

**AN EXTREME POSITIVE LINEAR OPERATOR  
ON  $M_n$  WHICH MAPS AN EXTREME  
POINT TO A NON-EXTREME POINT**

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**1. Introduction**

We denote  $M_n$  for the set of all  $n \times n$  complex matrices and  $E_n$  for the Hermitian part of  $M_n$ . Thus,  $E_n$  is the real ordered space of all  $n \times n$  Hermitian matrices with the positive cone consisting of all elements having nonnegative eigenvalues. A linear operator  $T$  from  $E_n$  to  $E_m$  is positive if  $T(P) \geq 0$  whenever  $P \geq 0$ , and  $T$  is extreme if  $S = \lambda T$  for some  $\lambda \geq 0$  whenever  $0 \leq S \leq T$ .

A linear operator which maps every extreme point  $xx^* \in E_n$  to either 0 or  $yy^* \in E_m$  will be called a 'simple' extreme linear operator.

It is proved in [1] and [2] that a positive linear operator on  $E_2$  or from  $E_2$  to  $E_3$  is extreme if and only if it is a simple extreme linear operator. In [3], it is proved that every positive linear operator on  $E_2$  is a sum of simple extreme positive linear operators.

Choi and Lam [4 ; Theorem 4.4] gave an example of a non-square extreme semidefinite biquadratic real polynomials. In the context of positive linear operators on  $M_n$ , 'simple' extreme operators correspond to (absolute) squares of bilinear homogeneous polynomials when we consider  $z^*T(xx^*)z$  be the equivalent semidefinite form corresponding to a positive linear operator  $T$  on  $M_n$ .

In this paper, we give an example of a non-square extreme semidefinite biquadratic in complex setting, i.e. a positive semidefinite complex polynomial which is not a sum of absolute squares of homogeneous bilinear forms. In our terms, it will be an example of an extreme positive linear operator which maps an extreme point of the positive cone in  $M_n$  to a non-extreme point in  $M_n$ .

We write

$$\mathbf{xx}^* = \begin{bmatrix} r_1^2 & r_1 r_2 e^{i\theta_1} & r_1 r_3 e^{i\theta_2} \\ & r_2^2 & r_2 r_3 e^{i\theta} \\ & & r_3^2 \end{bmatrix}$$

for  $\mathbf{x} \in C^3$  where  $\theta = \theta_2 - \theta_1$ , and let

$$T(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 I & r_1 r_3 (e_1 \cos \theta_2 + e_2 \sin \theta_2) + i r_2 r_3 (e_2 \cos \theta + e_1 \sin \theta) \\ & r_1^2 + r_2^2 \end{bmatrix}$$

where  $I$  is the identity in  $E_2$ , then it is routine to verify that  $T \geq 0$ . The linear operator defined above will always be denoted by  $T$  and all the linear operators we consider in this paper will be assumed to be from  $E_3$  to  $E_3$ .

Note that there is a natural extension of every positive linear operator on  $E_n$  to a positive linear operator on  $M_n$ .

Since  $T(e_3 e_3^T) = I_2$  where  $I_2$  is the identity in  $E_2$ ,  $T$  maps an extreme point to a non-extreme point. We have to prove that  $T$  is extreme. But, first we prove that  $T$  is not the sum of simple extreme positive linear operators, which gives us some assurance that  $T$  may be extreme.

## 2. T is not a Sum of Simple Extreme Operators

In the following, we will use  $E_{ii}$  for  $e_i e_i^T$ ,  $E_{kl}$  for  $(e_k e_l^T + e_l e_k^T)$ , and  $\tilde{E}_{kl}$  for  $i e_k e_l^T - i e_l e_k^T$ ,  $k \neq l$ .

LEMMA 2.1. *If  $S$  is a linear operator with  $0 \leq S \leq T$ , then  $S(E_{13})$ ,  $S(\tilde{E}_{13})$ ,  $S(E_{23})$ ,  $S(\tilde{E}_{23})$  are all of the form  $\begin{bmatrix} 0 & \mathbf{a} \\ & 0 \end{bmatrix}$  for some  $\mathbf{a} \in C^2$ .*

