J. Korean Math. Soc. 31 (1994), No. 1, pp. 11-28

MULTIPLE SOLUTIONS OF A CLASS OF SINGULAR PERTURBATION PROBLEMS WITH NEUMANN TYPE

Bongsoo Ko

1. Introduction

In this paper we discuss the existence of multiple nontrivial solutions and interior transition layers of those solutions of a class of semilinear elliptic singular perturbation problems with Neumann type:

$$\epsilon^2 \Delta u + f(x, u) = 0, \qquad x \in \Omega,$$

 $\frac{\partial u}{\partial n} = 0, \qquad x \in \partial \Omega,$ (I)

where $\frac{\partial u}{\partial n}$ denotes the outward normal derivative of u on $\partial\Omega$, and we assume that $\Omega \subset \mathbb{R}^n$ $(n \geq 1)$ is a smooth bounded open set, $\partial\Omega \in C^{2,\alpha}$ $(0 < \alpha < 1)$ and $\overline{\Omega} = \Omega \cup \partial\Omega$.

In section 2, we assume that $f: \overline{\Omega} \times R \to R$ satisfies the following:

- (1) $f \in C^1(\bar{\Omega} \times R)$
- (2) There exist exactly three functions $g_i : \overline{\Omega} \to R \ (i = 0, 1, 2)$ which belong to $C^2(\overline{\Omega})$, and

$$g_1(x) < g_0(x) < g_2(x)$$

and

$$f(x,g_i(x))=0$$

for all $x \in \overline{\Omega}$.

Received August 25, 1992.

This work was supported in part by Korea Science and Engineering Foundation under Grant 901-0103-014-1.

(3) There exists a positive constant K such that

$$f_u(x,g_i(x)) < -K$$

for all $x \in \overline{\Omega}$ and i = 1, 2.

(4) There exist two nonempty disjoint connected open subsets Ω_1 and Ω_2 of Ω such that for any point $x \in \partial \Omega_1$,

$$\int_{\gamma(x)}^{g_2(x)} f(x,u) \, du > 0$$

for all $\gamma(x) \in [g_1(x), g_2(x))$, and for any $x \in \partial \Omega_2$,

$$\int_{g_1(x)}^{\gamma(x)} f(x,u) \, du < 0$$

for all $\gamma(x) \in (g_1(x), g_2(x)]$. We also assume that $\partial \Omega_1$ and $\partial \Omega_2$ are smooth.

Constructing three pairs of quasisupersolutions and quasisubsolutions of the problem (I), we prove that there is ϵ_0 such that for any ϵ with $0 < \epsilon \leq \epsilon_0$ (I) has five distinct ordered solutions in $C^2(\bar{\Omega})$ between g_1 and g_2 and one of them has an interior transition layer as $\epsilon \to 0$.

In [1], the limit of global minimizers of functionals of the type

$$\frac{\epsilon^2}{2}\int_{\Omega}|\nabla u|^2\,dx+\int_{\Omega}F(|x|,u)\,dx\,,$$

as $\epsilon \to 0$, where $F(|x|, z) = \int_{r(|x|)} zf(|x|, u) du$, has been discussed previously in case the domain is an interval in \mathbb{R}^1 , or a ball, or an annulus in \mathbb{R}^n by the variational method.

We also discuss interior transition layers of solutions in the case of f(x, u) = u(u - a(x))(1 - u) and we show that several types of interior transition layers of solutions are dependent on the shape of the graph of the function a(x).

In the section 3, we discuss the existence of multiple solutions of (I)in the case of f(x, u) = g(x)h(u) for sufficiently small $\epsilon > 0$. In the problem we assume that h has at least three zeros $z_1 < z_2 < z_3$ and $h'(z_1) < 0$, $h'(z_2) > 0$, and $h'(z_3) < 0$, and the function g takes both positive values and negative values on the domain Ω . Constructing two pairs of quasisupersolutions and quasisubsolutions of (I), we show that there is ϵ_0 such that for any ϵ with $0 < \epsilon \le \epsilon_0$ the problem (I)has at least two distinct nontrivial solutions which lie between z_1 and z_3 and which have interior transition layers as $\epsilon \to 0$. We also prove that the existence of a nontrivial solution having the interior transition layer even though h has only two zeros.

In [2], in the case of f(x, u) = g(x)h(u) = g(x)u(1-u)[k(1-u)+(1-k)u], 0 < k < 1, and with condition $\int_{\Omega} g(x) dx < 0$ or $\int_{\Omega} g(x) dx > 0$, they proved by the bifurcation method that the existence of a nontrivial positive solution of (I) between 0 and 1.

Without the integral conditions for the function g, we prove that for all sufficiently small $\epsilon > 0$ the problem (I) has two nontrivial positive solutions and interior transition layers for the solutions according to the value of k if $k \neq 0$, $k \neq \frac{1}{2}$, and $k \neq 1$. We also prove that if k = 0, or $k = \frac{1}{2}$, or k = 1, then the problem (I) has at least one nontrivial positive solution having an interior transition layer as $\epsilon \to 0$.

