

ON THE GENERAL VOLODIN SPACE

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ABSTRACT. We first generalize the Volodin space which Volodin constructed in order to define a new algebraic K -theory. We investigate the topological(homotopy) properties of the general Volodin space. We also provide a theorem which seems to be useful in pure homotopy theory. We prove that $V(\ast_{\alpha} G_{\alpha}, \{G_{\alpha}\})$ is simply connected.

1. Introduction

Let G be a group. For a collection $\{G_{\alpha}\}$ of subgroups of G , the general Volodin space $X(\{G_{\alpha}\})$ is defined to be $\bigcup_{\alpha} BG_{\alpha}$. It is called so in this paper because Volodin used this space in defining a new algebraic K -theory. Let $G = GL_n(R)$ for a ring R . For a partial ordering α on $\{1, \dots, n\}$ the subgroup of triangular matrices is defined by

$$T_n^{\alpha}(R) = \{M \in GL_n(R) \mid M_{ij} = \delta_{ij} \text{ unless } i \overset{\alpha}{<} j\}$$

In this case the Volodin space $X(\{T_n^{\alpha}(R)\}) = W(GL_n(R), \{T_n^{\alpha}(R)\})/G = \bigcup_{\alpha} BT_n^{\alpha}(R)$ is simply denoted by $X_n(R)$. The space $X(R) = \varinjlim X_n(R)$ is called the Volodin model for algebraic K -theory. The space $V(GL_n(R), \{T_n^{\sigma}(R)\})$ is used to define Volodin K -theory as follows (cf. [5], [6]) :

$$K_i^V(R) := \pi_{i-1}(\varinjlim_n V(GL_n(R), \{T_n^{\sigma}(R)\})) \quad (i \geq 3)$$

In the case of hermitian K -theory we also have the Volodin-type K -theory. In this paper we deal with some homotopy theoretic properties

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of the general Volodin space. In section 2 we review some definitions and facts about simplicial sets which are not easily collected in the existing literature. In section 3 we prove that the map $W(G, \{G_\alpha\}) \rightarrow V(G, \{G_\alpha\})$ is a homotopy equivalence. $W(G, \{G_\alpha\})$ and $V(G, \{G_\alpha\})$ have their own advantages depending on situations. In Theorem 3.5 we look closer into the space $V(G, \{G_\alpha\})$.

2. Preliminaries

DEFINITION 2.1. Let Δ be a category whose objects are $[n] = \{0, 1, \dots, n\}$, $n \geq 0$, and a morphism $[m] \rightarrow [n]$ is a nondecreasing function. Δ is called the simplicial category. A simplicial object is a contravariant functor from Δ to a category \mathcal{C} which is usually a category of sets, topological spaces, abelian groups or rings etc. We denote a simplicial object $X : \Delta^{op} \rightarrow \mathcal{C}$ by X_* . X_n denotes $X([n])$, which is called the set of n -simplices. $g^* : X_n \rightarrow X_m$ denotes $X(g : [m] \rightarrow [n])$. A simplicial map between two simplicial objects $f_* : X_* \rightarrow Y_*$ is a natural transformation from X_* to Y_* .

There is an alternative definition of simplicial object. A simplicial object is a collection of objects $\{X_n\}_{n \geq 0}$ together with functions $d_i : X_n \rightarrow X_{n-1}$ ($0 \leq i \leq n$) and $s_i : X_n \rightarrow X_{n+1}$ ($0 \leq i \leq n$) satisfying the following relations

$$\begin{aligned} d_i d_j &= d_j d_i && \text{if } i < j \\ s_i s_j &= s_j s_{i-1} && \text{if } i > j \\ d_i s_j &= \begin{cases} s_{j-1} d_i & \text{if } i < j \\ \text{identity} & \text{if } i = j, j+1 \\ s_j d_{i-1} & \text{if } i > j+1. \end{cases} \end{aligned}$$

We call d_i 's face maps and s_i 's degeneracy maps. A simplicial map $f : X_* \rightarrow Y_*$ is a collection of maps $f_n : X_n \rightarrow Y_n$ ($n \geq 0$) which commute with face and degeneracy maps. For a simplicial object X , a simplex $x \in X$ is called degenerate if $x = s_i(x')$ for some $x' \in X$ and i . Otherwise it is called nondegenerate. Let Gps be a category of groups. A simplicial group means a simplicial object $\Delta \rightarrow Gps$. Every simplicial object can be regarded as a topological space (actually a CW -complex) via its geometric realization.