*Proof.* Note that we must have  $S(E_{11}) = t E_{33}$ ,  $S(E_{33}) = \begin{bmatrix} P & 0 \\ & 0 \end{bmatrix}$  for some  $t \geq 0$ ,  $0 \leq P \in E_2$ . Let

$$S(E_{13}) = \begin{bmatrix} A & \mathbf{a} \\ & \lambda \end{bmatrix}, \quad S(\tilde{E}_{13}) = \begin{bmatrix} B & \mathbf{b} \\ & \mu \end{bmatrix},$$

then

$$S \begin{bmatrix} 1 & 0 & r e^{i\theta} \\ & 0 & 0 \\ & & r^2 \end{bmatrix} = \begin{bmatrix} r^2 P + r(A \cos \theta + B \sin \theta) & r(a \cos \theta + b \sin \theta) \\ & t + r(\lambda \cos \theta + \mu \sin \theta) \end{bmatrix} \geq 0.$$

Hence  $t + r(\lambda \cos \theta + \mu \sin \theta) \geq 0$  for all  $r \geq 0, \theta \in \mathbf{R}$ , from which we obtain  $\lambda = \mu = 0$ . Also, from  $rP + A \cos \theta + B \sin \theta \geq 0$  for all  $r \geq 0$  and  $\theta \in \mathbf{R}$ , we obtain  $A = B = 0$ . A similar proof for  $S(E_{23})$  and  $S(\tilde{E}_{23})$  is omitted.

LEMMA 2.2. *If  $S$  is a simple extreme positive linear operator with  $0 \leq S \leq T$ , then*

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 \mathbf{qq}^* & r_3(\lambda r_1 e^{i\theta_2} + \mu r_2 e^{i\theta}) \mathbf{q} \\ |\lambda|^2 r_1^2 + |\mu|^2 r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) & \end{bmatrix}$$

where  $\mathbf{xx}^* = \begin{bmatrix} r_1^2 & r_1 r_2 e^{i\theta_1} & r_1 r_3 e^{i\theta_2} \\ & r_2^2 & r_2 r_3 e^{i\theta} \\ & & r_3^2 \end{bmatrix}$ ,  $\theta = \theta_2 - \theta_1$ ,  $f = \lambda \bar{\mu} + \bar{\lambda} \mu$ , and  $g = i(\lambda \bar{\mu} - \bar{\lambda} \mu)$  or

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 \mathbf{qq}^* & r_3(\lambda r_1 e^{-i\theta_2} + \mu r_2 e^{-i\theta}) \mathbf{q} \\ |\lambda|^2 r_1^2 + |\mu|^2 r_2^2 + r_1 r_2 (f' \cos \theta_1 + g' \sin \theta_1) & \end{bmatrix}$$

where  $f' = f, g' = -g$ .

*Proof.* Note the  $S(E_{33}) = \begin{bmatrix} \mathbf{qq}^* & 0 \\ & 0 \end{bmatrix}$  for some  $\mathbf{q} \in C^2$  since  $S(E_{33})$  is extreme by assumption. By Lemma 2.1,  $S(\mathbf{xx}^*)$  is of the form

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 \mathbf{qq}^* & r_1 r_3 (\mathbf{a} \cos \theta_2 + \mathbf{b} \sin \theta_2) + r_2 r_3 (\mathbf{c} \cos \theta + \mathbf{d} \sin \theta) \\ & f r_1^2 + g r_2^2 + r_1 r_2 (\gamma \cos \theta_1 + \delta \sin \theta_1) \end{bmatrix}.$$

Since  $S(\mathbf{xx}^*)$  is either 0 or extreme in  $E_3$  for all  $\mathbf{x} \in C^3$ , we have

$$(1) \quad \begin{aligned} & (f r_1^2 + g r_2^2 + r_1 r_2 (\gamma \cos \theta_1 + \delta \sin \theta_1)) \mathbf{qq}^* \\ & = \{r_1 (\mathbf{a} \cos \theta_2 + \mathbf{b} \sin \theta_2) + r_2 (\mathbf{c} \cos \theta + \mathbf{d} \sin \theta)\} \\ & \quad \cdot \{r_1 (\mathbf{a} \cos \theta_2 + \mathbf{b} \sin \theta_2) + r_2 (\mathbf{c} \cos \theta + \mathbf{d} \sin \theta)\}^*. \end{aligned}$$

By comparing the coefficients of  $r_1^2$ , we obtain  $f \mathbf{qq}^* = \cos^2 \theta_2 \mathbf{aa}^* + \sin^2 \theta_2 \mathbf{bb}^* + \sin \theta_2 \cos \theta_2 (\mathbf{ab}^* + \mathbf{ba}^*)$  for all  $\theta_2 \in \mathbf{R}$ . Thus, we have

$$(2) \quad \mathbf{aa}^* = \mathbf{bb}^* = f \mathbf{qq}^*, \quad \mathbf{ab}^* + \mathbf{ba}^* = 0.$$

