

THE FIXED POINT INDEX FOR ACCRETIVE MAPPINGS WITH k -SET CONTRACTION PERTURBATIONS IN CONES

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1. Introduction

The fixed point index plays an important role in solving the positive solutions of nonlinear equations in ordered Banach spaces ([7], [10], [11], [14], [15]). Many authors have studied the existence problems of positive solutions of nonlinear equations for nonlinear mappings ([1]-[5], [7], [9], [10], [14], [15]).

Let E be a Banach space and P be a closed cone in E , i.e., P is a closed convex set in E and

$$\lambda P \subset P \text{ for all } \lambda \geq 0 \text{ and } P \cap (-P) = \{0\}.$$

Let Ω be a nonempty open bounded subset of E . Let $A : D(A) \subset P \rightarrow 2^P$ be a multivalued accretive mapping, i.e., for all $x, y \in D(A)$, $a_1 \in Ax$ and $a_2 \in Ay$,

$$\|x - y\| \leq \|x - y + \lambda(a_1 - a_2)\|,$$

and let $K : \Omega \cap P \rightarrow P$ be a strict k -set contraction for $0 \leq k < 1$ ([12], [14]).

In this paper, we prove that if $(I+A)(D(A)) = P$ and $x \notin -Ax + Kx$ for all $x \in \partial\Omega \cap D(A)$, then the fixed point index is defined for a mapping $-A + K$ and $-A + K$ has a fixed point in $\Omega \cap D(A)$.

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2. Main Results

Let E be a Banach space, P be a closed cone in E and “ \leq ” be the order induced by P in E , i.e., $x \leq y$ if and only if $y - x \in P$.

PROPOSITION 1. *If $A : D(A) = P \rightarrow P$ is a continuous accretive mapping and for each $x \in P$, there exists $\beta(x) > 0$ such that $Ax \leq \beta(x) \cdot x$, then $(\lambda I + A)(P) = P$ for all $\lambda > 0$.*

Proof. For each $z \in P$, consider the following differential equation

$$(2.1) \quad \begin{cases} x'(t) &= -(\lambda I + A)x(t) + z, & t \in [0, +\infty), \\ x(0) &= u \in P. \end{cases}$$

For each $x \in P$, since $Ax \leq \beta(x) \cdot x$, there exists $W(x) \in P$ such that $\beta(x) \cdot x = Ax + W(x)$.

Thus we have

$$x + \epsilon(-\lambda x - Ax + z) = (1 - \epsilon\lambda - \epsilon\beta(x))x + \epsilon W(x) + \epsilon z$$

and so for sufficiently small $\epsilon > 0$ such that $1 - \epsilon\lambda - \epsilon\beta(x) > 0$, we have

$$(1 - \epsilon\lambda - \epsilon\beta(x))x + \epsilon W(x) + \epsilon z \in P.$$

Hence it follows that for all $x \in P$

$$\lim_{\epsilon \rightarrow 0^+} \frac{1}{\epsilon} \rho(x + \epsilon(-\lambda x - Ax + z), P) = 0$$

and, by Deimling [6], we know that (2.1) has only one solution in P . Let $x(t, u)$ be the unique solution of (2.1) with $x(0) = u$.

Now, we define a mapping $B_T : P \rightarrow P$ by

$$B_T u = x(T, u) \quad \text{for all } u \in P \text{ and a constant } T > 0.$$

For all $u, v \in P$, let $\phi(t) = \|x(t, u) - x(t, v)\|$. Then we have

$$\phi(t)D^-\phi(t) \leq (x'(t, u) - x'(t, v), x(t, u) - x(t, v))_-,$$

where $D^- \phi(t) = \limsup_{h \rightarrow 0^+} \frac{\phi(t) - \phi(t-h)}{h}$ and $(\cdot, \cdot)_-$ is the semi-inner product ([6]) and so

$$\begin{aligned} & \phi(t)D^- \phi(t) \\ & \leq (-\lambda x(t, u) - Ax(t, u) + \lambda x(t, v) + Ax(t, v), x(t, u) - x(t, v))_- \end{aligned}$$