DEFINITION 2.2. Let X_* be a simplicial object. Let Δ^n be the n -simplex. The geometric realization $|X_*|$ of X is defined to be the quotient of $\coprod_{n \geq 0} X_n \times \Delta^n$ by the following relations: Let $x \in X_n$ and $\lambda : [m] \rightarrow [n]$ in Δ . Then $(\lambda^*x, (t_0, \dots, t_m)) \approx (x, \lambda_*(t_0, \dots, t_m))$. We may think of $[m]$ as vertices of Δ^m , so $\lambda_* : \Delta^m \rightarrow \Delta^n$ is a linear extension of λ on barycentric coordinates. $|X_*|$ is clearly a CW -complex.

EXAMPLE 2.3. (Classifying space of a category) let \mathcal{C} be a small category. Then we can form a simplicial set $B_*\mathcal{C}$, which is called bar construction (or nerve) of \mathcal{C} : Let $B_0\mathcal{C} = \text{obj}(\mathcal{C})$. For $n \geq 1$, n -simplices $B_n\mathcal{C}$ is a set of all possible chains of morphisms of the form

$$A_0 \xrightarrow{\alpha_1} A_1 \xrightarrow{\alpha_2} \dots \xrightarrow{\alpha_n} A_n, \quad A_i \in \text{obj}\mathcal{C}, \alpha_j \in \text{mor}\mathcal{C}$$

The i -th face map d_i deletes the i -th object and composes maps if necessary. The i -th degeneracy map s_i replaces A_i by $A_i \xrightarrow{id} A_i$. The classifying space BC is defined by $BC = |B_*\mathcal{C}|$. BC may also be regarded as the space of commutative diagrams in \mathcal{C} . In particular, for a group G , we may regard G as a category with a single object $*$ and morphisms $* \xrightarrow{g} *$ for all $g \in G$. BG turns out to be the Eilenberg-MacLane space $K(G, 1)$.

For more details of simplicial set and classifying spaces, the readers refer to [2], [3] and [4].

DEFINITION 2.4. Let \mathcal{C} be a Top-like category, i.e., category of sets, simplicial sets or topological spaces etc. A monad is an endofunctor $F : \mathcal{C} \rightarrow \mathcal{C}$ together with natural transformations $\mu : FF \rightarrow F$ and $\eta : 1 \rightarrow F$ satisfying associativity and unicity ([2], p10). An object X in \mathcal{C} is called an F -algebra if there exists a map $ev : FX \rightarrow X$ compatible with μ and η . An F -functor is a functor G together with a natural transformation $\lambda : GF \rightarrow G$ compatible with μ and η . In particular, F itself is an F -functor together with $\mu : FF \rightarrow F$. Given an monad F , and F -algebra X and an F -functor G , the two-sided bar construction $B_*(G, F, X)$ is defined to be a simplicial object in \mathcal{C} whose n -simplices are GF^nX . The face maps are induced by $\eta : 1 \rightarrow F$. The

two-sided bar construction has the following property:

- i) $X \rightarrow B_*(F, F, X)$ and $B_*(F, F, X) \rightarrow X$
- ii) $GX \rightarrow B_*(G, F, FX)$ and $B_*(G, F, FX) \rightarrow X$

are inverse homotopy equivalences.

