

A GLOBAL STUDY ON SUBMANIFOLDS OF CODIMENSION 2 IN A SPHERE

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ABSTRACT. M be an $n(\geq 3)$ -dimensional compact connected and oriented Riemannian manifold isometrically immersed on an $(n+2)$ -dimensional sphere $S^{n+2}(c)$. If all sectional curvatures of M are not less than a positive constant c , show that M is a real homology sphere.

0. Introduction

Let M be an n -dimensional compact connected and oriented Riemannian manifold isometrically immersed in an $(n+2)$ -dimensional Euclidean space R^{n+2} . As is well known, if M is of positive curvature, then M is a homotopy sphere [4]. This result is generalized by Baldin and Mercuri [2], Baik and Shin [1] in the case of non-negative curvature, which is stated as follows : if M is of non-negative curvature, then M is either a homotopy sphere or diffeomorphic to a product of two spheres. In particular, if there is a point at which of positive curvature, then M is a homeomorphic to a sphere. This is a kind of reports which is devoted to study on a submanifolds of codimension 2 in a sphere $S^{n+2}(c)$. In the last section we prove the following :

Theorem 0.1. *Let M be an $n(\geq 3)$ -dimensional compact connected and oriented Riemannian manifold isometrically immersed on an $(n+2)$ -dimensional sphere $S^{n+2}(c)$. If all sectional curvatures of M are not less than a positive constant c , then M is a real homology sphere.*

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1. Associative curvature forms

Let V and W be real vector spaces of finite dimension n and p respectively, and B be a symmetric bilinear map of $V \times V$ into W . Suppose that $n > 2$ and W has an inner product \langle, \rangle . Define the associative curvature form $R_B : \wedge^2 V \times \wedge^2 V \rightarrow R$ by

$$R_B(x \wedge y, z \wedge w) = \langle B(x, z), B(y, w) \rangle - \langle B(x, w), B(y, z) \rangle. \quad (1.1)$$

for any vectors x, y, z and w in V . The map R_B is again symmetric and hence the eigenvalues of R_B is all real. R_B is said to be positive definite or positive semi-definite according as all eigenvalues of R_B are positive or non-negative, respectively. Next, we define the associative sectional curvature form K_B by

$$K_B(x, y) = R_B(x \wedge y, x \wedge y) \quad (1.2)$$

whenever $x \wedge y \neq 0$. The map K_B is said to be positive definite or positive semi-definite according as $K_B(x, y)$ is positive or non-negative for linearly independent vectors x and y in V , respectively.

Consider the following conditions for the bilinear map B :

- (1) There exists an orthonormal basis $\{\xi_{n+1}, \dots, \xi_{n+p}\}$ of W in such a way that the real valued function $H_a(x, y)$ on $V \times V$ defined by $H_a(x, y) = \langle B(x, y), \xi_a \rangle$ is non-negative for any indices $a = n+1, \dots, n+p$.
- (2) R_B is positive semi-definite.
- (3) K_B is positive semi-definite.

Lemma 1.1. (1) \rightarrow (2) \rightarrow (3) In particular, if $p = 2$, the conditions are all equivalent.

Proof. we prove the assertion (1) \rightarrow (2). Suppose the condition (1) holds. By making use of the function H_B for an orthonormal basis $\{\xi_a\}$ an image of B is given by $B(x, y) = \sum_a H_a(x, y)\xi_a$. Then we get

$$R_B(x \wedge y, z \wedge w) = \sum_a (H_a(x, z)H_a(y, w) - H_a(x, w)H_a(y, z)) \quad (1.3)$$

and we have $R = \sum_a R_a$. In order to prove that R_B is positive semi-definite, it suffices to show that all the map R_a are positive semi-definite. For a fixed index

a , let $\{e_1, \dots, e_n\}$ be an orthonormal basis for V which diagonalizes the function H_a , namely, $H_a(e_i, e_j) = \lambda_i \delta_{ij}$. Here and in the sequel, indices i and j run over the range $\{1, \dots, n\}$ and an index a run over the range $\{n + 1, \dots, n + p\}$, unless otherwise stated $\lambda_i > 0$ for all indices i , because H_a is positive semi-definite. Since the inner product \langle, \rangle of $\wedge^2 V$ is by definition

$$\langle x \wedge y, z \wedge w \rangle = \langle x, z \rangle \langle y, w \rangle - \langle x, w \rangle \langle y, z \rangle,$$

then the function (1,3) of the function R_a implies

$$R_a(e_i \wedge e_j, e_k \wedge e_l) = \lambda_i \lambda_j \langle e_i \wedge e_j, e_k \wedge e_l \rangle.$$

It means that $\{e_i \wedge e_j : i < j\}$ forms an orthonormal basis for $\wedge^2 V$ which diagonalizes R_a with eigenvalues $\lambda_i \lambda_j (\geq 0)$. So R_a is positive semi-definite.

