Pusan Kyöngnam Math. J. 10(1994), No. 1, pp 67-72

## MONOTONICITY OF HYPERBOLIC CURVATURE

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# 1. Introduction

Let  $\Omega$  be a hyperbolic region in the complex plane  $\mathbb{C}$  and  $K_{\Omega}(a, \gamma)$ denote the hyperbolic curvature of a  $C^2$  curve  $\gamma$  in  $\Omega$  at a point  $a \in \gamma$ . Flinn and Osgood [3] established a monotonicity property for the hyperbolic curvature. They proved that if  $\Omega$  is a simply connected subregion of a simply connected hyperbolic region  $\Delta$ , then for any  $C^2$ curve  $\gamma$  in  $\Omega$ 

$$\max \left\{ K_{\Omega}\left( a,\gamma
ight) ,2
ight\} \leq\max \left\{ K_{\Delta}\left( a,\gamma
ight) ,2
ight\} .$$

They also showed that the monotonicity property would not extend to arbitrary hyperbolic regions.

In this paper we show that the conclusion of the Flinn-Osgood Monotonicity Theorem remains valid for arbitrary hyperbolic regions provided that the group homomorphism  $g_* : \pi(\Omega, a) \to \pi(\Delta, a)$  induced by the inclusion mapping  $g : \Omega \to \Delta$  is a monomorphism.

### 2. Universal covering projections

Let D be the open unit disk in the complex plane C. Suppose  $\Omega$  is a hyperbolic region C and  $a \in \Omega$ . Then there exists a holomorphic universal covering projection  $f : (D,0) \to (\Omega,a)$ . This is called the General Riemann Mapping Theorem (see [1, p.142] or [2, p.39]); in case  $\Omega$  is simply connected this is the Riemann Mapping Theorem. We shall need the following properties of a covering projection (see [4, Ch. 5] or [8, Ch. 3]).

Received March 17,1994

(1) Given any path  $\gamma$  in  $\Omega$  with initial point *a*, there is a unique path  $\tilde{\gamma}$  in *D* with initial point 0 such that  $f \circ \tilde{\gamma} = \gamma$ . The path  $\tilde{\gamma}$  is called the lift of  $\gamma$  via f.

(2) Suppose  $\gamma_1, \gamma_2$  are two paths in  $\Omega$  from *a* to the common terminal point *b*. Let  $\tilde{\gamma}_j$  be the unique lift of  $\gamma_j$  via *f* with initial point 0. Then  $\tilde{\gamma}_1$  and  $\tilde{\gamma}_2$  have the same terminal point if and only if  $\gamma_1$  is homotopic to  $\gamma_2$  in  $\Omega$  with fixed end points.

(3) Suppose  $\gamma$  is a closed path in  $\Omega$  based at a and  $\tilde{\gamma}$  is the lift of  $\gamma$  via f with initial point 0. Then  $\tilde{\gamma}$  is a closed path if and only if  $\gamma$  is null homotopic.

(4) If  $g: (D,0) \to (\Omega,a)$  is any holomorphic function, then there is a unique holomorphic function  $\tilde{g}: (D,0) \to (D,0)$  such that  $f \circ \tilde{g} = g$ . The function  $\tilde{g}$  is called the lift of g relative to f.

We briefly indicate the construction of  $\tilde{g}$ . For  $\tilde{z} \in D$  let  $\tilde{\gamma}$  be any path in D from 0 to  $\tilde{z}$ . Then  $\gamma = g \circ \tilde{\gamma}$  is a path in  $\Omega$  from a to  $z = g(\tilde{z})$ . Since f is a covering projection, there is a unique lift  $\tilde{\delta}$  of  $\gamma$  in D via f with initial point 0. Let  $\tilde{w}$  be the terminal point of  $\tilde{\delta}$ . Then define  $\tilde{g}(\tilde{z}) = \tilde{w}$ . It remains to show that  $\tilde{g}$  is well-defined. Suppose  $\tilde{\gamma}_1, \tilde{\gamma}_2$  are both paths in D from 0 to  $\tilde{z}$ . Then  $\gamma_j = g \circ \tilde{\gamma}_j$  (j = 1, 2) are paths in  $\Omega$ from a to z. Since D is simply connected,  $\tilde{\gamma}_1$  is homotopic to  $\tilde{\gamma}_2$  in D. It follows that  $\gamma_1$  is homotopic to  $\gamma_2$  in  $\Omega$ . Let  $\tilde{\delta}_j$  be the lift of  $\gamma_j$  via f with initial point 0. Then  $\tilde{\delta}_1$  and  $\tilde{\delta}_2$  have the same terminal point since  $\gamma_1$  is homotopic to  $\gamma_2$ . This proves that  $\tilde{g}$  is well-defined.

