next results is due to Gang and Sleeman[5].

LEMMA 2.2. Suppose that $G(y) = (G_1(y_1, y_2), G_2(y_1, y_2))$ is quasimonotone nondecreasing and that solutions to the system (12) and (13) exist only in a finite time interval. That is, there exists a time $\tau > 0$ such that the solution to the system (12) exists for $t \in [0, \tau)$ and $y_1^2(t) + y_2^2(t) \to \infty$ as $t \to \tau$. Then the solution of (10) exists for only a finite time interval $0 \le t < t_0(t_0 \le \tau)$ and $g_1^2(t) + g_2^2(t) \to \infty$ as $t \to t_0$.

THEOREM 2.3. Suppose that the inequalities (9) hold in which $G(y) = (G_1(y), G_2(y))$ is quasimonotone nondecreasing and that the solutions of (12) blow up in finite time. Then the solutions to the system (1) satisfying the initial-boundary coditions blow up in finite time.

Proof. It follows from a direct consequence of Lemma 2.2.

An example which satisfies the inequalities (9) is as follows;

EXAMPLE 2.4. Let $f(u, v) = \lambda u + \lambda^2 (u^2 - v^2)$ and $g(u, v) = \lambda v - 2\lambda^2 uv$ ($\lambda > 0$) and let $\phi(x)$ be the first eigenfunction of the eigenvalue problem (6). By using Hölder's inequality, we obtain

$$\int_{-a}^{a} \phi f(u,v) dx \geq \lambda g_1(t) + \lambda^2 \left(\int_{-a}^{a} \phi u \ dx \right)^2 - \lambda^2 \int_{-a}^{a} \phi v^2 dx.$$

Let $R \subset \Omega_c = \{(u,v) | u \geq 0, 0 \leq v \leq c\}$ be an invariant region(See Lemma 3.2). Then

$$\int_{-c}^{a} \phi v^2 dx \le c^2.$$

Hence,

$$\int_{-a}^a \phi f(u,v) dx \geq \lambda g_1(t) + \lambda^2 g_1^2(t) - \lambda^2 c^2$$

for all u, v in R.

Similarly

$$\int_{-a}^{a}\phi g(u,v)dx\geq \lambda g_{2}(t)-2\lambda^{2}cg_{1}(t)$$

for all u, v in R.

If we choose $G_1(y_1, y_2) = \lambda y_1 + \lambda^2(y_1^2 - c^2)$ and $G_2(y_1, y_2) = \lambda y_2 - 2\lambda^2 c y_1$, then we see that G_1 is quasimonotone nondecreasing since $\frac{\partial G_1}{\partial y_2} = 0$. Consequently it is sufficient to consider the associated ordinary differential inequality;

$$g_1'(t) \geq -rg_1(t) + \lambda g_1(t) + \lambda^2(g_1^2(t) - c^2) \ g_1(0) = \int_{-a}^a \phi(x) u_0(x) dx.$$

3. Blow-up of the Solution for the Special Reaction Terms

In this section we analyse the following semilinear parabolic system

(P)
$$u_t - u_{xx} = \lambda u + \lambda^2 (u^2 - v^2), \quad (-a \le x \le a, \ t \ge 0)$$

 $v_t - v_{xx} = \lambda v - 2\lambda^2 uv, \quad (-a \le x \le a, \ t \ge 0)$

satisfying (2) and (3), where λ is a positive constant.

First, we deduce some geometrical and qualitative properties of (P).

LEMMA 3.1. The system (P) is symmetric about u-axis and invariant under a rotation through an angle of $\frac{2\pi}{3}$.

Proof. We introduce the following notations;

$$J = rac{\partial}{\partial t} - rac{\partial^2}{\partial x^2},$$
 $A = \left(egin{array}{c} u \ v \end{array}
ight), A^t = (u, v),$ $F(A^t) = \left(egin{array}{c} f(A^t) \ g(A^t) \end{array}
ight) = \left(egin{array}{c} \lambda u + \lambda^2 (u^2 - v^2) \ \lambda v - 2\lambda^2 uv \end{array}
ight).$

Then we can write (P) in the form

$$JA = F(A^t).$$

Let R_1 be a reflection about the u-axis and let R_2 be a rotation through an angle θ , i.e.,

$$R_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, R_2 = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

Then we can prove the followings;

$$J(R_1A) = F\left((R_1A)^t\right)$$

Nonexistence of Global Solutions for the Semilinear Parabolic System 73

and

$$J\left(R_2(\frac{2\pi}{3})A\right) = F\left[\left(R_2(\frac{2\pi}{3})A\right)^t\right].$$

This complete the proof of our lemma.