2. Main Results

DEFINITIONS. A function $w : \overline{\Omega} \to R$ is a quasisupersolution (or quasisubsolution) of (I) if for any $x_0 \in \overline{\Omega}$, there exist a neighborhood N of x_0 and a finite number of functions $w_k \in C^2(N), k = 1, 2, \dots, p$ such that

$$w(x) = \min_{1 \le k \le p} w_k(x) \quad \left(\text{or} \quad \max_{1 \le k \le p} w_k(x) \right)$$

for all $x \in N$, where p may depend on x_0 , and

$$\epsilon^2 \Delta w_{k}(x) + f(x, w_{k}(x)) \le 0 \quad (\text{or} \ge 0)$$

for all $x \in N \cap \Omega$ and $k = 1, 2, \dots, p$. Furthermore, if $x_0 \in \partial \Omega$,

$$\frac{\partial w_k}{\partial n}(x) \ge 0 \quad (\text{or} \quad \le 0)$$

for all k.

Constructing three pairs of quasisubsolutions and quasisupersolutions of (I) and using Theorem 3 in [4], we prove the existence of five distinct ordered solutions of (I) and interior transition layers of those solutions as $\epsilon \to 0$.

Theorem 3 in [4] is as follows:

THEOREM 2.1 [4]. Suppose that \bar{w}_1, \bar{w}_2 are quasisubsolutions and \hat{w}_1, \hat{w}_2 are quasisupersolutions of elliptic problems of the type:

$$egin{aligned} \Delta u(x)+fig(x,u(x)ig)&=0,&x\inarOmega,\ \end{aligned}$$
 (II) $p(x)u(x)+q(x)rac{\partial u}{\partial n}&=arphi(x),\qquad x\in\partialarOmega \end{aligned}$

such that $\bar{w}_1(x) \leq \hat{w}_2(x)$ and $\bar{w}_j(x) \leq \hat{w}_j(x)$ for all $x \in \bar{\Omega}$ and j = 1, 2, and $\bar{w}_2(x_0) > \hat{w}_1(x_0)$ for some $x_0 \in \bar{\Omega}$. If \hat{w}_1 and \bar{w}_2 are not solutions of (II), then (II) has at least three distinct solutions u_j in $C^2(\bar{\Omega})$, (j = 0, 1, 2), such that

$$ar{w}_j(x) \leq u_j(x) \leq \hat{w}_j(x), \quad u_1(x) \leq u_0(x) \leq u_2(x)$$

for all $x \in \overline{\Omega}$ and j = 1, 2, and especially

$$u_0 \in [\bar{w}_1, \hat{w}_2] \setminus [\bar{w}_1, \hat{w}_1] \cup [\bar{w}_2, \hat{w}_2].$$

REMARK. In Theorem 2-1, the notation $[\bar{w}_i, \hat{w}_j] = \{ u \in C(\bar{\Omega}) : \bar{w}_i(x) \le u(x) \le \hat{w}_j(x), x \in \bar{\Omega} \}, i \le j.$

The function f satisfies that $f \in C^{\alpha}(\bar{\Omega} \times I)$ (Here $0 < \alpha < 1$, I is a fixed finite closed interval in R) and there is a positive number Msuch that $|f(x, u) - f(x, v)| \leq M|u - v|$ for all $x \in \bar{\Omega}$ and $u, v \in I$. φ and $\partial \Omega$ are smooth.

In order to construct a quasisubsolution and a quasisupersolution of (I), we use a coordinate transformation near the boundary $\partial \Omega_1$ and $\partial \Omega_2$. If $x \in \Omega_i$, (i = 1, 2) we denote by t = t(x) the distance from x to $\partial \Omega_i$ and by s = s(x) the point of $\partial \Omega_i$ which is closest to x. Of course s(x) might not be uniquely defined, but will be if x is close

enough to $\partial \Omega_i$. Let O_i be the open set of all points of Ω_i such that the normal through distinct points of $\partial \Omega_i$ do not intersect on O_i . We denote x = (s,t) if $x \in O_i$ and x = s = (s,0) if $x \in \partial \Omega_i$, and if $x \in O_i$, we have

$$\epsilon^2 \Delta_x = \epsilon^2 \frac{\partial^2}{\partial t^2} + 0(\epsilon).$$

by the substitution x = (s, t).

Now consider the following boundary value problem:

$$\begin{cases} \frac{\partial^2 u}{\partial \tau^2} &= F(s, u(s, \tau)) \\ u(s, 0) &= \xi(s), \quad u(s, \infty) = 0, \end{cases}$$

where $s \in \partial \Omega$ is a parameter and $\tau \in [0, \infty)$ and F(s, u) is a real valued function.

The following fact is well known.

LEMMA [3]. Let $\xi(s)$ and F(s, u) be infinitely differentiable for all $s \in \partial \Omega$ and $u \in (-\infty, +\infty)$, all derivatives being uniformly continuous. For all $s \in \partial \Omega$, assume that

$$F(s,0) = 0, \quad F_u(s,0) > 0, \quad \int_0^w F(s,u) \, du > 0$$

for all $w \in (0, \xi(s)]$ or $[\xi(s), 0)$. Then there is a unique monotone solution $v(s, \tau)$ of the above boundary value problem and it is infinitely differentiable in s and τ . Moreover each of the derivatives of v decays exponentially as $\tau \to \infty$, uniformly in s, in the sense that if D is any C^{∞} linear differential operator in s and τ , then there exist positive constants C and β , possibly depending on D, such that $|Dv(s, \tau)| \leq ce^{-\beta\tau}$.