Similarly, from the coefficients of  $r_2^2$ , we obtain

$$(3) \quad cc^* = dd^* = gqq^*, \quad cd^* + dc^* = 0$$

From (2) and (3), we have  $\mathbf{a} = \lambda\mathbf{q}$ ,  $\mathbf{b} = \alpha\mathbf{q}$ ,  $\mathbf{c} = \mu\mathbf{q}$ ,  $\mathbf{d} = \beta\mathbf{q}$  with  $|\lambda|^2 = |\alpha|^2 = f$ ,  $|\mu|^2 = |\beta|^2 = g$ . Let  $\alpha = \lambda e^{i\sigma}$ ,  $\beta = \mu e^{i\tau}$  and substitute these into (1) with  $r_2 = 0$  to obtain  $1 = |\cos\theta_2 + e^{i\sigma}\sin\theta_2|^2$  for all  $\theta_2 \in \mathbf{R}$ , i.e.  $1 = 1 + 2\cos\sigma\sin\theta_2\cos\theta_2$ . Hence, we have  $\cos\sigma = 0$ , i.e.  $e^{i\sigma} = \pm i$ . Similarly, with  $r_1 = 0$  in (1), we obtain  $e^{i\tau} = \pm i$ .

Consider the case with  $e^{i\sigma} = i$ ,  $e^{i\tau} = -i$ , then we have

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 \mathbf{qq}^* & r_3(\lambda r_1 e^{i\theta_2} + \mu r_2 e^{-i\theta}) \\ |\lambda|^2 r_1^2 + |\mu|^2 r_2^2 + r_1 r_2 (\cos\theta_1 + \delta \sin\theta_1) \end{bmatrix} \geq 0$$

Hence, (1) becomes  $|\lambda|^2 r_1^2 + |\mu|^2 r_2^2 + r_1 r_2 (\gamma \cos\theta_1 + \delta \sin\theta_1) = |\lambda r_1 e^{i\theta_2} + \mu r_2 e^{-i\theta}|^2 = |\lambda|^2 r_1^2 + |\mu|^2 r_2^2 + r_1 r_2 (\bar{\lambda} \mu e^{-i(\theta+\theta_2)} + \lambda \bar{\mu} e^{i(\theta+\theta_2)})$  for all  $\theta_1, \theta_2 \in \mathbf{R}$ , with  $\theta = \theta_2 - \theta_1$ . Therefore, we must have  $\lambda = \mu = \gamma = \delta = 0$ , i.e.  $S = 0$ . Similarly, we obtain  $S = 0$  when  $e^{i\sigma} = -i$ ,  $e^{i\tau} = i$ . Thus, for a nontrivial  $S$ , we must have  $e^{i\sigma} = e^{i\tau}$  which is either  $i$  or  $-i$  and the result follows.

**THEOREM 2.3.** *T is not the sum of simple extreme operators.*

*Proof.* Suppose  $T$  is a sum of simple extreme poitive linear operators, then by Lemma 2.2, we must have

$$T(\mathbf{xx}^*) = \sum_{i=1}^m \begin{bmatrix} r_3^2 \mathbf{q}_i \mathbf{q}_i^* & (\lambda_i r_1 e^{i\theta_2} + \mu_i r_2 e^{i\theta}) r_3 \mathbf{q}_i \\ |\lambda_i|^2 r_1^2 + |\mu_i|^2 r_2^2 + r_1 r_2 (\gamma_i \cos\theta_1 + \delta_i \sin\theta_1) \end{bmatrix} \\ + \sum_{j=m+1}^{m+n} \begin{bmatrix} r_3^2 \mathbf{q}_j \mathbf{q}_j^* & (\lambda_j r_1 e^{-i\theta_2} + \mu_j r_2 e^{-i\theta}) r_3 \mathbf{q}_j \\ |\lambda_j|^2 r_1^2 + |\mu_j|^2 r_2^2 + r_1 r_2 (\gamma'_j \cos\theta_1 + \delta'_j \sin\theta_1) \end{bmatrix}.$$

