# ON A CONSTRUCTION OF A CARTESIAN CLOSED CATEGORY $\mathbb{D}(L)$ 

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## 1. Introduction

The language $L$ under consideration is called type-theoretic because its syntax is based on Russell's simple theory of types. $L$ will contain both constants and variables in every syntactic category, and it will allow quantification over variables of any category. Thus, $L$ will have not only variables ranging over individuals which is characteristic of firstorder languages, and variables ranging over predicates too, as does a second-order language, but variables ranging over every category defined in the type theory. Thus the language is known as a higher order language. We recall the concept of categories in $L$.

1. The category of terms of $L$ will be designated by the symbol $e$.
2. The category of formulas of $L$ will be designated by the symbol $t$.
3. The category of one-place predicates of $L$ will be designated by the symbol $\langle e, t\rangle$.
4. The category of two-place predicates of $L$ will be designated by $<e,\langle e, t\rangle>$.

Now we can give the formal definitions of the syntax and semantics of $L$.

## 2. Syntax of $L$

(1) The set of types of $L$ is defined recursivly as the following:[2]
(a) $e$ is a type.
(b) $t$ is a type.
(c) It $a$ and $b$ are any types, then $\langle a, b\rangle$ is a type.
(d) Nothing else is a type.
(2) The basic expressions of $L$ consist of non-logical constans and variables:
(a) For each type $a$, the set of non-logical constants of type $a$, denoted $C o n_{a}$, contains constants $C_{n, a}$ for each natural number $n$.
(b) For each type $a$, the set of variables of type $a$, denoted $V a r_{a}$, contains variables $V_{n, a}$ for each natural number $n$.
(3) Syntactic rules of $L$.

The set of meaningful expressions of type $a$, denoted " $M E_{a}$ ", for any type $a$ is defined recursively as follows :
(a) For each type $a$, every variable and every non-logical constant of type $a$ is a member of $M E_{a}$.
(b) For any types $a$ and $b$, if $\beta \in M E_{<a, b>}$ and $\alpha \in M E_{a}$, then $\beta(\alpha) \in M E_{b}$.
(c) - (g) If $\phi$ and $\psi$ are in $M E_{t}$, then so are each of the following $: \llbracket \neg \phi \rrbracket, \llbracket \phi \wedge \psi \rrbracket, \llbracket \phi \vee \psi \rrbracket, \llbracket \phi \rightarrow \psi \rrbracket, \llbracket \phi \leftrightarrow \psi \rrbracket$.
(h) If $\phi \in M E_{t}$ and $u$ is a variable (of any type), then $\forall u \phi \in M E_{t}$.
(i) If $\phi \in M E_{t}$ and $u$ is a variable (of any type), then $\exists u \phi \in M E_{t}$.

## 3. Semantics of $L$

A model for $L$ is then an ordered pair $\langle A, F\rangle$ such that A is the domain of individuals or entities and $F$ is a function assigning a denotation to each non-logical constant of $L$ of type $a$ from the set $D_{a}$.

An assignment of values to variables (variable assignment) $g$ is a function assigning to each variable to $V_{n, a}$ a denotation from the set $D_{a}$, for each type $a$ and natural number $n$.

The denotation of an expression of $L$ relative to a model $M$ and variable assignment $g$ is defined recursively as follows :
(a) If $\alpha$ is a non-logical constant, then $\llbracket \alpha \rrbracket^{M, g}=F(\alpha)$.
(b) If $\alpha$ is a variable, then $\left\lceil\alpha \rrbracket^{M, g}=g(\alpha)\right.$.
(2) If $\alpha \in M E_{<a, b>}$ and $\beta \in M E_{a}$, then $\llbracket \alpha(\beta) \rrbracket^{M, g}=\llbracket \alpha \rrbracket^{M, g}\left(\llbracket \beta \rrbracket^{M, g}\right)$.
(3)-(7) If $\phi$ and $\psi$ are in $M E_{t}$, then $\llbracket \neg \phi \rrbracket^{M, g}, \llbracket \phi \wedge \psi \rrbracket^{M, g}, \llbracket \phi \vee \psi \rrbracket^{M, g}$, $\llbracket \phi \rightarrow \psi \rrbracket^{M, g}$ and $\llbracket \phi \leftrightarrow \psi \rrbracket^{M, g}$ are as specified for the first-order predicate. If $\phi$ is an expression of category $M E_{t}$, then $\llbracket \neg \phi \rrbracket^{M, g}=1$ iff
$\llbracket \phi \rrbracket^{M, g}=0$; otherwise, $\llbracket \neg \phi \rrbracket^{M, g}=0$. Similarly for $\llbracket \phi \wedge \psi \rrbracket, \llbracket \phi \vee$ $\psi \rrbracket, \llbracket \phi \rightarrow \psi \rrbracket$, and $\llbracket \phi \leftrightarrow \psi \rrbracket$.
(8) If $\phi \in M E_{t}$ and $u$ is in $V a r_{a}$, then $\llbracket \forall u \phi \rrbracket^{M, g}=1$ iff for all $e$ in $D_{a} \llbracket \phi \|^{M, g} u=1$.
(9) If $\phi \in M E_{t}$ and $u$ is in $V a r_{a}$, then $\ u \phi \rrbracket^{M, g}=1$ iff for some $e$ in $D_{a} \llbracket \phi \rrbracket^{M, g} u=1$.