Hence, we can say that

$$\epsilon^2 \Delta_x v(s,\tau) = \frac{\partial^2 v}{\partial \tau^2} + 0(\epsilon)$$

as $\epsilon \to 0$, uniformly on $s \in \partial \Omega$, if $v(s,\tau)$ is the unique monotone solution of the above boundary value problem.

Using Lemma, we have the following theorem which yields the existence of a pair of quasisubsolution and quasisupersolution of (I).

THEOREM 2-2. Assume (1)-(4). Then there is $\epsilon_0 > 0$ such that for any ϵ with $0 < \epsilon \leq \epsilon_0$ there exist a quasisub solution $\bar{w}(x;\epsilon)$ and a quasisuper solution $\hat{w}(x;\epsilon)$ of (I) so that $\bar{w}(x;\epsilon) \leq \hat{w}(x;\epsilon)$ for all $x \in \overline{\Omega}$,

$$\lim_{\epsilon o 0} ar w(x;\epsilon)ig(\, {
m or}\, \hat w(x;\epsilon)ig) = egin{cases} g_2(x) & {
m in} & arOmega_1\ g_1(x) & {
m in} & arOmega_2\,, \end{cases}$$

and the convergence is uniform on every compact subset of indicated regions.

Proof. We first construct a quasisupersolution $\hat{w}(x; \epsilon)$ of (I). From the hypothesis (3), there is a positive constant r_1 such that

$$f_u(x,g_i(x)\pm r)\leq -K<0$$

for all $0 \leq r \leq r_1$ and for all $x \in \overline{\Omega}$, i = 1, 2. Let $\rho_0 > 0$ be a sufficiently small number so that $\rho_0 < r_1$, and let $L(s, \rho_0) = f(s, g_1(s) + \rho_0)$ for all $s \in \partial \Omega_2$. Then $L(s, \rho_0) < 0$ for all $s \in \partial \Omega_2$. Let F(s, u) = $-f(s, g_1(s) + \rho_0 + u) + L(s, \rho_0)$. Then F(s, 0) = 0 and $F_u(s, 0) \geq K > 0$ for all $s \in \partial \Omega_2$. Now, since

$$\int_{0}^{\beta(s)} F(s,u) \, du$$

= $\int_{g_1(s)+\rho_0}^{g_1(s)+\rho_0+\beta(s)} -f(s,u) \, du + L(s,\rho_0)\beta(s).$

and since if we choose ρ_0 so that

$$\int_{g_1(s)+\rho_0}^{g_2(s)+\rho_0} -f(s,u)\,du>0$$

for all $s \in \partial \Omega_2$, then

$$\int_{g_1(s)+\rho_0}^{g_1(s)+\rho_0+\beta(s)} -f(s,u)\,du>0$$

for all $\beta(s) \in (0, g_2(s) - g_1(s)]$. Since

$$\lim_{\rho_0\to 0} L(s,\rho_0) = 0,$$

uniformly for all $s \in \partial \Omega_2$,

$$\int_0^{\beta(s)} F(s,u) \ du > 0$$

for all $\beta(s) \in (0, g_2(s) - g_1(s)]$. Then, by Lemma, there is a unique monotone solution $v(s, \tau)$ of the problem

$$\frac{\partial^2 v}{\partial \tau^2} = -f(s, g_1(s) + \rho_0 + v) + L(s, \rho_0)$$
$$v(s, 0) = g_2(s) - g_1(s), \quad v(s, \infty) = 0$$

such that v and the first derivatives and second derivatives of v in sand τ decay exponentially as $\tau \to \infty$. Let $t = \epsilon \tau$ and $V(s,t) = v(s, \frac{t}{\epsilon})$, and let $\bar{O}_{\kappa} = \{(s,t) \in \bar{\Omega}_2 : 0 \leq t \leq \kappa, s \in \partial \Omega_2\}$, where κ is so chosen that the normals through distinct points of $\partial \Omega_2$ do not intersect on \bar{O}_{κ} . Then if $x = (s,t) \in O_{\kappa}$,

$$\begin{aligned} \epsilon^2 \Delta V(x) &= \epsilon^2 \frac{\partial^2 V}{\partial t^2} + 0(\epsilon) \\ &= \frac{\partial^2 v}{\partial \tau^2} + 0(\epsilon) \\ &= -f(s, g_1(s) + \rho_0 + v(s, \tau)) + L(s, \rho_0) + 0(\epsilon) \\ V(s, 0) &= v(s, 0), \quad V(s, \infty) = 0 \end{aligned}$$

We take a smooth function $\sigma(t) \in C^{\infty}([0,\infty))$ such that $\sigma(t) = 1$ for $0 \leq t \leq \frac{\kappa}{3}$ and $\sigma(t) = 0$ for $\frac{2}{3}\kappa \leq t$, and $0 \leq \sigma(t) \leq 1$ for all $t \geq 0$, and we define $\hat{V}(s,t) = V(s,t)\sigma(t)$ for $(s,t) \in \bar{O}_{\kappa}$ and $\hat{V}(x) = 0$ for $x \in \Omega_2 \setminus \bar{O}_{\kappa}$. Then the function \hat{V} is in $C^2(\bar{\Omega}_2)$. We note that κ is independent of ϵ .

