

## GENERALIZED REIDEMEISTER NUMBER ON A TRANSFORMATION GROUP

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ABSTRACT. In this paper we study the generalized Reidemeister number  $R(\varphi, \psi)$  for a self-map  $(\varphi, \psi) : (X, G) \rightarrow (X, G)$  of a transformation group  $(X, G)$ , as an extension of the Reidemeister number  $R(f)$  for a self-map  $f : X \rightarrow X$  of a topological space  $X$ .

### 1. Introduction

It is observed that the number of the fixed point classes for a self-map  $f : X \rightarrow X$  of a compact connected ANR could be calculated by defining an equivalence relation on the fundamental group  $\pi_1(X, x_0)$ .

The number of equivalence classes of  $\pi_1(X, x_0)$ , the Reidemeister number  $R(f)$ , equals the number of the fixed point classes of  $f$ .

F.Rhodes [3] represented the fundamental group  $\sigma(X, x_0, G)$  of a transformation group  $(X, G)$ , a group  $G$  of homeomorphisms of a space  $X$ , as a generalization of the fundamental group  $\pi_1(X, x_0)$  of a topological space  $X$ .

In the present paper we defined the generalized Reidemeister number  $R(\varphi, \psi)$  for a self-map  $(\varphi, \psi) : (X, G) \rightarrow (X, G)$  of the transformation group  $(X, G)$  and investigate its homotopy invariance. We also give the algebraic estimation of the definition of  $R(\varphi, \psi)$  in the same way as in [2].

### 2. Preliminaries

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In this paper, a transformation group is a pair  $(X, G)$ , where  $X$  is a path connected space with base point  $x_0$  and  $G$  is a group of homeomorphisms of  $X$ . A map  $(\varphi, \psi): (X, G) \rightarrow (X, G)$  consists of a continuous map  $\varphi: X \rightarrow X$  and a homomorphism  $\psi: G \rightarrow G$  such that  $\varphi(gx) = \psi(g)\varphi(x)$  for every pair  $(x, g)$ .

Given any element  $g$  of  $G$ , a path  $\alpha$  of order  $g$  with base point  $x_0$  is a continuous map  $\alpha: I \rightarrow X$  such that  $\alpha(0) = x_0$  and  $\alpha(1) = gx_0$ . A path  $\alpha$  of order  $g_1$  and a path  $\beta$  of order  $g_2$  form a new path  $\alpha + g_1\beta$  of order  $g_1g_2$  defined by the following equations

$$(\alpha + g_1\beta)(t) = \begin{cases} \alpha(2t), & 0 \leq t \leq \frac{1}{2}, \\ g_1\beta(2t - 1), & \frac{1}{2} \leq t \leq 1. \end{cases}$$

Two paths  $\alpha$  and  $\beta$  of the same order  $g$  are said to be homotopic if there is a continuous map  $F: I \times I \rightarrow X$  such that

$$\begin{aligned} F(t, 0) &= \alpha(t), & 0 \leq t \leq 1, \\ F(t, 1) &= \beta(t), & 0 \leq t \leq 1, \\ F(0, s) &= x_0, & 0 \leq s \leq 1, \\ F(1, s) &= gx_0, & 0 \leq s \leq 1. \end{aligned}$$

The equivalence relation  $\alpha \sim \beta$  denotes that  $\alpha$  and  $\beta$  are homotopic paths of the same order. Denote the equivalence class containing a path  $\alpha$  of order  $g$  by  $[\alpha; g]$ . Two homotopic classes of paths of different orders  $g_1$  and  $g_2$  are distinct, even if  $g_1x_0 = g_2x_0$ . F.Rhodes [3] showed that the set of homotopy classes of paths of prescribed order with the rule of composition  $*$  is a group, where  $*$  is defined by  $[\alpha; g_1] * [\beta; g_2] = [\alpha + g_1\beta; g_1g_2]$ . This group was called the fundamental group of  $(X, G)$  with base points  $x_0$ , and was denoted by  $\sigma(X, x_0, G)$ . He also proved that  $\sigma(X, x_0, G)$  is an invariant of the base point  $x_0$ .