First, we consider the case with  $m \geq 1, n \geq 1$ . By comparing the

corresponding elements, we obtain

$$(4) \quad \sum_{i=1}^m \lambda_i \mathbf{q}_i + \sum_{j=m+1}^{m+n} \lambda_j \mathbf{q}_j = \mathbf{e}_1, \sum_{i=1}^m \lambda_i \mathbf{q}_i - \sum_{j=m+1}^{m+n} \lambda_j \mathbf{q}_j = -i\mathbf{e}_2$$

$$(5) \quad \sum_{i=1}^m \mu_i \mathbf{q}_i + \sum_{j=m+1}^{m+n} \mu_j \mathbf{q}_j = i\mathbf{e}_2, \sum_{i=1}^m \mu_i \mathbf{q}_i - \sum_{j=m+1}^{m+n} \mu_j \mathbf{q}_j = \mathbf{e}_1$$

$$(6) \quad \sum_{i=1}^m \mathbf{q}_i \mathbf{q}_i^* + \sum_{j=m+1}^{m+n} \mathbf{q}_j \mathbf{q}_j^* = I_2$$

$$(7) \quad \sum_{i=1}^{m+n} |\lambda_i|^2 = 1, \sum_{i=1}^{m+n} |\mu_i|^2 = 1$$

From (4), we obtain  $\sum_{i=1}^m \lambda_i \mathbf{q}_i = \frac{1}{2} \begin{pmatrix} 1 \\ -i \end{pmatrix} \equiv \xi_1$ ,  $\sum_{j=m+1}^{m+n} \lambda_j \mathbf{q}_j = \frac{1}{2} \begin{pmatrix} 1 \\ i \end{pmatrix} \equiv \xi_2$ . Note that  $\{\xi_1, \xi_2\}$  is linearly independent and hence we may write  $\mathbf{q}_j = a_{j1} \xi_1 + a_{j2} \xi_2$ ,  $j = 1, 2, \dots, m+n$ . Then the above relations become

$$\begin{aligned} & \left( \sum_{i=1}^m \lambda_i a_{i1} \right) \xi_1 + \left( \sum_{i=1}^m \lambda_i a_{i2} \right) \xi_2 = \xi_1, \\ & \left( \sum_{i=m+1}^{m+n} \lambda_i a_{i1} \right) \xi_1 + \left( \sum_{i=m+1}^{m+n} \lambda_i a_{i2} \right) \xi_2 = \xi_2 \end{aligned}$$

from which we obtain

$$(8) \quad \sum_{i=1}^m \lambda_i a_{i1} = \sum_{j=m+1}^{m+n} \lambda_j a_{j2} = 1, \sum_{i=1}^m \lambda_i a_{i2} = \sum_{j=m+1}^{m+n} \lambda_j a_{j1} = 0$$

Similary from (5), we obtain

$$(9) \quad \sum_{i=1}^m \mu_i a_{i1} = \sum_{j=m+1}^{m+n} \mu_j a_{j2} = 0, \sum_{i=1}^m \mu_i a_{i2} = - \sum_{j=m+1}^{m+n} \mu_j a_{j1} = 1$$

Note that  $q_{j1} = \frac{1}{2}(a_{j1} + a_{j2})$ ,  $q_{j2} = \frac{i}{2}(-a_{j1} + a_{j2})$  from  $\mathbf{q}_j = a_{j1} \xi_1 + a_{j2} \xi_2$  and hence, we have  $|q_{j1}|^2 = \frac{1}{4}(|a_{j1}|^2 + |a_{j2}|^2 + a_{j1} \bar{a}_{j1} + \bar{a}_{j1} a_{j2})$ ,  $|q_{j2}|^2 =$

$\frac{1}{4}(|a_{j1}|^2 + |a_{j2}|^2 - a_{j1}\bar{a}_{j2} - \bar{a}_{j1}a_{j2})$ . But from (6), we have  $\sum_{j=1}^{m+n} |q_{jk}|^2 = 1$  for  $k = 1, 2$ . Therefore, we have

$$(10) \quad \sum_{j=1}^{m+n} |a_{j1}|^2 + \sum_{j=1}^{m+n} |a_{j2}|^2 = 4, \quad \sum_{j=1}^{m+n} (a_{j1}\bar{a}_{j2} + \bar{a}_{j1}a_{j2}) = 0$$