Let $\hat{U}(x;\epsilon) = g_1(x) + \rho_0 + \hat{V}(x)$ for all $x \in \overline{\Omega}_2$. Now we prove that

$$\epsilon^2 \Delta \hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon)) \leq 0$$

in Ω_2 . For any x = (s, t) with $0 < t \le \frac{\kappa}{3}$,

$$\begin{split} &\epsilon^{2}\Delta\hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon)) \\ &= \epsilon^{2}\Delta\hat{V}(x) + f(x,\hat{U}(x;\epsilon)) + 0(\epsilon^{2}) \\ &= \frac{\partial^{2}v}{\partial\tau^{2}} + f(x,\hat{U}(x;\epsilon)) + 0(\epsilon) \\ &= -f(s,g_{1}(s) + \rho_{0} + v(s,\tau)) + f(x,g_{1}(s) + \rho_{0} + v(s,\tau)) \\ &- f(x,g_{1}(s) + \rho_{0} + v(s,\tau)) + f(x,g_{1}(x) + \rho_{0} + v(s,\tau)) \\ &+ L(s,\rho_{0}) + 0(\epsilon) \\ &= \nabla_{x}f(x^{*},g_{1}(s) + \rho_{0} + v(s,\tau)) \circ \left[\frac{dx}{dt}(t^{*})\right]t \\ &+ f_{u}(x,u^{*})\left(\nabla g_{1}(x^{**}) \circ \frac{dx}{dt}(t^{**})\right)t + L(s,\rho_{0}) + 0(\epsilon), \end{split}$$

where x^* and x^{**} are on the line segment passing through the point x and s on O_{κ} , and u^* is between $\hat{U}(x;\epsilon)$ and $g_1(s) + \rho_0 + v(s,\tau)$, and $0 < t^*, t^{**} < t$, and \circ is the inner product in \mathbb{R}^n . Hence

$$\epsilon^2 \Delta \hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon)) = 0(t) + 0(\epsilon) + L(s,\rho_0).$$

If ϵ and κ are sufficiently small, then

$$\epsilon^2 \Delta \hat{U}(x;\epsilon) + fig(x;\epsilon)ig) \leq 0.$$

For any x = (s, t) with $\frac{\kappa}{3} < t < \frac{2}{3}\kappa$,

$$\begin{aligned} &\epsilon^2 \Delta \hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon)) \\ &= \epsilon^2 \Delta \hat{V}(s,t) + f(x,g_1(x) + \rho_0 + \hat{V}(s,t)) + 0(\epsilon^2) \\ &= \frac{\partial^2 v}{\partial \tau^2} \sigma + f(x,g_1(x) + \rho_0 + V\sigma) + 0(\epsilon). \end{aligned}$$

Since $\frac{\partial^2 v}{\partial \tau^2}$ and v decay exponentially as $\tau \to \infty$ and $f(x, g_1(x) + \rho_0) < 0$, so

$$\epsilon^2 \Delta \hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon)) \le 0$$

Multiple solutions of a class

if ϵ is sufficiently small. For any $x \in \Omega_2 \setminus \overline{O}_{\frac{2}{2}\kappa}$,

$$\hat{U}(x;\epsilon)=g_1(x)+\rho_0.$$

Then

$$\epsilon^2 \Delta \hat{U}(x;\epsilon) + f(x,\hat{U}(x;\epsilon))$$

=0(\epsilon^2) + f(x,g_1(x) + \rho_0) \le 0

if ϵ is sufficiently small. Furthermore, we note that if $x \in \partial \Omega_2$,

$$\hat{U}(x;\epsilon)=g_2(x)+\rho_0.$$

We choose a function $h \in C^2(\bar{\Omega})$ such that $\frac{\partial h}{\partial n} \ge 0$ on $\partial \Omega$ and $g_2(x) < h(x) \le g_2(x) + \rho_0$ in $\bar{\Omega}$. Let

$$\hat{w}(x;\epsilon) = \left\{egin{array}{cc} \min\{\hat{U}(x;\epsilon),h(x)\} & ext{ if } x\inar{arDeta}_2 \ h(x) & ext{ if } x\inar{arDeta}\setminusar{arDeta}_2 \ . \end{array}
ight.$$

Since f(x, h(x)) < 0 for all $x \in \overline{\Omega}$,

$$\epsilon^2 \Delta \hat{w}(x;\epsilon) + f(x,\hat{w}) \le 0$$

if \hat{w} is twice partial differentiable at x in Ω . Moreover, if $x = (s, 0) \in \partial \Omega$, then

$$rac{\partial \hat{w}}{\partial n}(x) = rac{\partial h}{\partial n}(x) \ge 0$$
 .

We hence note that $\hat{w}(x;\epsilon)$ is a quasisupersolution of (I) if $\epsilon > 0$ is sufficiently small.

To construct a quasisubsolution of (I), we let $G(s, u) = f(s, g_2(s) - \nu_0 - u) - l(s, \nu_0)$, where $l(s, \nu_0) = f(s, g_2(s) - \nu_0)$ for all $s \in \partial \Omega_1$ and for some ν_0 with $0 < \nu_0 < r_1$. Then $l(s, \nu_0) > 0$, G(s, 0) = 0, $G_u(s, 0) \ge K$, and

$$\int_0^{\alpha(s)} G(s,u)\,du > 0$$

for all $\alpha(s) \in (0, g_2(s) - g_1(s)]$ if ν_0 is sufficiently small.