By Lemma 3.1, we will only consider the system (P) in region Γ which is bounded from below by v = 0 and from the left by $v = \sqrt{3}u$ rather than the (u, v)-plane.

LEMMA 3.2. Let

$$\Gamma_c = \{ (u, v) \mid u \ge 0, 0 \le v \le c, v \le \sqrt{3}u, c \ge \frac{\sqrt{3}}{2\lambda} \}.$$

If any solution(u, v) of (P) satisfies all of its boundary and initial values in Γ_c , then $(u, v) \in \Gamma_c$ for all (x, t) at which the solution is defined. That is, Γ_c is an invariant region for the system (P).

Proof. The rescaling functions

$$(14) w = \sqrt{3}u - v \text{ and } z = v$$

satisfy the system

(15)
$$w_t - w_{xx} = \frac{\lambda}{\sqrt{3}} w(\sqrt{3} + \lambda w + 4\lambda z)$$
$$z_t - z_{xx} = \frac{\lambda}{\sqrt{3}} z(\sqrt{3} - 2\lambda w - 2\lambda z).$$

The rescaling function (14) transform the region Γ in (u, v)-plane into the whole of the first quadrant in the (w, z)-plane and the region Γ_c becomes a strip

$$\Omega_c = \{ (w, z) \mid w \geq 0, 0 \leq z \leq c, c \geq \frac{\sqrt{3}}{2\lambda} \}$$

in the first quadrant of the (w, z)-plane.

Notice that from the local existence theorem (see [7]), it is well-known fact that there exists a solution to the system (P) for any

initial value $(w_0, z_0) \in \Omega_c$ and for $(x, t) \in [-a, a] \times [0, \epsilon)$ where $\epsilon > 0$ is sufficiently small. Also, we may assume that $[0, \epsilon)$ is the maximal time interval of the existence of the solution for (P).

Using Theorem 14.11 in [7] we know that the solution can not escape the region Ω_c by crossing the lower boundary z=0 and the left boundary w=0. Therefore we must only show that the solution can not leave by crossing the upper boundary z = c.

To show this, setting $I(z(x,t)) = z(x,t) - c(c \ge \frac{\sqrt{3}}{2\lambda})$, we obtain

$$\Omega_c = \{ (w, z) \mid w \ge 0, z \ge 0, I \le 0 \}.$$

Assume that there is an $x_0 \in (-a, a)$ and $t_0 \in (0, \epsilon)$ such that

$$I(z(x,t)) < 0, \quad (x,t) \in (-a,a) \times (0,t_0)$$

 $I(z(x_0,t_0)) = 0.$

Then since $\frac{\partial}{\partial t}I(z(x,t)) = z_{xx} + \frac{\lambda}{\sqrt{3}}z(\sqrt{3} - 2\lambda w - 2\lambda z)$ from (15), (16)

$$\frac{\partial}{\partial t} I(z(x_0, t_0)) = z_{xx}(x_0, t_0) - \frac{2}{\sqrt{3}} \lambda^2 wz - \frac{2}{\sqrt{3}} \lambda^2 z(z - \frac{\sqrt{3}}{2\lambda})$$

$$= z_{xx}(x_0, t_0) - \frac{2}{\sqrt{3}} \lambda^2 wz - \frac{2}{\sqrt{3}} \lambda^2 \delta(\frac{\sqrt{3}}{2\lambda} + \delta)$$

$$< z_{xx}(x_0, t_0)$$

where $\delta = z(x_0, t_0) - \frac{\sqrt{3}}{2\lambda} \ge 0$. Let $K(x) = z(x, t_0) - c$. Then $K(x_0) = I(z(x_0, t_0)) = 0$ and $K'(x)=z_x(x,t_0).$

If $K'(x_0) = z_x(x_0, t_0)$ is positive in some interval $(x_0, x_0 +$ η), then K(x) is also positive in that interval $(x_0, x_0 + \eta)$ for η sufficiently small.