3. The Volodin space

In this section we introduce a simplicial set $W(G, \{G_\alpha\})$ and a simplicial complex $V(G, \{G_\alpha\})$ and show that they are homotopy equivalent. We introduce the Volodin space and state some important properties of the space. The Volodin space plays an important role in algebraic K -theory.

DEFINITION 3.1. Let G be a group and $\{G_\alpha\}$ be a family of its subgroups. Denote by $V(G, \{G_\alpha\})$ a simplicial complex whose vertices are elements of G and g_0, \dots, g_p ($g_i \neq g_j$) form a p -simplex if and only if all $g_i^{-1}g_j$ lie in the same G_k for some k . Denote by $W(G, \{G_\alpha\})$ the geometric realization of the simplicial set whose p -simplices are the sequences (g_0, \dots, g_p) of elements of G such that all $g_i^{-1}g_j$ lie in the same G_α and the face and degeneracy maps are omissions and repetitions, respectively. Note that $W(G, \{G_\alpha\}) \cong \bigcup_\alpha B(G, G_\alpha, *)$, where $B(G, G_\alpha, *)$ is the two-sided bar construction. The homeomorphism is given by

$$(g_0, \dots, g_p) \mapsto (g_0, g_0^{-1}g_1, g_1^{-1}g_2, \dots, g_{p-1}^{-1}g_p)$$

The general Volodin space $X(\{G_\alpha\})$ is defined by $\bigcup_\alpha BG_\alpha$ which equals

$$W(G, \{G_\alpha\})/G = \bigcup_\alpha B(*, \{G_\alpha\}, *).$$

The following theorem may be known to some experts in homotopy theory, but the authors provide the proof because it does not seem to be in the literature.

THEOREM 3.2. Let W be a CW-complex and V be a simplicial complex. Let $f : W \rightarrow V$ be a cellular map. Then if $f^{-1}(\Delta)$ is contractible for every closed simplex Δ in V , then f is a homotopy equivalence.

PROOF. Let V_i be the i -skeleton of V and let $W_i = f^{-1}(V_i)$. We first show by induction that for each n , for every finite subcomplex V_n^α of V_n , $f : W_n^\alpha = f^{-1}(V_n^\alpha) \rightarrow V_n^\alpha$ is a homotopy equivalence. For $n = 0$, $f : W_0^\alpha \rightarrow V_0^\alpha$ is clearly an equivalence for each finite subcomplex V_0^α of V_0 . We assume, by induction, that $f : W_i^\alpha = f^{-1}(V_i^\alpha) \rightarrow V_i^\alpha$ is an equivalence for every finite subcomplex V_i^α of V_i for $i \leq n-1$. Let $V_n^{\alpha_0}$ be an arbitrary finite subcomplex of V_n . Then $V_n^{\alpha_0} = (V_n^{\alpha_0})^{(n-1)} \cup (\text{finite } n\text{-simplices})$ is homotopy equivalent to $W_n^{\alpha_0}$ by the following argument: Let K_0 be any n -dimensional subcomplex of V_n such that $f : f^{-1}(K_0) \rightarrow K_0$ be an equivalence. Let $K' = K_0 \cup_{\partial \Delta^n} \Delta^n \subset V_n$. Then we can easily see that $f^{-1}(K') \rightarrow K'$ is also a homotopy equivalence from the following pushout squares (actually cofibration squares):

$$\begin{array}{ccccc} f^{-1}(\partial \Delta^n) & \longrightarrow & f^{-1}(\Delta^n) & & \partial \Delta^n & \longrightarrow & \Delta^n \\ \downarrow & & \downarrow & & \downarrow & & \downarrow \\ f^{-1}(K_0) & \longrightarrow & f^{-1}(K') & & K_0 & \longrightarrow & K' \end{array}$$