By the similar method used in constructing quasisupersolution of (I), we can find a quasisubsolution $\bar{w}(x;\epsilon)$ of (I) having the following properties:

$$\begin{split} \bar{w}(x;\epsilon) &= \begin{cases} \max\{\bar{U}(x;\epsilon),k(x)\} & textif \quad x\in\Omega_1\\ k(x) & \text{if} \quad x\in\bar{\Omega}\setminus\bar{\Omega}_1, \\ \bar{w}(x;\epsilon) &= g_1(s) - \nu_0 \quad \text{for all} \quad x\in\partial\Omega_1, \\ k\in C^2(\bar{\Omega}), \ g_1(x) - \nu_0 &\leq k(x) < g_1(x) \text{ in } \bar{\Omega}, \ \frac{\partial k}{\partial n} \leq 0 \text{ on } \partial\Omega, \\ \bar{U}(x;\epsilon) &= g_2(x) - \nu_0 + \bar{v}(x) \quad \text{for all} \quad x\in\bar{\Omega}_1, \\ \bar{v}(x;\epsilon) &= \begin{cases} U(s,t)\sigma(t) & \text{for } (s,t)\in\bar{O}_\eta\\ 0 & \text{for all} \quad x\in\Omega_1\setminus\bar{O}_\eta, \\ \bar{O}_\eta &= \{(s,t)\in\bar{\Omega}_1: 0\leq t\leq\eta, s\in\partial\Omega_1\} \end{cases}. \end{split}$$

Here η is so chosen that the normals through distinct points of $\partial\Omega_1$ do not intersect on \bar{O}_{η} and η is independent of ϵ . As before $\sigma(t) \in C^{\infty}([0,\infty)), \ \sigma(t) = 1$ for $0 \le t \le \frac{\eta}{3}$ and zero for $\frac{2}{3}\eta \le t$, and $0 \le \sigma(t) \le 1$ for all $t \ge 0$.

Finally, $U(s,t) = u(s,\tau)$, $(t = \epsilon \tau)$, is the unique monotone solution of the problem:

$$\frac{\partial^2 u}{\partial \tau^2} = f(s, g_2(s) - \nu_0 - u) - l(s, \nu_0)$$
$$u(s, 0) = g_2(s) - g_1(s), \quad u(s, \infty) = 0$$

Clearly, $\bar{w}(x;\epsilon) \leq \hat{w}(x;\epsilon)$ for all $x \in \bar{\Omega}$ and the convergence for \bar{w} and \hat{w} as $\epsilon \to 0$ is true if we choose ρ_0 and ν_0 smaller and smaller. This completes the proof.

Choosing four functions $p_i(x)$, (i = 1, 2, 3, 4) such that $p_i \in C^2(\overline{\Omega})$, for each $x \in \partial \Omega$,

$$rac{\partial p_1}{\partial n} \leq 0, \quad rac{\partial p_2}{\partial n} \geq 0, \quad rac{\partial p_3}{\partial n} \leq 0, \quad rac{\partial p_4}{\partial n} \geq 0,$$

and for each $x \in \overline{\Omega}$,

$$egin{aligned} &fig(x,p_1(x)ig)>0,\;fig(x,p_2(x)ig)<0,\;fig(x,p_3(x)ig)>0,\;fig(x,p_4(x)ig)<0\,,\ &g_1(x)-
u_0\leq p_1(x)\leq g_1(x)\leq p_2(x)\leq g_1(x)+
u_0\,,\ &g_2(x)-
u_0\leq p_3(x)\leq g_2(x)\leq p_4(x)\leq g_2(x)+
u_0\,, \end{aligned}$$

and using Theorem 2-1 and Theorem 2-2, we conclude the following theorem which is the main result.

THEOREM 2-3. With assumptions (1)-(4), there is $\epsilon_0 > 0$ such that for any ϵ with $0 < \epsilon \leq \epsilon_0$ the problem (I) has at least five distinct ordered solutions $u_j(x;\epsilon)$ in $C^2(\bar{\Omega})$ such that

$$p_1(x) \leq u_1(x;\epsilon) \leq p_2(x),$$

 $u_1(x;\epsilon) \leq u_2(x;\epsilon) \leq u_3(x;\epsilon),$
 $\bar{w}(x;\epsilon) \leq u_3(x;\epsilon) \leq \hat{w}(x;\epsilon),$
 $p_3(x) \leq u_5(x;\epsilon) \leq p_4(x),$
 $u_3(x;\epsilon) \leq u_4(x;\epsilon) \leq u_5(x;\epsilon),$

for all $x \in \overline{\Omega}$. Especially

$$\begin{split} &\lim_{\epsilon \to 0} u_j(x;\epsilon) = g_j(x) \quad x \in \bar{\Omega} \quad (j = 1, 5) \,, \\ &\lim_{\epsilon \to 0} u_2(x;\epsilon) = g_1(x) \quad x \in \Omega_2 \,, \\ &\lim_{\epsilon \to 0} u_4(x;\epsilon) = g_2(x) \quad x \in \Omega_1 \,, \\ &\lim_{\epsilon \to 0} u_3(x;\epsilon) = \begin{cases} g_1(x) \quad x \in \Omega_2 \\ g_2(x) \quad x \in \Omega_1 \,, \end{cases} \end{split}$$

and the above convergencies are uniform on every compact subset of indicated regions.