Next the assertion (2) \rightarrow (3) is trivial. In the case where $p = 2$, it only remains to prove that the condition (3) implies the condition (1).

Suppose that the map K_B is positive semi-definite. Then for all pair (x, y) of linearly independent vectors, we have

$$K_B(x, y) = \langle B(x, x), B(y, y) - \|B(x, y)\|^2 \rangle > 0, \tag{1.4}$$

where $\| \cdot \|$ means the norms for the vector space W . Now there might exist a non-asymptotic vector x in $V - \{0\}$. Suppose that any vector x in $V - \{0\}$ is asymptotic. Then $H_a(x, x)$ must be equal to zero, because of $H_a(x, x) = \langle B(x, x), \xi_a \rangle$ for any orthonormal basis $\{\xi_a\}$ for W . If this case can be regarded as the special one of positive semi-definiteness, then it is nothing but the condition (1). Choose an orientation for W , and for fixed vector x_0 and any vector x in $V - \{0\}$, let $\theta(x)$ denote an angle from $B(x_0, x_0)$ to $B(x, x)$. $\theta(x)$ is defined only module 2π but it follows from (1.4) that θ is continuous function of $V - \{0\}$ into the closed interval $[-\frac{\pi}{2}, \frac{\pi}{2}]$. For a unit sphere S of V centered with origin the restriction of θ to S is also continuous, so it must attain its maximum θ_1 and minimum θ_2 . Again, taking the inequality (1,4) into account, we get $\theta_1 - \theta_2 \leq \frac{\pi}{2}$.

Let $\bar{\theta} = (\theta_1 + \theta_2)/2$, $\bar{\theta}_1 = \bar{\theta} + \frac{\pi}{4}$ and $\bar{\theta}_2 = \bar{\theta} - \frac{\pi}{4}$, and $\xi(\theta)$ be a unit vector in W to which the direct angle from $B(x_0, x_0)$ is equal to θ . Then by putting $\xi_{n+1} = \xi(\bar{\theta}_1)$ and $\xi_{n+2} = \xi(\bar{\theta}_2)$, $\{\xi_{n+1}, \xi_{n+2}\}$ is an orthonormal basis for W , and by choosing the angle θ_1 and θ_2 it turns out that

$$\bar{\theta}_2 \leq \theta_2 \leq \theta(x) \leq \theta_1 \leq \bar{\theta}_1$$

for any vector x in S . This implies that the angle between $\xi(\theta(x))$ and $\xi_\alpha(\alpha = n + 1, n + 2)$ is less than or equal to $\frac{\pi}{2}$ for any x in S , and so is the angle between $B(x, x)$ and ξ_α , because of $B(x, x) = \|B(x, x)\|\xi(\theta(x))$.

Thus the forms H_α are both positive semi-definite. This concludes the proof.

2. Curvature operator

In this section, the concept of the curvature operator in a Riemannian manifold (M, g) will be introduced and the manifold structures of M which are influenced by some conditions of the operator are investigated.

For a point x in M , let R_x be an associated curvature operator. A linear map P^* of $\wedge^2 M_x$ into $\wedge^2 M_x^*$ for any point x in M is defined by $u \wedge v \rightarrow R(\cdots, u, v)$ and by this duality an endomorphism p_x of $\wedge^2 M_x^*$ into itself is manufactured. It turns out that p_x satisfies

$$\langle p_x(u^* \wedge v^*), w^* \wedge z^* \rangle = \langle p_x^*(u, v), w^* \wedge z^* \rangle = R_x(u, v, w, z) \tag{2.1}$$

for any vectors u, v, w and z in M_x , where μ^* denotes the dual form in M_x associated with the vector u . The operator p_x is called a curvature operator at x . Since p_x is the symmetric operator, each eigenvalue of it is real. If all eigenvalues of p_x are contained in the interval $[\lambda, \mu]$, then one says $\lambda \leq p_x \leq \mu$, and if for any point x on M this property is satisfied, then $p(M)$ is a set which consists of all curvature operators at all points in M .