The semantic value of an expression does not depend on variables that are not free in the expression. So we add the following definition.

The denotation of an expression of $L$ relative to a model $M$ is defined as follows:
(1) For any expression $\phi$ in $M E_{t}, \llbracket \phi \rrbracket^{M}=1$ iff $\llbracket \phi \rrbracket^{M, g}=1$ for every value assignment $g$.
(1) For any expression $\phi$ in $\left.M E_{\ell}, \llbracket \phi\right]^{M}=0$ iff $\mathbb{\|} \phi \mathbb{\rrbracket}^{M, g}=0$ for every value assignment $g$.

## 4. A type model $D$ of a language $L$

Let us construct a type model $D$ of a higher-order type-theoretic language $L$. Let $E$ be a singleton of type $e$. Starting from $D_{0}=$ $\{t\}$ a chain of approximations of a type model $D$ is built by defining $D_{n+1}=E+<D_{n}, D_{n}>$ where + represents disjoint sum and $<$ $D_{n}, D_{n}>$ is the space of all continuous mappings from $D_{n}$ to $D_{n}$, and embedding each $D_{n}$ in $D_{n+1}$ by a suitable projection pair ( $i_{n}, p_{n}$ ) of $D_{n}$ on $D_{n+1}$ where $i_{n}: D_{n} \rightarrow D_{n+1}, p_{n}: D_{n+1} \rightarrow D_{n}$ with the properties $p_{n} \circ i_{n}=\imath d_{D_{n}}, \imath_{n} \circ p_{n} \subseteq i d_{D_{n+1}}$. A standard way of building $D$ is by using Scott's inverse limit construction([4] [5]). The inverse limit of this chain can be defined as a set

$$
D=\left\{<d^{(n)}>_{n \in \omega} \mid d^{(n)}=p_{n}\left(d^{(n+1)}\right)\right\}
$$

Each $D_{n}$ can be embedded in $D$ by a projection pair ( $2_{n \infty}, p_{\infty n}$ ). If $d \in D_{n}$, we identify $d$ with $\imath_{n \infty}(d) \in D$. There we can assume $D_{0} \subseteq D_{1} \subseteq \cdots \subseteq D_{n} \subseteq \cdots \subseteq D$. Let $d_{n}$ stand for $i_{n \infty} \circ p_{\infty n}(d)$. It
holds $d_{n}=i_{n \infty} \circ p_{\infty n}(d) \subseteq d$. Also if $d \in D_{n}$, then we have $d_{n}=d$. Now we may take the type model $D$ of $L$ into account of the equational form $D=E+<D, D>$.

Defining a partial ordering $\leqq$ on $D_{n}$ by $d \leqq f$ if and only if $d(a) \leqq$ $f(a)$ for all $a \in D_{n}$, the set of all continuous functions from $D_{n}$ to $D_{n}$ is a complete partial ordered set (c.p.o.s) and the disjoint sum of $E+<D_{n}, D_{n}>$ is a complete one, too.
$S \operatorname{cott}([7])$ obtained $D$ by other construction as, for example, the one based on his information systems. The existence of continuous projections $(-)_{n}: D \rightarrow D$ needs us some suitable properties of mappings $(-)_{n}$ as Scott's approach did. Moreover notice that the inverse limit construction can be carried on is the category c.p.o.. Especially we do not need to assume that $D$ is a domain in the usual sense.