We shall employ this lifting property in the special case where  $f : (D,0) \to (\Omega,a)$  and  $h : (D,0) \to (\Delta,a)$  are covering projections,  $\Omega \subset \Delta$  and  $g : \Omega \to \Delta$  is the inclusion map. Then  $g \circ f : (D,0) \to (\Delta,a)$  has a lift  $\tilde{g}$  via h.

The fundamental group of  $\Omega$  with base point *a* will be denoted by  $\pi(\Omega, a)$ . For a closed path  $\gamma$  based at *a*,  $[\gamma]$  is the homotopy class determined by  $\gamma$ . A continuous function  $g: (\Omega, a) \to (\Delta, b)$  induces a group homomorphism  $g_*: \pi(\Omega, a) \to \pi(\Delta, b)$  defined by  $g_*([\gamma]) = [g \circ \gamma]$ .

The following result is well known (see [6]). We include a proof for the convenience of the reader.

**Theorem 1.** Suppose  $\Omega$  and  $\Delta$  are hyperbolic regions in  $\mathbb{C}$  with  $\Omega \subset \Delta$  and  $a \in \Omega$ . Let  $g : \Omega \to \Delta$  be the inclusion map and  $g_* : \pi(\Omega, a) \to \pi(\Delta, a)$  the induced group homomorphism. Assume that  $f : (D, 0) \to (\Omega, a)$  and  $h : (D, 0) \to (\Delta, a)$  are holomorphic universal covering projections. If  $g_*$  is a monomorphism, then there exists a conformal mapping  $\tilde{g}$  of (D, 0) into itself such that  $f = g \circ f = h \circ \tilde{g}$ .

**Proof.** We already know that a holomorphic function  $\tilde{g}: (D,0) \to (D,0)$  exists such that  $g \circ f = h \circ \tilde{g}$ . All that remains is to show that  $\tilde{g}$  is one-to-one. Suppose  $\tilde{z}_1, \tilde{z}_2 \in D, \tilde{z}_1 \neq \tilde{z}_2$  and  $\tilde{g}(\tilde{z}_1) = \tilde{g}(\tilde{z}_2)$ . Let  $\tilde{\gamma}_j$  be the radial path in  $\Omega$  from 0 to  $\tilde{z}_j$  (j = 1, 2). Then  $\gamma_j = f \circ \tilde{\gamma}_j$  is a path in  $\Omega$  from a to  $f(\tilde{z}_j)$ . Note that

$$f(\widetilde{z}_1) = h(\widetilde{g}(\widetilde{z}_1)) = h(\widetilde{g}(\widetilde{z}_2)) = f(\widetilde{z}_2),$$

so that  $\gamma_1, \gamma_2$  both end at the same point. Because  $\tilde{\gamma}_1, \tilde{\gamma}_2$  do not have the same endpoint but do have the same initial point, the paths  $\gamma_1, \gamma_2$ are not homotopic in  $\Omega$ . Hence,  $[\gamma_1 * \gamma_2^{-1}]$  is nontrivial in  $\pi(\Omega, a)$ . Since  $g_*$  is a monomophism, we conclude that  $[\gamma_1 * \gamma_2^{-1}]$  is also nontrivial in  $\pi(\Delta, a)$ , or  $\gamma_1$  and  $\gamma_2$  are not homotopic in  $\Delta$ . If  $\tilde{\delta}_j = \tilde{g} \circ \tilde{\gamma}_j$ , then

$$h \circ \widetilde{\delta}_{j} = h \circ \widetilde{g} \circ \widetilde{\gamma}_{j} = f \circ \widetilde{\gamma}_{j} = \gamma_{j}$$

Thus,  $\tilde{\delta}_j$  is a lift of  $\gamma_j$  via the covering  $h: (D,0) \to (\Delta, a)$  and 0 is the initial point of  $\tilde{\delta}_j$ . Because  $\gamma_1$  is not homotopic to  $\gamma_2$  in  $\Delta$ , it follows that  $\tilde{\delta}_1$  and  $\tilde{\delta}_2$  must have distinct endpoints. This contradicts the fact that both  $\tilde{\delta}_1$  and  $\tilde{\delta}_2$  end at  $\tilde{g}(\tilde{z}_1) = \tilde{g}(\tilde{z}_2)$ . This contradiction shows that  $\tilde{g}$  must be injective.

**Remark.** For multiply connected regions  $\Omega \subset \Delta$  there is a simple geometric criterion for  $g_*$  to be a monomorphism. The condition is that every hole in  $\Omega$  must contain at least one hole of  $\Delta$ .