Now, for an orthonormal basis $\{u_1, \cdots, u_n\}$ of M_x and its dual basis $\{w^1, \cdots, w^n\}$ for M_x^* relative to $\{u_1, \cdots, u_n\}$, the following equation is given :

$$\langle p_x(w^i \wedge w^j), w^i \wedge w^j \rangle = R(u_i, u_j, u_i, u_j) = g(R(u_i, u_j)u_i, u_j), \tag{2.2}$$

from which

$$\langle p_x(w^i \wedge w^j), w^i \wedge w^j \rangle = k(u_i, u_j), \tag{2.3}$$

where $k(u_i, u_j)$ means a sectional curvature of a plane section spanned by the orthonormal vectors u_i and u_j . It follows that $K(M) \geq 0$ if $p(M) \geq 0$. Under the pinching of the curvature operator $p(M)$, the curvature tensor R and the Ricci tensor S are also pinched as follows :

$$\begin{aligned} \lambda(\delta_{il}\delta_{jk} - \delta_{ik}\delta_{jl}) &\leq g(R(u_i, u_j)u_k, u_l) \leq \mu(\delta_{jl}\delta_{ik} - \delta_{ik}\delta_{jl})\lambda(n - 1)\delta_{ij} \\ &\leq S(u_i, u_j) \leq \mu(n - 1)\delta_{ij}. \end{aligned} \tag{2.4}$$

Thus, if $\lambda \leq p(M) \leq \mu$. Remark here that the converse is not necessarily true.

Now, it plays an important role to restrict with the manifold structures of M that the curvature operator $p(M)$ is pinched. This is first studied by Yano and Bochner [5]. Suppose that $\lambda \leq p(M) \leq \mu$. Given any p -form w in $\wedge^p M_x^*$, we put

$$\begin{aligned}
 F(w) &= \sum_{i,j} \sum_{i_2 \cdots i_p} S(i,j) w(j, i_2, \dots, i_p) \\
 &\quad - \frac{p-1}{2} \sum_{i,j,k,l} \sum_{i_3, \dots, i_p} R(i,j,k,l) w(i,j, i_3, \dots, i_p) \cdot w(k,l, i_3, \dots, i_p)
 \end{aligned}
 \tag{2.5}$$

then the function $F(w)$ can be bounded from below. Namely, it follows from (2.4) that $F(w) \geq \{(n-1)\lambda - (p-1)\mu\} \{w\}^2$.

This implies $F(w) > 0$ if $\lambda = \frac{\mu}{2}$ and $2p < n + 1$.

In order to generalize the theorem due to Yano and Bochner, the other expression of the function F will be considered by making use of the curvature operator since components of any p -form w in $\wedge^p M_x^*$ with respect to the orthonormal basis $\{u_1, \dots, u_n\}$ for M_x are given by $w(i_1, \dots, i_p)$, where $\{w^{i_1} \wedge \dots \wedge w^{i_p}\} (i_1, \dots, i_p \in \{1, 2, \dots, n\})$ is an orthonormal basis of $\wedge^p M_x^*$, the p -form w is expressed by

$$w = \sum_{i_1, \dots, i_p} w(i_1, \dots, i_p) w^{i_1} \wedge \dots \wedge w^{i_p}$$

For a p -form w at x we shall consider a family of exterior 2-forms $(i_1, \dots, i_p)^w$ corresponded to the p -form w , which is defined by

$$(i_1, \dots, i_p)^w = \sum_{k=i}^p \sum_{j_k=l}^n w(i_1, \dots, i_{k-1}, j_k, i_{k+1}, \dots, i_p) w^{j_k} \wedge w^{i_k}.
 \tag{2.6}$$

Moreover a family of scalars $(i_1, \dots, i_p)^{\theta(w)}$ associated with the form w is produced.