REMARK. In fact, the above theorem is true in case that $f \in C^{\alpha}(\bar{\Omega} \times I)$, $0 < \alpha < 1$, and I is a bounded interval in R such that $g_i(x) \in I$ for all i = 1, 3 and for all $x \in \bar{\Omega}$, if we replace the assumption (3) by the hypothesis that there is a positive number r_1 such that

$$f(x,g_i(x)-r)>0 \quad ext{and} \quad f(x,g_i(x)+r)<0$$

for all $x \in \overline{\Omega}$, for all r with $0 < r \le r_1$, and i = 1, 3.

From Theorem 2-3 and Remark, we have the following results:

COROLLARY 1. In the problem (I), let f(x, u) = u(u - a(x))(1 - u). If the function a(x) has the following properties: 0 < a(x) < 1 for all $x \in \overline{\Omega}$, $a \in C^1(\overline{\Omega})$, and there are two nonempty disjoint connected open subsets Ω_1 and Ω_2 with smooth boundaries such that for any point $x \in \partial \Omega_1$,

$$\int_{\gamma(x)}^1 u(u-a(x))(1-u)\,du > 0$$

for all $\gamma(x) \in [0, 1)$, and for any $x \in \partial \Omega_2$

$$\int_0^{\gamma(x)} u(u-a(x))(1-u)\,du < 0$$

for all $\gamma(x) \in (0, 1]$, then for all sufficiently small $\epsilon > 0$ the problem (I) has at least three distinct positive nontrivial ordered solutions $u_j(x; \epsilon)$ in $C^2(\bar{\Omega})$ such that

$$0 < u_1(x;\epsilon) \le u_2(x;\epsilon) \le u_3(x;\epsilon) < 1$$

for all $x \in \overline{\Omega}$,

$$egin{aligned} &\lim_{\epsilon o 0} u_1(x;\epsilon)=0 & x\in arOmega_2\,,\ &\lim_{\epsilon o 0} u_3(x;\epsilon)=1 & x\in arOmega_1\,,\ &\lim_{\epsilon o 0} u_2(x;\epsilon)=egin{cases} 1 & x\in arOmega_1\,,\ &0 & x\in arOmega_2\,, \end{aligned}$$

and the above convergencies are uniform on every compact subset of indicated regions.

COROLLARY 2. Let f(x,u) = u(u-a(x))(1-u), 0 < a(x) < 1 for all $x \in \overline{\Omega}$, and $a \in C^1(\overline{\Omega})$. If there are N nonempty disjoint connected open subsets $\Omega_1, \Omega_2, \dots, \Omega_N$ of Ω such that their boundaries are smooth, for any point $x \in \partial \Omega_i$ (i's are odd)

$$\int_{\gamma(x)}^1 f(x,u)\,du>0$$

for all $\gamma(x) \in [0, 1)$, and for any point $x \in \partial \Omega_j$ (j's are even)

$$\int_0^{\gamma(x)} f(x,u) \, du < 0$$

for all $\gamma(x) \in (0,1]$, then for all sufficiently small $\epsilon > 0$ the problem (I) has three distinct nontrivial positive ordered solutions $u_k(x;\epsilon)$ in $C^2(\bar{\Omega})$ such that

$$0 < u_1(x;\epsilon) \leq u_2(x;\epsilon) \leq u_3(x;\epsilon) < 1$$

for all $x \in \overline{\Omega}$,

$$\begin{split} &\lim_{\epsilon \to 0} u_1(x;\epsilon) = 0 \quad x \in \Omega_j \quad (j = \text{even}) \,, \\ &\lim_{\epsilon \to 0} u_3(x;\epsilon) = 1 \quad x \in \Omega_i \quad (i = \text{odd}) \,, \\ &\lim_{\epsilon \to 0} u_2(x;\epsilon) = \begin{cases} 1 \quad x \in \Omega_i \quad (i = \text{odd}) \\ 0 \quad x \in \Omega_j \quad (j = \text{even}) \end{cases} \end{split}$$

and the above convergencies are uniform on every compact subset of indicated regions.

3. The function f(x, u) = g(x)h(u) case

Consider a model with two alleles A_1 and A_2 corresponding to three possible genotypes A_1A_1 , A_1A_2 , A_2A_2 . The population lives in a region Ω in \mathbb{R}^n . Let u(x,t) denote the frequency of the allele A_1 at time t at the point x in Ω . Changes in gene frequency are assumed to be caused only by the flow of genes within Ω and selective advantages for certain genotypes in certain subregions of Ω .

In [2], they said that u satisfies the semilinear parabolic equation

$$u_t(x,t) = \epsilon^2 \Delta u + g(x)h(u)$$

in Ω , where h(u) = u(1-u)[k(1-u) + (1-k)u], for some constants $\epsilon > 0$, and 0 < k < 1. They assumed that g takes on both positive and negative values on the region Ω and that either

$$\int_{\Omega} g(x) \, dx < 0$$

or

$$\int_{\Omega} g(x)\,dx > 0\,.$$

They then proved by bifurcation method that there is $\epsilon_0 > 0$ such that for all ϵ with $0 < \epsilon \leq \epsilon_0$ the problem (I) has a nontrivial positive solution $u(x;\epsilon)$ in $C^2(\bar{\Omega})$ such that $0 < u(x;\epsilon) < 1$ for all $x \in \bar{\Omega}$.