## 5. A cartesian closed category by types $\mathbb{D}(L)$

The complete partial ordered set $D$ of recursive and polymorphic types for the language $L$ gives rise to a category $D(L)$. The objects are the partial equivalence relations (p.e.r.) $\llbracket \alpha \rrbracket$ of $\alpha \in T^{0}$. An arrow $\llbracket \alpha \rrbracket \rightarrow \llbracket \beta \rrbracket$ is a transformation system from a p.e.r. $\mathbb{K} \alpha \rrbracket$ to $a$ p.e.r. $\llbracket \beta \rrbracket$. We may think of the objects of $\mathbb{H}(L)$ as type structures of sentences or knowledges and of the arrows as new representations of types or linguistic transformations.

We may regard an object $\llbracket \alpha \rrbracket$ in $\mathbb{D}(L)$ as a representative tree structure of types based on type $t$. The arrow $f: \llbracket \alpha \rrbracket \rightarrow \llbracket \beta \rrbracket$ of $\mathbb{D}(L)$ are triples $\{\llbracket \alpha \rrbracket,|f|, \llbracket \beta \rrbracket$ ), where $|f|$ is an element of product $\llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket$. We may think of $f$ as denoting a relation between the sets $\llbracket \alpha \rrbracket$ and $\llbracket \beta \rrbracket$. Equality between relations $f, g: \alpha \| \Rightarrow \llbracket \beta \rrbracket$ is defined thus :

$$
f \cdot=\cdot g \text { means }|f|=|g|
$$

The identity $1_{[\alpha]}: \llbracket \alpha \rrbracket \rightarrow \llbracket \alpha \rrbracket$ is defined by

$$
\mathcal{L}_{[\alpha]}=\left\{<a, a^{\prime}>\in \llbracket \alpha \rrbracket \times \llbracket \alpha \|_{\|} \mid a=a^{\prime}\right\}
$$

Composition of relations $f:\lceil\alpha] \times \llbracket \beta \rrbracket$ and $g: \llbracket \beta \rrbracket \times \llbracket \gamma]$ is defined by $|g f|=\left\{<a, c>\in[\alpha] \times\left.[\gamma]\right|_{\vec{G} \in[\beta]}(<a, b>\in|f| \wedge<b, c>\in|g|)\right\}$.

It is easily seen that $\mathbb{D}(L)$ is a category.
A cartesian closed category is a category $\mathbb{D}$ with finite products (hence having a terminal object) such that, for each object $A$ of $\mathbb{D}$, the functor $(-) \times A: \mathbb{D} \rightarrow \mathbb{D}$ has a right adjoint, denoted by $(-)^{A}$ : $\mathbb{D} \rightarrow \mathbb{D}$. This means that, for all objects $A, B$ and $C$ of $\mathbb{D}$, there is an isomorphism

$$
H o m_{\mathbb{D}}(A \times B, C) \xrightarrow{\sim} \operatorname{Hom}_{\mathbb{D}}\left(A, C^{B}\right)
$$

and moreover, this isomorphism is natural in $A, B$ and $C$.
Theorem 5.1. $\mathbb{M}(L)$ forms a cartesian closed category.
Proof. The terminal object 1 of $\mathbb{D}(L)$ is defined by $1=\{*\}$, while products are defined by

$$
\llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket \equiv\{<a, b>\mid a \in \llbracket \alpha \rrbracket \wedge b \in \llbracket \beta \rrbracket\} .
$$

The arrows $\left.0_{\lfloor\alpha]}: \llbracket \alpha \rrbracket \rightarrow 1, \Pi_{\llbracket \alpha],[\beta]}: \llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket \rightarrow \llbracket \alpha\right]$ and

$$
\begin{aligned}
& \Pi_{\lceil\alpha \rrbracket,[\beta]}^{\prime}: \llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket \rightarrow \llbracket \beta \rrbracket \text { are defined thus : } \\
& \left|0_{[\alpha]}\right| \equiv \llbracket \alpha \rrbracket \times\{*\} \equiv\{\langle a, *>\in \llbracket \alpha \rrbracket \times 1| a \in \llbracket \alpha \rrbracket\},
\end{aligned}
$$

> Moreover, if $f: \llbracket r \rrbracket \rightarrow \llbracket \alpha \rrbracket$ and $g: \llbracket r \rrbracket \rightarrow \llbracket \beta \rrbracket$,
> we define $<f, g>: \llbracket \gamma \rrbracket \rightarrow \llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket$ by
> $|<f, g>| \equiv\{\langle c,<a, b \gg \in \llbracket \gamma \rrbracket \times(\llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket)|<c, a>\in|f| \wedge<$ $c, b>\in|g|\}$.