Now, from (7),  $\sum_{i=1}^m |\lambda_i|^2 \leq 1$  and hence from (8), we must have  $\sum_{i=1}^m |a_{i1}|^2 \geq 1, \sum_{j=m+1}^{m+n} |a_{j2}|^2 \geq 1$ . Similarly, from (7) and (9) we obtain  $\sum_{i=1}^m |a_{i2}|^2 \geq 1, \sum_{j=m+1}^{m+n} |a_{j1}|^2 \geq 1$ . Applying these results to (10), we obtain

$$\sum_{j=1}^m |a_{j1}|^2 = \sum_{j=1}^m |a_{j2}|^2 = \sum_{j=m+1}^{m+n} |a_{j1}|^2 = \sum_{j=m+1}^{m+n} |a_{j2}|^2 = 1.$$

Therefore,  $(\bar{\lambda}_i)_{i=1}^m$  and  $(a_{j1})_{j=1}^m$  are  $m$ -vectors of norm less than or equal to 1 with inner product of value 1. Thus we must have  $(\bar{\lambda}_i) = (a_{j1})$ , but this would imply  $\lambda_i = 0$  for  $i \geq m + 1$  which is contrary to the second equality of (8).

Next, we consider the case with  $n = 0$ . Then the relations (4) must still hold without the second summation terms, i.e.  $\sum_{i=1}^m \lambda \mathbf{q}_i = \mathbf{e}_1, \sum_{i=1}^m \lambda \mathbf{q}_i = -ie_2$  which is certainly not possible. A similar argument can be applied so that  $m \neq 0$ .

### 3. The Positive Linear Operator T is Extreme

LEMMA 3.1. *Let*

$$S(\mathbf{x}\mathbf{x}^*) = \begin{bmatrix} dr_3^2 I & r_1 r_3 (\xi_1 \cos \theta_2 + \xi_2 \sin \theta_2) + r_2 r_3 (\eta_1 \cos \theta + \eta_2 \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix} \geq 0,$$

where  $\xi_i, \eta_i \in C^2$ . If  $\text{rank}(S(\mathbf{x}\mathbf{x}^*)) \leq 2$  for all  $\mathbf{x} \in C^3$  or if  $0 \leq S \leq T$ , then

- (1)  $\xi_1^* \xi_1 = \xi_2^* \xi_2 = ad, \xi_1^* \xi_2 + \xi_2^* \xi_1 = 0,$
- (2)  $\eta_1^* \eta_1 = \eta_2^* \eta_2 = bd, \eta_1^* \eta_2 + \eta_2^* \eta_1 = 0,$
- (3)  $\xi_1^* \eta_1 + \eta_1^* \xi_1 = \xi_2^* \eta_2 + \eta_2^* \xi_2 = fd,$
- (4)  $\xi_1^* \eta_2 + \eta_2^* \xi_1 = -(\xi_2^* \eta_1 + \eta_1^* \xi_2) = -gd.$

*Proof.* Note that  $\text{rank}(T(\mathbf{x}\mathbf{x}^*)) \leq 2$  since for each  $\mathbf{x} \neq 0$ ,  $T(\mathbf{x}\mathbf{x}^*)$  can be written as a sum of two extreme elements; one in  $E_2$  and the other in  $E_3$ . Hence, if  $0 \leq S \leq T$ , then  $\text{rank}(S(\mathbf{x}\mathbf{x}^*)) \leq 2$  for all  $\mathbf{x} \in C^3$ . Therefore, by [5; Theorem 4, p47] we have for all  $r_1, r_2 \geq 0, \theta_1, \theta_2 \in R$ ,

$$\begin{aligned} & d(ar_1^2 + br_2^2 + r_1r_2(f\cos\theta_1 + g\sin\theta_1)) \\ & = \{r_1(\xi_1^*\cos\theta_2 + \xi_2^*\sin\theta_2) + r_2(\eta_1^*\cos\theta + \eta_2^*\sin\theta)\} \\ & \cdot \{r_1(\xi_1\cos\theta_2 + \xi_2\sin\theta_2) + r_2(\eta_1\cos\theta + \eta_2\sin\theta)\}. \end{aligned}$$

We take  $r_1 = 1, r_2 = 0, \theta_1 = 0$  (i.e.  $\theta = \theta_2$ ) to obtain

$$ad = \xi_1^*\xi_1\cos^2\theta_2 + \xi_2^*\xi_2\sin^2\theta_2 + (\xi_1^*\xi_2 + \xi_2^*\xi_1)\sin\theta_2\cos\theta_2$$

for all  $\theta_2 \in \mathbf{R}$  and hence (1) follows. Similarly, with  $r_1 = 0, \theta_1 = 0$  we obtain (2).