### 3. Main results

Let  $(\varphi, \psi): (X, G) \rightarrow (X, G)$  be a mapping. It is easy to see that if  $\alpha$  is a path in  $X$  of order  $g$  with base point  $x_0$  then  $\varphi\alpha$  is a path in  $X$  of order  $\psi(g)$  with base point  $\varphi(x_0)$ . Furthermore, if  $\alpha \sim \beta$  then  $\varphi\alpha \sim \varphi\beta$ . Thus  $(\varphi, \psi)$  induces a homomorphism  $(\varphi, \psi)_*: \sigma(X, x_0, G) \rightarrow \sigma(X, \varphi(x_0), G)$  defined by  $(\varphi, \psi)_*[\alpha; g] = [\varphi\alpha; \psi(g)]$ .

If  $\lambda$  is a path from  $\varphi(x_0)$  to  $x_0$ , then  $\lambda$  induces an isomorphism

$$\lambda_* : \sigma(X, \varphi(x_0), G) \rightarrow \sigma(X, x_0, G)$$

defined by  $\lambda_*[\alpha; g] = [\lambda\rho + \alpha + g\lambda; g]$  for each  $[\alpha; g] \in \sigma(X, \varphi(x_0), G)$ , where  $\rho(t) = 1-t$ . This isomorphism  $\lambda_*$  depends only on the homotopy class of  $\lambda$ .

Consider the composition

$$\sigma(X, x_0, G) \xrightarrow{(\varphi, \psi)_*} \sigma(X, \varphi(x_0), G) \xrightarrow{\lambda_*} \sigma(X, x_0, G).$$

**DEFINITION 3.1.** Let  $\lambda_*(\varphi, \psi)_* = (\varphi, \psi)_\sigma$ . Two elements  $[\alpha; g_1]$  and  $[\beta; g_2]$  in  $\sigma(X, x_0, G)$  are said to be  $(\varphi, \psi)_\sigma$ -equivalent, denoted by  $[\alpha; g_1] \stackrel{(\varphi, \psi)_\sigma}{\sim} [\beta; g_2]$ , if there exists  $[\gamma; g] \in \sigma(X, x_0, G)$  such that  $[\alpha; g_1] = [\gamma; g][\beta; g_2](\varphi, \psi)_\sigma([\gamma; g]^{-1})$ . This is an equivalence relation on  $\sigma(X, x_0, G)$ . Let  $\sigma(X, x_0, G)'(\varphi, \psi)_\sigma$  be the set of equivalence classes of  $\sigma(X, x_0, G)$  under  $(\varphi, \psi)_\sigma$ -equivalence.

The cardinality of  $\sigma(X, x_0, G)'(\varphi, \psi)_\sigma$  is the *algebraic Reidemeister number* of  $(\varphi, \psi)_\sigma$ , and is denoted by  $R_*(\varphi, \psi)_\sigma$ . With this view, we may define the *Reidemeister number* of a map  $(\varphi, \psi); (X, G) \rightarrow (X, G)$ ,  $R(\varphi, \psi)$ , to be the algebraic Reidemeister number of  $(\varphi, \psi)_\sigma$ . In symbols,

$$R(\varphi, \psi) = R_*(\varphi, \psi)_\sigma = \#\sigma(X, x_0, G)'(\varphi, \psi)_\sigma.$$

**LEMMA 3.2.** *The definition of  $R(\varphi, \psi)$  is independent of the choice of the path  $\lambda$  from  $\varphi(x_0)$  to  $x_0$ .*

*Proof.* Let  $\tau$  denote another path from  $\varphi(x_0)$  to  $x_0$ . Then  $\lambda^{-1}\tau$  is a loop at  $x_0$  and therefore induces an inner automorphism

$$(\lambda^{-1}\tau)_* : \sigma(X, x_0, G) \rightarrow \sigma(X, x_0, G)$$

generated by the element  $[\lambda^{-1}\tau; e]$ , since

$$(\lambda^{-1}\tau)_*[\alpha; g] = [\lambda^{-1}\tau\rho; e][\alpha; g][\lambda^{-1}\tau; e].$$