The scalar is also defined by

$$(i_1, \dots, i_p)^{\theta(w)} = \langle p_x(i_1, \dots, i_p)^w, (i_1, \dots, i_p)^w \rangle.
 \tag{2.7}$$

We have by (1.4)

$$F(w) = A(w) - \frac{p-1}{2} B(w),
 \tag{2.8}$$

where $A(w) = \sum_{i,j} \sum_{i_2, \dots, i_p} S(i,j) w(j, i_2, \dots, i_p) w(j, i_2, \dots, i_p)$,

$B(w) = \sum_{i,j,k,l} \sum_{i_3, \dots, i_p} R(i,j,k,l) w(i,j, i_3, \dots, i_p) w(k,l, i_3, \dots, i_p)$.

The following Lemma 2.1 and Lemma 2.2 are due to Meyer [3].

Lemma 2.1. $F(w) = \frac{1}{p} \sum_{i_1, \dots, i_p} (i_1, \dots, i_p)^{\theta(w)}$

Lemma 2.2. *If w is an exterior p -form on M which does not vanish at x for $i \leq p \leq n - 1$, then the associated 2-form is not equal to zero at x .*

By making use of Lemmas 2.1 and 2.2, the following property is verified.

Theorem 2.3. *Let M be an n -dimensional compact and oriented Riemannian manifold. If all curvature operators satisfy $p(M) > 0$, then M is a real homology sphere*

Proof. The hypothesis $p(M) > 0$ implies that for a point x all eigenvalues of the operator p_x are positive, by (2,7) any exterior p -form w satisfies the condition

$$(i_1, \dots, i_p)^{\theta(w)} \geq 0$$

for any indices i_1, \dots, i_p . It follows from Lemma 2.1 that $F(w) \geq 0$.

It implies that in the equation

$$(\Delta w, w) = \|\nabla w\|^2 + Q(w),$$

where $Q(w) = \int_M F(w) dV_M$, Δw is the Laplacian of w and ∇w is the covariant derivative of w , the second term $Q(w)$ of the right hand side is positive. If the p -form w is harmonic, then $\Delta w = 0$ and we obtain that $F(w)$ and Δw vanish everywhere on M . Thus the p -form is parallel. Since w is parallel, the norm $\|w\|$ vanishes everywhere on M . Therefore, by the Theorem due to Hodge the p -th homology group H^p satisfies

$$H^p(M, R) = 0, 0 < p < n$$

This completes the proof.

3. Proof of Theorem 0.1.

Let $S^{n+2}(c)$ be an $(n + 2)$ -dimensional sphere of constant curvature. Let i be an isometric immersion of an n -dimensional compact and oriented Riemannian manifold M into the sphere $S^{n+2}(c)$. For any point of M we shall denote $i(M)$ on $S^{n+2}(c)$ by the same symbol x , since there is no danger of confusion and moreover

the computation is local. Furthermore, a tangent vector u at x is identified with $d_{i_x}(u)$. Then the tangent space M_x at x is a subspace of the tangent space \bar{M}_x of ambient space $\bar{M} = S^{n+2}(c)$ at x .

Let N_x be the orthogonal complement of M_x in \bar{M}_x , which is called a normal space to M at x . Let H be the second fundamental form of the immersion i . For the triple (M_x, N_x, H_x) at each point x in M , (algebraic preliminaries which prepared) for section 1 can be applied.

Let R_B be the associated curvature form on M_x which is defined by (1,1) and K_B be the real valued map on $M_x \times M_x$ defined by (1,2). From (1,1) we have

$$R_B(u \wedge v, w \wedge z) = R(u, v, w, z) - (\langle u, w \rangle \langle v, z \rangle - \langle u, z \rangle \langle v, w \rangle), \quad (3.1)$$

where R denotes the Riemannian curvature tensor on M . Then we get

$$K_B(u, v) = (K(u, v) - c)(\|u\|^2\|v\|^2 - \langle u, v \rangle^2), \quad (3.2)$$

where $K(u, v)$ is the sectional curvature of plane spanned by linearly independent vectors u and v on M_x . By the assumption of the Theorem 0.1, it follows that $K_B \geq 0$ from (3,2). Thus, by the Lemma 1.1 the associated curvature from $R_B \geq 0$. Hence the curvature form p_x at x of M satisfies $p_x \geq c$, because of (2,1). Then we have $p(M) \geq c \geq 0$.

By the Theorem 2.1, M is a real homology sphere. This completes the proof.

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