Substituting (1) and (2) into the above equation, we get

$$\begin{aligned} d(f\cos\theta_1 + g\sin\theta_1) & = (\xi_1^*\eta_1 + \eta_1^*\xi_1)\cos\theta_2\cos\theta + (\xi_1^*\eta_2 + \eta_2^*\xi_1)\cos\theta_2\sin\theta \\ & + (\xi_2^*\eta_1 + \eta_1^*\xi_2)\sin\theta_2\cos\theta + (\xi_2^*\eta_2 + \eta_2^*\xi_2)\sin\theta_2\sin\theta. \end{aligned}$$

We take  $\theta = 0$  (i.e.  $\theta_1 = \theta_2$ ) and  $\theta = \frac{\pi}{2}$  to obtain (3) and (4).

**COROLLARY 3.2.** *Let*

$$S(\mathbf{x}\mathbf{x}^*) = \begin{bmatrix} r_3^2 D & r_1r_3(\xi_1\cos\theta_2 + \xi_2\sin\theta_2) + r_2r_3(\eta_1\cos\theta + \eta_2\sin\theta) \\ & ar_1^2 + br_2^2 + r_1r_2(f\cos\theta_1 + g\sin\theta_1) \end{bmatrix}$$

where  $D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}$  with  $d_1 \neq 0, d_2 \neq 0$ , and let  $U = \begin{bmatrix} U_0 & 0 \\ 0 & 1 \end{bmatrix}$  where  $U_0 = (\mathbf{u}_1, \mathbf{u}_2)$  is a unitary matrix. If  $0 \leq S \leq U \circ T$ , where  $U \circ T$  is the composition of  $U$  and  $T$ , then the following are satisfied.

- (1)  $\langle \xi_1, \xi_1 \rangle = \langle \xi_2, \xi_2 \rangle = a, \text{Re}\langle \xi_1, \xi_2 \rangle = 0$
- (2)  $\langle \eta_1, \eta_1 \rangle = \langle \eta_2, \eta_2 \rangle = b, \text{Re}\langle \eta_1, \eta_2 \rangle = 0$
- (3)  $\text{Re}\langle \xi_1, \eta_1 \rangle = \text{Re}\langle \xi_2, \eta_2 \rangle = \frac{1}{2}f$
- (4)  $\text{Re}\langle \xi_2, \eta_1 \rangle = -\text{Re}\langle \xi_1, \eta_2 \rangle = \frac{1}{2}g$

where  $\langle \mathbf{z}, \mathbf{w} \rangle = \frac{1}{d_1} \bar{z}_1 w_1 + \frac{1}{d_2} \bar{z}_2 w_2$  whenever  $\mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$ ,  $\mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$ . And if  $d_1 \neq 1, d_2 \neq 1$  then

$$(5) \quad \langle \langle \mathbf{u}_1 - \xi_1, \mathbf{u}_1 - \xi_1 \rangle \rangle = \langle \langle \mathbf{u}_2 - \xi_2, \mathbf{u}_2 - \xi_2 \rangle \rangle = 1 - a, \\ \operatorname{Re} \langle \langle \mathbf{u}_1 - \xi_1, \mathbf{u}_2 - \xi_2 \rangle \rangle = 0$$

$$(6) \quad \langle \langle i\mathbf{u}_2 - \eta_1, i\mathbf{u}_2 - \eta_1 \rangle \rangle = \langle \langle i\mathbf{u}_1 - \eta_2, i\mathbf{u}_1 - \eta_2 \rangle \rangle = 1 - b, \\ \operatorname{Re} \langle \langle i\mathbf{u}_2 - \eta_1, i\mathbf{u}_1 - \eta_2 \rangle \rangle = 0$$

$$(7) \quad \operatorname{Re} \langle \langle \mathbf{u}_1 - \xi_1, \mathbf{u}_2 - \xi_2 \rangle \rangle = \operatorname{Re} \langle \langle i\mathbf{u}_2 - \eta_1, i\mathbf{u}_1 - \eta_2 \rangle \rangle = \frac{1}{2} f$$

$$(8) \quad \operatorname{Re} \langle \langle \mathbf{u}_2 - \xi_2, i\mathbf{u}_2 - \eta_1 \rangle \rangle = -\operatorname{Re} \langle \langle \mathbf{u}_1 - \xi_1, i\mathbf{u}_1 - \eta_2 \rangle \rangle = \frac{1}{2} g,$$

where  $\langle \langle \mathbf{z}, \mathbf{w} \rangle \rangle = \frac{1}{1-d_1} \bar{z}_1 w_1 + \frac{1}{1-d_2} \bar{z}_2 w_2$ .