Since A is accretive, we have

$$\begin{aligned} & (-Ax(t, u) + Ax(t, v), x(t, v) - x(t, v))_- \\ & = -(Ax(t, u) - Ax(t, v), x(t, u) - x(t, v))_+ \\ & \leq 0. \end{aligned}$$

Therefore, we have

$$\phi(t)D^- \phi(t) \leq -\lambda \phi^2(t) \quad \text{and} \quad \phi(t) \leq e^{-\lambda T} \phi(0)$$

and so $\|B_T u - B_T v\| \leq e^{-\lambda T} \|u - v\|$. Hence, B_T has a unique fixed point $u_0 \in P$, i.e., $B_T u_0 = u_0$. This implies that $x'(t, u_0) = 0$ for all $t > 0$. Therefore, we have $0 = -\lambda u_0 - Au_0 + z$ and so $z \in (A + \lambda I)(P)$. This completes the proof. \square

Next, we assume that $A : D(A) \subset P \rightarrow 2^P$ is a multivalued accretive mapping and $(A + I)(D(A)) = P$. Then it is well-known that $(I + A)^{-1}$ is nonexpansive ([4]).

Let Ω be an open bounded subset of E and $K : \overline{\Omega} \cap P \rightarrow P$ be a strict k -set contraction for $k \in [0, 1)$. Suppose that $D(A) \cap \overline{\Omega} \neq \emptyset$ and $x \notin -Ax + Kx$ for all $x \in \partial\Omega \cap D(A)$. Then $x \neq (I + A)^{-1}Kx$ for all $x \in \partial\Omega \cap P$ and $(I + A)^{-1}K$ is also a strict k -set contraction. Therefore, the fixed point index $i((I + A)^{-1}K, \Omega \cap P)$ is well defined ([1], [10]). Now, we define

$$i(-A + K, \Omega \cap D(A)) = i((I + A)^{-1}K, \Omega \cap P).$$

Then we have the following:

THEOREM 2. (1) *If $\Omega = B(0, r)$ and $Kx = x_0 \in B(0, r) \cap P$ for all $x \in \overline{B(0, r)} \cap P$, then*

$$i(-A + K, B(0, r) \cap D(A)) = 1.$$

(2) If $\Omega = \Omega_1 \cup \Omega_2$ and $\Omega_1 \cap \Omega_2 = \emptyset$, then

$$i(-A + K, \Omega \cap D(A)) = i(-A + K, \Omega_1 \cap D(A)) + i(-A + K, \Omega_2 \cap D(A)).$$

(3) Let $H(t, x) : [0, 1] \times (\overline{\Omega} \cap P) \rightarrow P$ be uniformly continuous in x for each $t \in [0, 1]$ and $H(t, \cdot) : \Omega \cap P \rightarrow P$ be a strick k -set contraction, where k does not depend on t . If, for all $t \in [0, 1]$,

$$x \notin -Ax + H(t, x) \text{ for all } x \in \partial\Omega \cap D(A),$$

then $i(-A + H(t, x), \Omega \cap D(A))$ does not depend on t .

(4) If $i(-A + K, \Omega \cap D(A)) \neq 0$, then $x \in -Ax + Kx$ has a solution in $\Omega \cap D(A)$, i.e., $-A + K$ has a fixed point in $\Omega \cap D(A)$.

Proof. (2), (3) and (4) are obvious ([1], [10]).

Now, we prove (1). First, we have

$$(2.2) \quad 0 \in D(A) \text{ and } 0 \in A0$$

In fact, since $(A + I)(D(A)) = P$, there exist $x \in D(A)$ and $a \in Ax$ such that $x + a = 0$. Since $x \geq 0$ and $a \geq 0$, we have $x = 0$ and $a = 0 \in A0$. Hence we have

$$(2.3) \quad (A + I)^{-1}0 = 0.$$

Next, we prove that

$$(2.4) \quad i((I + A)^{-1}K, \Omega \cap P) = 1, \quad \Omega = B(0, r).$$

Since $(I + A)^{-1}Kx = (I + A)^{-1}x_0$ for all $x \in \overline{\Omega} \cap P$ and

$$\|(I + A)^{-1}x_0 - (I + A)^{-1}0\| \leq \|x_0\| < r,$$

it follows that $(I + A)^{-1}x_0 \in \Omega \cap P = B(0, r) \cap P$ and, by Amman [1] and Li [10],