Now, without the integral condition for g we prove the existence of two nontrivial positive solutions as well as the existence of interior transition layers of the solutions as $\epsilon \to 0$. Here we assume that $g \in C^1(\bar{\Omega})$ and $h \in C^1(I)$, where I is an interval in R.

THEOREM 3.1. Let f(x,u) = g(x)h(u), h have three zeros $z_1 < z_2 < z_3$ and no other zeros between z_1 and z_3 , and h satisfy that $h'(z_1) < 0$, $h'(z_2) > 0$, and $h'(z_3) < 0$. If $\Omega_1 = \{x \in \Omega : g(x) < 0\}$ and $\Omega_2 = \{x \in \Omega : g(x) > 0\}$ are connected open subsets of Ω with smooth boundaries, then there is ϵ_0 such that for all ϵ with $0 < \epsilon \le \epsilon_0$ the problem (I) has two nontrivial ordered solutions $u_i(x;\epsilon)$ in $C^2(\overline{\Omega})$ so that $z_1 \le u_i(x;\epsilon) \le z_3$ for all $x \in \overline{\Omega}$ and they have the following interior transition layers:

$$\lim_{\epsilon \to 0} u_1(x; \epsilon) = \begin{cases} z_2 & x \in \Omega_1 \\ z_1 & x \in \Omega_2 \\ \end{cases},$$
$$\lim_{\epsilon \to 0} u_2(x; \epsilon) = \begin{cases} z_2 & x \in \Omega_1 \\ z_3 & x \in \Omega_2 \\ \end{cases},$$

and the above convergence are uniform on every compact subset of indicated regions.

Proof. For any $x \in \Omega_1$ and for any $z_1 < u < z_2$, f(x, u) > 0. Since $f(x, z_2) = 0$, $f_u(x, z_2) < 0$, and

$$\int_{z_1}^{z_2} f(x,u)\,du > 0$$

for all $x \in \Omega_1$, by the similar construction on the proof of Theorem 2-2, there is a function $\bar{u}_1(x;\epsilon) \in C^2(\bar{\Omega}_1)$ such that for all sufficiently

small $\epsilon > 0$,

$$egin{aligned} \epsilon^2 \Delta ar{u}_1 + f(x,ar{u}_1) &\geq 0, \quad x \in \Omega_1, \ ar{u}_1(x;\epsilon) &= z_1, \quad x \in \partial \Omega_1, \ z_1 &< ar{u}_1(x;\epsilon) < z_2, \quad x \in ar{\Omega}_1, \end{aligned}$$

and $\lim_{\epsilon \to 0} \bar{u}_1(x; \epsilon) = z_2$ uniformly on every compact subset of Ω_1 . Let

$$ar{w}_1(x;\epsilon) = \left\{egin{array}{ccc} ar{u}_1(x;\epsilon) & ext{ if } & x\in arOmega_1, \ z_1 & ext{ if } & x\in ar{arOmega}\setminus arOmega_1 \end{array}
ight.$$

,

Then $\bar{w}_1(x;\epsilon)$ is a quasisubsolution of the problem (I).

Similarly, for any $x \in \Omega_2$ and for any $z_1 < u < z_2$, f(x, u) < 0. Since $f(x, z_1) = 0$, $f_u(x, z_1) < 0$, and $\int_{z_1}^{z_2} f(x, u) du < 0$ for all $x \in \Omega_2$, there is a function $\hat{u}_1(x; \epsilon) \in C^2(\bar{\Omega}_2)$ such that for all sufficiently small $\epsilon > 0$,

$$egin{aligned} \epsilon^2 \Delta \hat{u}_1 + f(x, \hat{u}_1) &\leq 0, \qquad x \in arOmega_2, \ \hat{u}_1(x; \epsilon) &= z_2, \qquad x \in \partial \Omega_2, \ z_1 &< \hat{u}_1(x; \epsilon) < z_2, \qquad x \in ar\Omega_2, \end{aligned}$$

and $\lim_{\epsilon \to 0} \hat{u}_1(x; \epsilon) = z_1$ uniformly on every compact subset of Ω_2 . Let

$$\hat{w}_1(x;\epsilon) = \left\{egin{array}{ccc} \hat{u}_1(x;\epsilon) & ext{ if } x\in \Omega_2, \ z_2 & ext{ if } x\in ar{arOmega}\setminus \Omega_2 \end{array}
ight.$$

Then $\hat{w}_1(x;\epsilon)$ is a quasisupersolution of the problem (I). Since

$$ar{w}_1(x;\epsilon) \leq \hat{w}_1(x;\epsilon)$$

for all $x \in \overline{\Omega}$, there is a solution $u_1(x;\epsilon) \in C^2(\overline{\Omega})$ such that

$$z_1 \leq \bar{w}_1(x;\epsilon) \leq u_1(x;\epsilon) \leq \hat{w}_1(x;\epsilon) \leq z_2$$

for all $x \in \overline{\Omega}$ and for all sufficiently small $\epsilon > 0$.

By the same method, for any $x \in \Omega_1$ and for any $z_2 < u < z_3$, f(x,u) < 0. Since $f(x,z_2) = 0$, $f_u(x,z_2) < 0$, and $\int_{z_2}^{z_3} f(x,u) du < 0$

for all $x \in \Omega_1$, there is a quasisupersolution $\hat{w}_2(x;\epsilon)$ of the problem (I) such that $\lim_{\epsilon \to 0} \hat{w}_2(x;\epsilon) = z_2$ uniformly on every compact subset of Ω_1 and $\hat{w}_2(x;\epsilon) = z_3$ for all $x \in \overline{\Omega} \setminus \Omega_1$.