*Proof.* For  $\mathbf{z} \in C^3$  with  $\mathbf{z}^T = (z_1, z_2, z_3)$  where  $z_i \neq 0$ ,  $i = 1, 2, 3$ , we define

$$S_{\mathbf{z}} = \begin{bmatrix} a & \alpha & \beta \\ & b & \gamma \\ & & c \end{bmatrix} = \begin{bmatrix} |z_1|^2 a & z_1 \bar{z}_2 \alpha & z_2 \bar{z}_3 \beta \\ & |z_2|^2 b & z_2 \bar{z}_3 \gamma \\ & & |z_3|^2 c \end{bmatrix},$$

then  $S_{\mathbf{z}}$  is a one-to-one strongly positive linear operator, i.e. both  $S_{\mathbf{z}}$  and  $S_{\mathbf{z}}^{-1}$  are positive. Let  $\mathbf{d}^T = \left( \frac{1}{\sqrt{d_1}}, \frac{1}{\sqrt{d_2}}, 1 \right)$  and let  $S_1 = S_{\mathbf{d}} \circ S, T_1 = S_{\mathbf{d}} \circ U \circ T$ . Then we have  $0 \leq S_1 \leq T_1$  where

$$S_1(\mathbf{x}\mathbf{x}^*) = \begin{bmatrix} r_3^2 I & r_1 r_3 (\xi_1' \cos \theta_2 + \xi_2' \sin \theta_2) + r_2 r_3 (\eta_1' \mathbf{e}_1 \cos \theta + \eta_2' \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}$$

with  $\xi_j'^T = \left( \frac{\xi_{1j}}{\sqrt{d_1}}, \frac{\xi_{2j}}{\sqrt{d_2}} \right)$ ,  $\eta_j'^T = \left( \frac{\eta_{1j}}{\sqrt{d_1}}, \frac{\eta_{2j}}{\sqrt{d_2}} \right)$ . Now, we apply Lemma 3.1 to obtain  $\xi_1'^* \xi_1' = \xi_2'^* \xi_2' = a$ ,  $\xi_1'^* \xi_2' + \xi_2'^* \xi_1' = 0$ , etc which can be written as  $\langle \xi_1, \xi_1 \rangle = \langle \xi_2, \xi_2 \rangle = a$ ,  $\operatorname{Re} \langle \xi_1, \xi_2 \rangle = 0$  and so forth. Thus, the relations (1) through (4) are obtained.

To prove the relations (5) through (8), we consider  $R = U \circ T - S$  and repeat the above process.

LEMMA 3.3. *Let*

$$S(\mathbf{x}\mathbf{x}^*) = \begin{bmatrix} r_3^2 D & r_1 r_3 (\xi_1 \cos \theta_2 + \xi_2 \sin \theta_2) + r_2 r_3 (\eta_1 \cos \theta + \eta_2 \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}$$

where  $D = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix}$ . If  $0 \leq S \leq T$  then  $d_1 = d_2 = a$



*Proof.* Note that we have  $0 \leq \lambda S \leq T$  for all  $0 \leq \lambda \leq 1$  and hence if  $d_1 \neq 1, d_2 \neq 1$  then by Lamma 3.2, we have

$$\begin{aligned} \langle\langle \mathbf{e}_1 - \lambda \xi_1, \mathbf{e}_1 - \lambda \xi_1 \rangle\rangle &= \langle\langle \mathbf{e}_2 - \lambda \xi_2, \mathbf{e}_2 - \lambda \xi_2 \rangle\rangle = 1 - \lambda a, \\ \text{i.e., } \frac{|1 - \lambda z_1|^2}{1 - \lambda d_1} + \frac{\lambda^2 |w_1|^2}{1 - \lambda d_2} &= 1 - \lambda a \end{aligned}$$