$$i((I + A)^{-1}K, B(0, r) \cap P) = 1.$$

Therefore, $i(-A + K, B(0, r) \cap D(A)) = 1$. This completes the proof. \square

LEMMA 3. If $Kx \not\geq x$ for all $x \in \partial\Omega \cap P$ and $0 \in \Omega$, then

$$i(-A + K, \Omega \cap D(A)) = 1.$$

Proof. Let $H(t, x) = tKx$ for all $t \in [0, 1]$ and $x \in \bar{\Omega} \cap P$. If $x \in -Ax + tKx$ for some $x \in \partial\Omega \cap D(A)$ and $t \in [0, 1]$, then $t \neq 0$ (otherwise, we have $x = 0 \in \partial\Omega$, which is a contradiction). Thus we have $Kx \geq x/t \geq x$, which contradicts $Kx \not\geq x$. Hence, $H(t, x)$ satisfy all the conditions of (3) in Theorem 2 and so

$$i(-A + K, \Omega \cap D(A)) = i(-A + 0, \Omega \cap D(A)).$$

By (2.3), we have $(I+A)^{-1}0 = 0 \in \Omega \cap P$ and so $i((I+A)^{-1}0, \Omega \cap P) = 1$ and

$$(2.5) \quad i(-A + 0, \Omega \cap D(A)) = 1.$$

Therefore, we have

$$i(-A + K, \Omega \cap D(A)) = 1.$$

This completes the proof. □

COROLLARY 4. If $0 \in \Omega$ and $Kx < x$ for all $x \in \partial\Omega \cap P$, then $-A + K$ has a fixed point in $\Omega \cap D(A)$.

Proof. By hypothesis, it is obvious to prove that $Kx \not\geq x$ for all $x \in \partial\Omega \cap P$. By Lemma 3,

$$i(-A + K, \Omega \cap D(A)) = 1.$$

Therefore, by (4) of Theorem 2, $-A + K$ has a fixed point in $\Omega \cap D(A)$. □

LEMMA 5. Suppose that $u_0 \neq 0$ for $u_0 \in P$ and $x - tu_0 \notin -A(x - tu_0) + Kx$. If $x \in \partial\Omega \cap P$ and $x - tu_0 \in D(A)$ for $t \geq 0$, then

$$i(-A + K, \Omega \cap D(A)) = 0.$$

Proof. Suppose that $i((I + A)^{-1}K, \Omega \cap D(A)) \neq 0$ and for each $\tau > 0$, let $H(t, x) = (I + A)^{-1}K + t\tau u_0$ for all $x \in \Omega \cap P$ and $t \in [0, 1]$.

It is obvious that $H(t, x)$ is uniformly continuous in x for each t and $H(t, \cdot)$ is a strict k -set contraction for each t . By Amman [1] and Li [8], we have

$$i((I + A)^{-1}K + \tau u_0, \Omega \cap P) = i((I + A)^{-1}K, \Omega \cap P) \neq 0.$$

Thus there exists $x_\tau \in \Omega \cap P$ such that

$$(2.6) \quad x_\tau - (I + A)^{-1}Kx_\tau = \tau u_0.$$

Letting $\tau \rightarrow \infty$, the left side of (2.6) is bounded, but the right side of (2.6) is unbounded, which is a contradiction. Therefore, we have

$$i(-A + K, \Omega \cap D(A)) = 0.$$

This completes the proof. □

THEOREM 6. *Let $A : D(A) \subset P \rightarrow 2^P$ be a multivalued accretive mapping such that $(I + A)(D(A)) = P$ and let Ω_1, Ω_2 be two open bounded subsets of E with $0 \in \Omega_1 \subset \Omega_2$. Suppose that if $K : \overline{\Omega}_2 \cap P \rightarrow$ is a strict k -set contraction mapping and $0 \neq u_0 \in P$, then*

(i) *for each $x \in \partial\Omega_2$, $x \notin Kx$ and for each $x \in \partial\Omega_1 \cap P$ and $t \geq 0$,*

$$x - tu_0 \in D(A) \quad \text{and} \quad x - tu_0 \notin -A(x - tu_0) + Kx$$

or

(ii) *for each $x \in \partial\Omega_1$, $x \notin Kx$ and for each $x \in \partial\Omega_2 \cap P$ and $t \geq 0$,*

$$x - tu_0 \in D(A) \quad \text{and} \quad x - tu_0 \notin -A(x - tu_0) + Kx.$$

If either (i) or (ii) is satisfied, then $-A + K$ has a fixed point in $(\Omega_2 - \overline{\Omega}_1) \cap D(A)$.