$f^{-1}(\partial \Delta^n) \rightarrow \partial \Delta^n$ is an equivalence by induction hypothesis. $f^{-1}(\Delta^n) \rightarrow \Delta^n$ and $f^{-1}(K_0) \rightarrow K_0$ are also equivalences by our assumptions, so $f^{-1}(K') \rightarrow K'$ is an equivalence. (Actually we are thinking of a cube diagram). Hence every finite subcomplex V_n^α of V_n is homotopy equivalent to $W_n^\alpha = f^{-1}(V_n^\alpha)$. Now for each n we have

$$W_n = \varinjlim_{\alpha} W_n^\alpha \rightarrow \varinjlim_{\alpha} V_n^\alpha = V_n \text{ is a homotopy equivalence.}$$

Moreover, we have

$$W = \varinjlim W_n \rightarrow \varinjlim V_n = V \text{ is also a homotopy equivalence.} \quad \square$$

Theorem 3.2 seems to have some applications in homotopy theory and simplicial topology. We here have an immediate application.

LEMMA 3.3. *The obvious map $f : W(G, \{G_k\}) \rightarrow V(G, \{G_k\})$ is a homotopy equivalence.*

PROOF. It suffices to show that $f^{-1}(\Delta^n)$ is contractible for each simplex $\Delta^n = (g_0, g_1, \dots, g_n)$ in $V(G, \{G_k\})$. It is easy to see that $f^{-1}(\Delta^n)$ can be regarded as a simplicial set whose p -simplices are all sequences (h_0, \dots, h_p) of elements of the set $\{g_0, g_1, \dots, g_n\}$. $f^{-1}(\Delta^n)$ is contractible by the following general fact: For a nonempty set X the simplicial set whose p -simplices are all sequences (x_0, \dots, x_p) of elements of X (with the same face and degeneracy maps as above) is contractible. \square

Both $W(G, \{G_\alpha\})$ and $V(G, \{G_\alpha\})$ have their own advantages depending on the homotopy theoretic situations. $V(G, \{G_\alpha\})$ is more naive and sometimes more transparent. $W(G, \{G_\alpha\})$, on the other hand, is often easier to work with in dealing with abstract homotopy theory or homology theory.

We now have some interesting properties of these spaces.

Let G be a group and $\{G_\alpha\}$ be a collection of subgroups of G . Then from Seifert van-Kampen theorem we get the following

LEMMA 3.4. $\pi_1 X(\{G_\alpha\})$ is isomorphic to the amalgamated free product $\ast_\alpha G_\alpha$ if the collection $\{G_\alpha\}$ is closed under finite intersection.

We have some more properties of $V(G, \{G_\alpha\})$.

THEOREM 3.5. Let H be a subgroup of G generated by $\{G_\alpha\}$. Let $T = \ast_\alpha G_\alpha$. Then we have

- (a) $V(H, \{G_\alpha\})$ is a connected component of $V(G, \{G_\alpha\})$.
- (b) $V(T, \{G_\alpha\})$ is a universal covering of both $X(\{G_\alpha\})$ and $V(H, \{G_\alpha\})$.

PROOF. (a) Since every element of H is expressed as a finite product of elements in some G_α 's, every vertex in $V(H, \{G_\alpha\})$ is joined with 1 by a path. On the other hand if $g \notin H$, then g cannot be joined with 1 by a path.

(b) It suffices to show that $V(T, \{G_\alpha\})$ is simply connected. Let w be a loop at 1 in $V(T, \{G_\alpha\})$. Then w is homotopic to a loop that consists of 1-simplices. So up to homotopy every path in $V(T, \{G_\alpha\})$ can be

identified with a finite product of elements g_α 's, where g_α is contained in some G_α . Since w is a loop at 1, w is realized as $\prod_{finite} g_\alpha = 1$, $g_\alpha \in G_\alpha$.

The group T is a free group modulo some relations. Through finite steps of reduction using these relations, $\prod g_\alpha$ reduces to 1. Each reduction happens in some G_α , which means that it geometrically happens in a simplex. Hence in each reduction the homotopy type of the loop does not change. Thus this loop w is homotopic to a trivial loop. \square

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