#### 3. Hyperbolic curvature

We begin by recalling a few basic facts about the hyperbolic curvature. We refer the reader to [5], [6], and [7] for further details. Let  $\lambda_{\Omega}(z) |dz|$  be the hyperbolic metric on the hyperbolic region  $\Omega$ . If  $\gamma$  is a  $C^2$  curve in a hyperbolic region  $\Omega$  with parametrization z = z(t), then the hyperbolic curvature of  $\gamma$  at a point z = z(t) is given by

$$K_{\Omega}(z,\gamma) = \frac{1}{\lambda_{\Omega}(z)} \left[ K_{e}(z,\gamma) + 2Im \left\{ \frac{\partial \log \lambda_{\Omega}(z)}{\partial z} \frac{z'(t)}{|z'(t)|} \right\} \right],$$

where

$$K_{e}(z,\gamma) = \frac{1}{\left|z'(t)\right|} Im\left\{\frac{z''(t)}{z'(t)}\right\}$$

denotes the euclidean curvature of  $\gamma$  at z = z(t). Because the hyperbolic metric is invariant under holomorphic covering projections, the same is true of the hyperbolic curvature. That is,  $K_{\Omega}(z,\gamma) = K_{\Delta}(f(z), f \circ \gamma)$  if  $\Omega$  and  $\Delta$  are hyperbolic regions and  $f: \Omega \to \Delta$  is a holomorphic covering projection of  $\Omega$  onto  $\Delta$ .

**Lemma.** Suppose  $\Omega$  and  $\Delta$  are hyperbolic simply connected regions in C. If g is a conformal mapping of  $\Omega$  onto  $g(\Omega) \subset \Delta$ , then for any path  $\gamma$  in  $\Omega$ 

$$\max \left\{ K_{\Omega}\left( a,\gamma\right) ,2\right\} \leq \max \left\{ K_{\Delta}\left( g(a),g\circ\gamma\right) ,2\right\} .$$

**Proof.** Since the hyperbolic curvature is a conformal invariant,

$$K_{\Omega}(a,\gamma) = K_{g(\Omega)}(g(a), g \circ \gamma).$$

The Flinn-Osgood Monotonicity Theorem yields

$$\max\left\{K_{g(\Omega)}\left(g(a),g\circ\gamma\right),2\right\}\leq \max\left\{K_{\Delta}\left(g(a),g\circ\gamma\right),2\right\}$$

so this establishes the lemma.

We can now state our main result.

**Theorem 2.** Suppose  $\Omega$  and  $\Delta$  are hyperbolic regions,  $\Omega \subset \Delta$  and  $a \in \Omega$ . If  $g: \Omega \to \Delta$  is the inclusion map and  $g_*: \pi(\Omega, a) \to \pi(\Delta, a)$  is a monomorphism, then for any path  $\gamma$  through a,

$$\max \left\{ K_{\Omega}\left( a,\gamma\right) ,2\right\} \leq\max \left\{ K_{\Delta}\left( a,\gamma\right) ,2\right\} .$$

**Proof.** We need only consider the case in which  $K_{\Omega}(a, \gamma) \geq 2$ . Let  $f: (D,0) \to (\Omega,a)$  and  $h: (D,0) \to (\Delta,a)$  be holomorphic universal covering projections. Since  $g_*$  is a monomorphism, it follows from Theorem 1 that there is a conformal mapping  $\tilde{g}$  of (D,0) into itself such that  $g \circ f = h \circ \tilde{g}$ . Let  $\tilde{\gamma}$  be the lift of  $\gamma$  via f with initial point 0. Then  $\overline{\delta} = \tilde{g} \circ \tilde{\gamma}$  is the lift of  $\gamma$  via h with initial point 0. The invariance of hyperbolic curvature under holomorphic coverings implies that

$$K_{\Omega}\left(a,\gamma
ight)=K_{D}\left(0,\widetilde{\gamma}
ight),\ K_{\Delta}\left(a,\gamma
ight)=K_{D}\left(0,\widetilde{\delta}
ight),$$

so it suffices to show that

$$K_D(0,\widetilde{\gamma}) \leq K_D(0,\widetilde{\delta}).$$

Since  $\tilde{g}$  is a conformal mapping of (D,0) into itself and  $\tilde{g} \circ \tilde{\gamma} = \tilde{\delta}$ ,  $K_D(0,\tilde{\gamma}) \geq 2$ , this is a consequence of previous Lemma.

If  $\Omega$  is a simply connected subregion of a hyperbolic region  $\Delta$ , then  $\pi(\Omega, a) = 1$  for each  $a \in \Omega$ . Hence the induced group homomorphism  $g_* : \pi(\Omega, a) \to \pi(\Delta, a)$  is a monomorphism. Thus, we obtain the following result.

**Corollary.** Suppose  $\Delta$  is a hyperbolic region in C and  $\Omega$  is a simply connected subregion of  $\Delta$ . If  $\gamma$  is a path in  $\Omega$ , then for all  $z \in \gamma$ 

$$\max \left\{ K_{\Omega}\left(z,\gamma
ight),2
ight\} \leq \max \left\{ K_{\Delta}\left(z,\gamma
ight),2
ight\} .$$

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