Similarly, for any $x \in \Omega_2$ and for any $z_2 < u < z_3$, f(x,u) > 0. Since $f(x,z_3) = 0$, $f_u(x,z_3) < 0$, and $\int_{z_2}^{z_3} f(x,u) du > 0$ for all $x \in \Omega_2$, there is a quasisubsolution $\bar{w}_2(x;\epsilon)$ of the problem (I) such that $\lim_{\epsilon \to 0} \bar{w}_2(x;\epsilon) = z_3$ uniformly on every compact subset of Ω_2 and $\bar{w}_2(x;\epsilon) = z_2$ for all $x \in \bar{\Omega} \setminus \Omega_2$. We note that $\bar{w}_2(x;\epsilon) \leq \hat{w}_2(x;\epsilon)$ for all $x \in \bar{\Omega}$. Hence there is another nontrivial solution $u_2(x;\epsilon)$ of the problem (I) such that

$$z_2 \leq ar{w}_2(x;\epsilon) \leq u_2(x;\epsilon) \leq \hat{w}_2(x;\epsilon) \leq z_3$$

for all $x \in \overline{\Omega}$ and for all sufficiently small $\epsilon > 0$.

Introducing some functions $\bar{h} < h$ and $\hat{h} > h$ which satisfy the conditions on the derivatives at z_1 , z_2 , and z_3 in Theorem 3-1, we can prove the same existence result in the case of $h'(z_1) \leq 0$ and $h'(z_3) \leq 0$.

COROLLARY 1. Theorem 3-1 is true if we replace the assumptions

$$h'(z_1) < 0$$
 and $h'(z_3) < 0$

by $h'(z_1) \leq 0$ and $h'(z_3) \leq 0$, h(u) < 0 for all $z_1 < u < z_2$ and h(u) > 0 for all $z_2 < u < z_3$.

COROLLARY 2. In Theorem 3-1, let h have two zeros z_1 and z_2 and no other zeros between them, and let $h'(z_1) < 0$ and $h'(z_2) > 0$. Then there is ϵ_0 such that for all ϵ with $0 < \epsilon \leq \epsilon_0$ the problem (I) has a nontrivial solution $u(x;\epsilon)$ in $C^2(\bar{\Omega})$ so that $z_1 < u(x;\epsilon) < z_2$ for all $x \in \bar{\Omega}$,

$$\lim_{\epsilon \to 0} u(x; \epsilon) = \begin{cases} z_2 & x \in \Omega_1 \\ z_1 & x \in \Omega_2 \end{cases}$$

and the above convergence is uniform on every compact subset of the indicated regions.

From Theorem 3-1, Corollary 1 and 2, we have the following results:

Corollary 3. Let f(x, u) = g(x)u(1-u)[k(1-u)+(1-k)u]. Then there is ϵ_0 such that for all ϵ with $0 < \epsilon \leq \epsilon_0$,

(1) if either k > 1 or k < 0, there exist two nontrivial positive solutions $u_i(x;\epsilon)$ in $C^{(\bar{\Omega})}$ so that $0 < u_i(x;\epsilon) < 1$ for all $x \in \bar{\Omega}$,

(2) if $k \in \{0, \frac{1}{2}, 1\}$, there exists a nontrivial positive solution $u(x; \epsilon)$ in $C^2(\bar{\Omega})$ so that $0 < u(x; \epsilon) < 1$ for all $x \in \bar{\Omega}$ and

$$\lim_{\epsilon \to 0} u(x; \epsilon) = \begin{cases} 0 & x \in \Omega_1 \\ 1 & x \in \Omega_2 \end{cases},$$

(3) if $\frac{1}{2} < k < 1$, there exist two nontrivial positive solutions $u_i(x;\epsilon)$ in $C^2(\bar{\Omega})$ so that $0 < u_i(x;\epsilon) < \frac{k}{2k-1}$ for all $x \in \bar{\Omega}$,

$$\lim_{\epsilon \to 0} u_1(x;\epsilon) = \begin{cases} 0 & x \in \Omega_2 \\ 1 & x \in \Omega_1 \\ \end{bmatrix},$$
$$\lim_{\epsilon \to 0} u_2(x;\epsilon) = \begin{cases} 1 & x \in \Omega_2 \\ \frac{k}{2k-1} & x \in \Omega_1 \\ \end{cases},$$

(4) if $0 < k < \frac{1}{2}$, there exist two nontrivial solutions $u_i(x;\epsilon)$ in $C^2(\bar{\Omega})$ so that $\frac{k}{2k-1} < u_i(x;\epsilon) < 1$ for all $x \in \bar{\Omega}$,

$$\lim_{\epsilon \to 0} u_1(x;\epsilon) = \begin{cases} 1 & x \in \Omega_2 \\ 0 & x \in \Omega_1 \\ \vdots \\ u_2(x;\epsilon) = \begin{cases} \frac{k}{2k-1} & x \in \Omega_2 \\ 0 & x \in \Omega_1 \end{cases}$$

and the above convergencies are uniform on every compact subset of indicated regions.

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Department of Mathematics Education Cheju National University Cheju City 690-756, Korea