Applying this automorphism to the left-hand side of  $\lambda_*(\varphi, \psi)_*$  we have

$$R_*(\lambda_*(\varphi, \psi)_*) = R_*(\tau_*\lambda_*^{-1}\lambda_*(\varphi, \psi)_*) = R_*(\tau_*(\varphi, \psi)_*).$$

Hence we have independence of the path  $\lambda$ .  $\square$   $\square$

For a given homotopy  $F : \varphi_1 \cong \varphi_2 : X \rightarrow X$  and a given path  $c : I \rightarrow X$ , define the (diagonal) path  $\langle F, c \rangle : I \rightarrow X$  by  $\langle F, c \rangle(t) = F(c(t), t)$ ,  $0 \leq t \leq 1$ . Then the path  $\langle F, c \rangle$  preserves inverse in the following sense.

LEMMA 3.3. [1]  $\langle F, c \rangle^{-1} = \langle F^{-1}, c^{-1} \rangle$ .

Our first result is the following.

THEOREM 3.4. (Homotopy Invariance) *Let  $(\varphi_1, \psi_1), (\varphi_2, \psi_2)$  be self-maps of  $(X, G)$ . If  $F : \varphi_1 \cong \varphi_2 : X \rightarrow X$  is homotopy from  $\varphi_1$  to  $\varphi_2$ , then  $R(\varphi_1, \psi_1) = R(\varphi_2, \psi_2)$ .*

*Proof.* Let  $x_0 \in X$ . Then  $\langle F, x_0 \rangle$  is a path from  $\varphi_1(x_0)$  to  $\varphi_2(x_0)$ . Thus the path  $\langle F, x_0 \rangle$  induces a homomorphism

$$\langle F, x_0 \rangle_* : \sigma(X, \varphi_1(x_0), G) \rightarrow \sigma(X, \varphi_2(x_0), G).$$

So we obtain the following induced commutative diagram

$$\begin{array}{ccc} \sigma(X, x_0, G) & \xrightarrow{(\varphi_1, \psi_1)_*} & \sigma(X, \varphi_1(x_0), G) \\ (\varphi_2, \psi_2)_* \searrow & & \nearrow \langle F^{-1}, x_0 \rangle_* \\ & & \sigma(X, \varphi_2(x_0), G) \end{array}$$

From Lemma 3.2 and Lemma 3.3, we have

$$\begin{aligned} R(\varphi_1, \psi_1) &= R_*(\lambda_*(\varphi_1, \psi_1)_*) \\ &= R_*(\lambda_* \langle F, x_0 \rangle_*^{-1} (\varphi_2, \psi_2)_*) \\ &= R_*((\langle F^{-1}, x_0 \rangle \lambda)_*(\varphi_2, \psi_2)_*) \\ &= R(\varphi_2, \psi_2). \end{aligned}$$

Hence we complete the proof of theorem.  $\square$   $\square$

Let  $\sigma(X, x_0, G)'$  be a commutator subgroup of  $\sigma(X, x_0, G)$  generated by the set

$$\{[\alpha; g_1][\beta; g_2][\alpha; g_1]^{-1}[\beta; g_2]^{-1} \mid [\alpha; g_1][\beta; g_2] \in \sigma(X, x_0, G)\}.$$

For a convenient notation, we shall write  $\bar{\sigma}(X, x_0, G)$  for the quotient group  $\sigma(X, x_0, G)/\sigma(X, x_0, G)'$ .

**THEOREM 3.5.** *If  $(\varphi, \psi) : (X, G) \rightarrow (X, G)$  is a self-map, then*

$$R(\varphi, \psi) \geq \# \text{Coker}(1 - (\varphi, \psi))_{\bar{\sigma}} \geq 1,$$

where  $1$  and  $(\varphi, \psi)_{\bar{\sigma}}$  denote respectively the identity isomorphism and the endomorphism of  $\bar{\sigma}(X, x_0, G)$  induced by  $(\varphi, \psi)$ .