Proof. Suppose that the condition (i) is satisfied. By Lemma 3 and Lemma 5, we have

$$(2.7) \quad i(-A + K, \Omega_2 \cap D(A)) = 1$$

and

$$(2.8) \quad i(-A + K, \Omega_1 \cap D(A)) = 0,$$

respectively. Thus, from (2) of Theorem 2, (2.7) and (2.8), it follows that

$$i(-A + K, (\Omega_2 - \overline{\Omega}_1) \cap D(A)) = 1.$$

Therefore, by (4) of Theorem 2, $-A + K$ has a fixed point in $(\Omega_2 - \overline{\Omega}_1) \cap D(A)$.

If (ii) is satisfied, the proof is similar to the case (i). This completes the proof. \square

THEOREM 7. *If, for each $x \in \partial\Omega \cap D(A)$, $\|Kx\| \leq \|x\|$ and $0 \in \Omega$, then $-A + K$ has a fixed point in $\overline{\Omega} \cap D(A)$.*

Proof. we may assume that

$$(2.9) \quad x \notin -Ax + Kx \text{ for all } x \in \partial\Omega \cap D(A).$$

Let $H(t, x) = tKx$ for all $x \in \partial\Omega \cap P$ and $t \in [0, 1]$. It is obvious that $H(t, x)$ is uniformly continuous in x for each $t \in [0, 1]$ and $H(t, \cdot)$ is a strict k -set contraction for each t . We show that

$$(2.10) \quad x \notin -Ax + H(t, x) \text{ for all } x \in \partial\Omega \cap D(A) \text{ and } t \in [0, 1].$$

If $x \in -Ax + H(t, x)$ for some $x \in \partial\Omega \cap D(A)$ and $t \in [0, 1]$, then $x = (I + A)^{-1}H(t, x)$. Since $(I + A)^{-1}$ is nonexpansive and $(I + A)^{-1}0 = 0$, we have

$$\|x\| \leq \|H(t, x)\| = \|tKx\| \leq t\|x\|.$$

Therefore, we have $t = 1$, which contradicts (2.8). Thus, by (3) of Theorem 2,

$$i(-A + K, \overline{\Omega} \cap D(A)) = i(-A + 0, \overline{\Omega} \cap D(A))$$

and so (2.5) implies $i(-A + K, \overline{\Omega} \cap D(A)) = 1$. Therefore, by (4) of Theorem 2, $-A + K$ has a fixed point in $\overline{\Omega} \cap D(A)$. This completes the proof. \square

THEOREM 8. *If $0 \in \Omega$ and $\|Kx\| \leq \|x + a\|$ for all $x \in \partial\Omega \cap D(A)$ and $a \in Ax$, then $-A + K$ has a fixed point in $\overline{\Omega} \cap D(A)$.*

Proof. We may assume that $x \notin -Ax + Kx$ for all $x \in \partial\Omega \cap D(A)$. Let $H(t, x) = tKx$ for all $t \in [0, 1]$ and $x \in \overline{\Omega} \cap P$. If $x \in -Ax + tKx$ for some $x \in \partial\Omega \cap D(A)$ and $t \in [0, 1]$, then $tKx \in x + Ax$. Thus there exists $a \in Ax$ such that $tKx = x + a$ and so we have $\|Kx\| \leq t\|Kx\|$. By the assumption, since $t \neq 1$, we have $Kx = 0$ and so $x + a = 0$. Therefore, by (2.3), we have $x = 0 \in \partial\Omega$, which contradicts $0 \in \Omega$. Thus we have $x \notin -Ax + H(t, x)$ for all $x \in \partial\Omega \cap D(A)$ and $t \in [0, 1]$. The rest of the proof is similar to that of Theorem 7. This completes the proof. \square

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