Now we define

$$
\llbracket \beta]^{[\alpha \rrbracket} \equiv\{\rho \in \mathbb{I} \alpha \rrbracket \times \llbracket \beta \rrbracket \mid \rho: \llbracket \alpha \rrbracket \rightarrow \llbracket \beta \rrbracket\} .
$$

We also define $\varepsilon_{[\beta], \llbracket \alpha]}: \llbracket \beta \rrbracket^{\lfloor\alpha]} \times \llbracket \alpha \rrbracket \rightarrow \llbracket \beta \rrbracket$ by
$\left|\varepsilon_{\llbracket \beta],[\alpha]}\right| \equiv\{\ll \rho, a>, b>\in((\llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket) \times \llbracket \alpha \rrbracket) \times \llbracket \beta \rrbracket \mid \rho: \llbracket \alpha \rrbracket \rightarrow$ $\llbracket \beta \rrbracket \wedge<a, b\rangle \in \rho\}$.

Moreover, if $h: \llbracket \alpha \rrbracket \times \llbracket \beta \rrbracket \rightarrow \llbracket \gamma]$ then $h^{*}: \llbracket \alpha \rrbracket \times \llbracket \gamma \rrbracket^{[\beta]}$ is obtained. Thus

$$
\begin{aligned}
& \left|h^{*}\right| \equiv\{<a, \rho>\in \llbracket \alpha \rrbracket \times(\llbracket \beta \rrbracket \times \llbracket \gamma \rrbracket) \mid a \in \llbracket \alpha \rrbracket \wedge \rho: \llbracket \beta \rrbracket \rightarrow \llbracket \gamma \rrbracket \wedge \forall b \in \llbracket \beta \rrbracket \\
& \exists c \in[\gamma](\ll a, b\rangle, c>\in|h| \wedge<b, c>\in \rho)\}
\end{aligned}
$$

Let us consider a valuation on an designated object $\Omega$ to objects of $\mathbb{D}(L)$. A valuation is a function $V: a \rightarrow \Omega$ where $a \in \llbracket \alpha \rrbracket$. Let us take $\Omega=\{1 /(n+1) \mid n=0,1,2, \cdots\}$. We say $\llbracket \rrbracket \rrbracket$ is well-typed whenever, for every $a \in \llbracket \alpha \rrbracket, a$ is degenerated to type $t$ under the operations of iterative formulations $\beta(\alpha)$. This means that, for every $a \in \mathbb{K} \alpha \mathbb{\rrbracket}$, there exists a number $n$ such that $\beta^{n}(a) \in D_{0}$. On the other case we have an irreducible type $\llbracket \alpha \rrbracket^{\prime}$ for which the formulation operation can not be applicable no longer, i.e., $\lfloor\alpha]^{\prime} \in D_{n}$ for some $n \neq 0$. We call this number $n$ the irreducible degree of $\llbracket \alpha \rrbracket$. Now let us assign the valuation as follows :
for every $a \in \llbracket \alpha \rrbracket$,
(i) $V(a)=1$ whenever $\lceil\alpha]$ is well-typed,
(ii) $V(a)=1 /(n+1)$ whenever the irreducible degree of $\llbracket \alpha \rrbracket$ is $n$.

The valuation is extended to a function $V: \llbracket \alpha \rrbracket \rightarrow \Omega$ by the rules for all $\llbracket \alpha \rrbracket$ in $\mathbb{D}(L)$ :
(i) $V(\sim \llbracket \alpha \rrbracket)=1-V(\llbracket \alpha \rrbracket)$
(ii) $V(\llbracket \alpha \rrbracket \wedge \llbracket \beta \rrbracket)=\min (V(\llbracket \alpha \rrbracket), V(\llbracket \beta \rrbracket))$
(iii) $V(\llbracket \alpha \rrbracket \vee \llbracket \beta \rrbracket)=\max (V(\llbracket \alpha \rrbracket), V(\llbracket \beta \rrbracket))$
(iv) $V(\llbracket \alpha \rightarrow \beta \rrbracket)=V(\sim \llbracket \alpha \rrbracket \vee \llbracket \beta \rrbracket)$
(v) $V(\llbracket \forall \varphi \alpha \rrbracket)=\inf _{2}\left(V\left(d_{1}\right)\right)$, where $d_{1} \in \llbracket \forall \varphi \alpha \rrbracket$
(vi) $V(\llbracket \exists \varphi \alpha \rrbracket)=\sup _{2}\left(V\left(d_{\mathrm{t}}\right)\right)$, where $d_{2} \in \llbracket \exists \varphi \alpha \rrbracket$

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