*Proof.* Obviously, there exists a canonical homomorphism

$$\theta_{\sigma} : \sigma(X, x_0, G) \rightarrow \bar{\sigma}(X, x_0, G)$$

such that  $\text{Ker}\theta_{\sigma} = \sigma(X, x_0, G)'$ . Hence the following diagram is commutative:

$$\begin{array}{ccc} \sigma(X, x_0, G) & \xrightarrow{(\varphi, \psi)_{\sigma}} & \sigma(X, x_0, G) \\ \downarrow \theta_{\sigma} & & \downarrow \theta_{\sigma} \\ \bar{\sigma}(X, x_0, G) & \xrightarrow{(\varphi, \psi)_{\bar{\sigma}}} & \bar{\sigma}(X, x_0, G) \end{array}$$

For  $[\gamma; g] \in \sigma(X, x_0, G)$ , any element of the  $(\varphi, \psi)_{\sigma}$ -equivalent class containing  $[\beta; g_2]$  may be expressed in the form

$$[\alpha; g_1] = [\gamma; g][\beta; g_2](\varphi, \psi)_{\sigma}([\gamma; g]^{-1}).$$

From the above diagram, we can easily obtain

$$\begin{aligned} \theta_{\sigma}([\alpha; g_1]) &= \theta_{\sigma}([\gamma; g][\beta; g_2](\varphi, \psi)_{\sigma}([\gamma; g]^{-1})) \\ &= \theta_{\sigma}([\gamma; g]) + \theta_{\sigma}([\beta; g_2]) - \theta_{\sigma}(\varphi, \psi)_{\sigma}([\gamma; g]) \\ &= \theta_{\sigma}([\gamma; g]) + \theta_{\sigma}([\beta; g_2]) - (\varphi, \psi)_{\bar{\sigma}}\theta_{\sigma}([\gamma; g]) \\ &= \theta_{\sigma}([\beta; g_2]) + (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])). \end{aligned}$$

Thus there exists an element  $[\gamma; g] \in \sigma(X, x_0, G)$  such that

$$\begin{aligned} \theta_{\sigma}([\alpha; g_1]) - \theta_{\sigma}([\beta; g_2]) &= \\ (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])) &\in (1 - (\varphi, \psi)_{\bar{\sigma}})(\bar{\sigma}(X, x_0, G)). \end{aligned}$$

Let  $\eta_{\bar{\sigma}} : \bar{\sigma}(X, x_0, G) \rightarrow \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}})$  be the natural projection. Now consider

$$\sigma(X, x_0, G) \xrightarrow{\theta_{\sigma}} \bar{\sigma}(X, x_0, G) \xrightarrow{\eta_{\bar{\sigma}}} \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}}).$$

Since both  $\theta_{\sigma}$  and  $\eta_{\bar{\sigma}}$  are epimorphisms,  $\eta_{\bar{\sigma}}\theta_{\sigma}$  is also an epimorphism. Moreover, the  $\eta_{\bar{\sigma}}\theta_{\sigma}$  images of all element of a  $(\varphi, \psi)_{\sigma}$ -equivalent class are the same element of  $\text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}})$ . This completes the proof of theorem.  $\square$   $\square$

**COROLLARY 3.6.** *Let  $(\varphi, \psi) : (X, G) \rightarrow (X, G)$  be a self-map. If  $\sigma(X, x_0, G)$  is abelian and  $G$  is abelian, then*

$$R(\varphi, \psi) = \# \text{Coker}(1 - (\varphi, \psi)_{\bar{\sigma}}).$$

*Proof.* If  $\sigma(X, x_0, G)$  is abelian, then the natural homomorphism  $\theta_{\sigma} : \sigma(X, x_0, G) \rightarrow \bar{\sigma}(X, x_0, G)$  is an isomorphism. From Definition 3.1,  $[\alpha; g_1] \sim [\beta; g_2]$  if and only if there exists  $[\gamma; g] \in \sigma(X, x_0, G)$  such that

$$\theta_{\sigma}([\alpha; g_1] - \theta_{\sigma}([\beta; g_2])) = (1 - (\varphi, \psi)_{\bar{\sigma}})(\theta_{\sigma}([\gamma; g])),$$

In other words,

$$\eta_{\bar{\sigma}}\theta_{\sigma}([\alpha; g_1]) - \eta_{\bar{\sigma}}\theta_{\sigma}([\beta; g_2]) = 0.$$

This completes the proof of theorem. □ □

## References

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