Therefore,

$$z(x,t)-c>0 \text{ for } (x,t)\in (x_0,x_0+\eta)\times (t_0,t_0+\eta).$$

This is a contradiction to z(x,t)-c<0 for $(x,t)\in(-a,a)\times(0,t_0)$ So $K'(x_0) > 0$ is impossible.

Nonexistence of Global Solutions for the Semilinear Parabolic System 75

Similarly, we can show that $K'(x_0) < 0$ is impossible. Hence $K'(x_0) = 0$.

Notice that since $K(x_0) = 0$, $K'(x_0) = 0$, and $K(x) \le 0$, K(x) has a local maximum at $x = x_0$ and $K''(x_0) = z_{xx}(x_0, t_0) \le 0$. So, from the inequality (16),

$$\frac{\partial}{\partial t}I(z(x_0,t_0)) < z_{xx}(x_0,t_0) \le 0$$

which means that the solution can not leave Ω_c by crossing the upper boundary z = c. Therefore Ω_c is invariant.

Here, we establish the nonexistence of the global solution for the system (P).

First, we consider the system (P) with initial condition

(17)
$$(u_0(x), v_0(x)) \in \Gamma_c \text{ for } x \in [-a, a], c \ge \frac{\sqrt{3}}{2\lambda}.$$

From the local existence theorem for parabolic system, we see that there is a solution to the initial value problem (P) satisfying (17) which exists for $0 \le t < T$. From Lemma 3.2 and the initial condition (17), we obtain that

(18)
$$u(x,t) \ge 0, 0 \le v(x,t) \le c, c \ge \frac{\sqrt{3}}{2\lambda}$$

for $(x,t) \in [-a,a] \times [0,T)$.

LEMMA 3.3. For the eigenvalue problem (6), $r = \frac{\pi^2}{16a^2}$ is the least eigenvalue and $\phi(x) = \frac{\pi}{4\sqrt{2}a}(\cos\frac{\pi}{4a}x + \sin\frac{\pi}{4a}x)$ is the corresponding normalized eigenfunction.

From Example 2.4, we consider the following system of ordinary differential inequalities

(19)
$$y_1'(t) \ge -ry_1(t) + \lambda y_1(t) + \lambda^2 (y_1^2(t) - c^2), \\ y_2(t) \ge -ry_2(t) + \lambda y_2(t) - 2\lambda^2 c y_1(t)$$

with initial conditions

(20)
$$y_1(0) = \int_{-a}^{a} \phi(x) u_0(x) dx, \\ y_2(0) = \int_{-a}^{a} \phi(x) v_0(x) dx.$$

THEOREM 3.4. If the system of ordinary differential inequalities (19) satisfying (20) has a unbounded solution, then the system (P) satisfying (17) blows up in finite time.

Proof. Since the first inequality of (19) does not depend on the variable y_2 , we need only consider the following equation associated with the first inequality;

(21)
$$z' = (\lambda - r)z + \lambda^{2}(z^{2} - c^{2})$$
$$z(0) = y_{1}(0).$$

Since $(\lambda - r)^2 + 4\lambda^4 c^2$ is positive, we can separate the right-hand side of the first equation of (21) into

$$\lambda^2 z^2 + (\lambda - r)z - \lambda^2 c^2 = \lambda^2 (z - z_1)(z - z_2),$$

where $z_1 + z_2 = \frac{r - \lambda}{\lambda^2}$, $z_1 z_2 = -c^2$, and $z_1 < 0 < z_2$. Consequently, (21) implies that

(22)
$$z' = \lambda^2 (z - z_1)(z - z_2)$$

and also z_1 and z_2 are the equilibria of (22) in which $z=z_1$ is stable while $z=z_2$ is unstable.

In the region below $z=z_2$, all the solutions of (21) exist globally. So we will only consider the region above $z=z_2$, i.e., $z>z_2>0>z_1$.

Integrating (22) from 0 to t in this region, we obtain

$$\frac{1}{z_2 - z_1} \left(\frac{dz}{z - z_2} - \frac{dz}{z - z_1} \right) = \lambda^2 dt$$

or

$$\frac{1}{z_2 - z_1} \int_{z_0}^{z} \frac{dz}{z - z_2} - \frac{1}{z_2 - z_1} \int_{z_0}^{z} \frac{dz}{z - z_1} = \int_{0}^{t} \lambda^2 dt$$

where $z_2 < z_0 < z$. So

$$\frac{z-z_2}{z-z_1} = \left(\frac{z_0-z_2}{z_0-z_1}\right) e^{\lambda^2(z_2-z_1)t}$$

or

$$z = \frac{z_2(z_0 - z_1) - z_1(z_0 - z_2)e^{\lambda^2(z_2 - z_1)t}}{(z_0 - z_1) - (z_0 - z_2)e^{\lambda^2(z_2 - z_1)t}}$$

where $z_2(z_0 - z_1) - z_1(z_0 - z_2)e^{\lambda^2(z_2 - z_1)t}$ is positive.

On solving the equation $(z_0 - z_1) - (z_0 - z_2)e^{\lambda^2(z_2 - z_1)t} = 0$, we obtain the life span $t = T^*$ of the system (P),

$$T^* \equiv T(z_0, \lambda) = \frac{1}{\lambda^2(z_2 - z_1)} \left[ln(z_0 - z_1) - ln(z_0 - z_2) \right].$$

Since $\frac{1}{z_2-z_1}>0$ and $\frac{z_0-z_1}{z_0-z_2}>1$, T is positive. Hence we have proved.

LEMMA 3.5. If $z_0 > z_2$, then the solution of (21) exists only in a finite time interval $0 \le t < T(z_0, \lambda)$ with

$$\lim_{t\to T}z(t)=\infty.$$

REMARK. In order to obtain an explicit condition for the blowup of the solution for the system (P) satisfying (17), we need to express z_0 and z_2 in terms of λ , r, ϕ , and (u_0, v_0) . First,

$$z_0 = y_1(0) = \int_{-a}^{a} \phi(x) u_0(x) dx.$$

From $\lambda^2 z^2 + (\lambda - r)z - \lambda^2 c^2 = 0$, we have the larger root

$$z_2=rac{r-\lambda+\sqrt{(\lambda-r)^2+4\lambda^4c^2}}{2\lambda^2}$$

where $r = \frac{\pi^2}{16a^2}$, $c = \frac{\sqrt{3}}{2\lambda} + \delta$, $\delta \ge 0$. So, (23)

$$z_2 = rac{\pi^2 - 16\lambda a^2}{32a^2\lambda^2} + rac{1}{2\lambda^2} \left[(rac{\pi^2 - 16\lambda a^2}{16a^2})^2 + 4\lambda^4 (rac{\sqrt{3}}{2\lambda} + \delta)^2
ight]^{rac{1}{2}}.$$

THEOREM 3.6. If the blow-up condition

$$\int_{-a}^{a} \phi(x) u_0(x) dx > \frac{\pi^2 - 16\lambda a^2}{32a^2\lambda^2} + \frac{1}{2\lambda^2} \left[\left(\frac{\pi^2 - 16\lambda a^2}{16a^2} \right)^2 + 4\lambda^4 \left(\frac{\sqrt{3}}{2\lambda} + \delta \right)^2 \right]^{\frac{1}{2}}$$

holds where

$$\phi(x) = \frac{\pi}{4\sqrt{2}a}(\cos\frac{\pi}{4a}x + \sin\frac{\pi}{4a}x)$$

and $\delta > 0$ is an arbitrary constant, then the solution of (P) satisfying (17) blows up in finite time.

REMARK. If $a = \frac{\pi}{4}$, then $z_0 > z_2$ implies that

$$\frac{1}{\sqrt{2}}\int_{-\frac{\pi}{4}}^{\frac{\pi}{4}}(cosx+sinx)dx > \frac{1-\lambda+\sqrt{(1-\lambda)^2+4\lambda^4c^2}}{2\lambda^2}.$$

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