where  $\xi_1^T = (z_1, w_1), \xi_2^T = (z_2, w_2)$  for all  $0 \leq \lambda \leq 1$ . Expanding this out, we have  $(1 - \lambda a)\{1 - \lambda(d_1 + d_2) + \lambda^2 d_1 d_2\} = (1 - \lambda d_2)\{1 + \lambda^2 |z_1|^2 - \lambda(z_1 + \bar{z}_1)\} + (1 - \lambda d_1)\{\lambda^2 |w_1|^2\}$ . By comparing the coefficients of  $\lambda$ , we have  $a + d_1 + d_2 = d_2 + z_1 + \bar{z}_1$  and from the coefficients of  $\lambda^2$ ,  $|z_1|^2 + |w_1|^2 + d_2(z_1 + \bar{z}_1) = d_1 d_2 + a d_1 + a d_2$ . From these relations, we get  $|z_1|^2 + |w_1|^2 = a d$ , and hence we have  $Re(z_1) = \frac{1}{2}(a + d_1) \leq |z_1| \leq \sqrt{a d_1}$  from which we obtain  $a = d_1, z_1 = \bar{z}_1 = |z_1|, w_1 = 0$ . Similarly, from  $\langle\langle \mathbf{e}_2 - \lambda \xi_2, \mathbf{e}_2 - \lambda \xi_2 \rangle\rangle = 1 - \lambda a$ , we obtain  $a = d_2$ .

Now, assume  $d_1 = 1, d_2 \neq 1$ . Then we have, for  $r_3 = 1$

$$\begin{aligned} S(\mathbf{x}\mathbf{x}^*) &= \begin{bmatrix} 1 & 0 & r_1(z_1 \cos \theta_2 + z_2 \sin \theta_2) + r_2(\alpha_1 \cos \theta + \alpha_2 \sin \theta) \\ d_2 & r_1(w_1 \cos \theta_2 + w_2 \sin \theta_2) + r_2(\beta_1 \cos \theta + \beta_2 \sin \theta) \\ & & a r_1^2 + b r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix} \\ &\leq \begin{bmatrix} 1 & 0 & r_1 \cos \theta_2 + i r_2 \sin \theta \\ & 1 & r_1 \sin \theta_2 + i r_2 \cos \theta \\ & & r_1^2 + r_2^2 \end{bmatrix} \end{aligned}$$

By looking at the first row of  $(T - S)(\mathbf{x}\mathbf{x}^*)$ , we find that  $z_1 = 1, z_2 = 0, \alpha_1 = 0, \alpha_2 = i$  since (1,1)-element is zero. Also, from  $S(\mathbf{x}\mathbf{x}^*) \geq 0$ , we find  $\xi_i^* \xi_i \leq 1, \eta_i^* \eta_i \leq 1, i = 1, 2$  and hence  $w_1 = \beta_2 = 0$ . Therefore, we have

$$S(\mathbf{x}\mathbf{x}^*) = \begin{bmatrix} 1 & 0 & r_1 \cos \theta_2 + i r_2 \sin \theta \\ & d_2 & r_1 w_2 \sin \theta_2 + r_2 \beta_1 \cos \theta \\ & & a r_1^2 + b r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}.$$

Now, we look at the relation

$$\begin{aligned} 0 &\leq \begin{bmatrix} d_2 & r_1 w_2 \sin \theta_2 + r_2 \cos \theta \\ & a r_1^2 + b r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix} \\ &\leq \begin{bmatrix} 1 & r_1 \sin \theta_2 + r_2 i \cos \theta \\ & r_1^2 + r_2^2 \end{bmatrix}. \end{aligned}$$

Substituting  $r_1 = 1, r_2 = 0, \theta_2 = \frac{\pi}{2}$ , we find that

$$0 \leq \begin{bmatrix} d_2 & w_2 \\ & a \end{bmatrix} \leq \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix}$$

and hence  $d_2 = w_2 = a$ . Similarly, with  $r_1 = 0, r_2 = 1, \theta = 0$ , we obtain  $d_2 = b, \beta_1 = bi$ . Thus, we have

$$\begin{aligned} 0 &\leq \begin{bmatrix} a & a(r_1 \sin \theta_2 + ir_2 \beta_1 \cos \theta) \\ & a(r_1^2 + r_2^2) + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix} \\ &\leq \begin{bmatrix} 1 & r_1 \sin \theta_2 + ir_2 \cos \theta \\ & r_1^2 + r_2^2 \end{bmatrix} \end{aligned}$$

from which we conclude  $f = g = 0$ . Finally, we now have

$$S(\mathbf{xx}^*) = \begin{bmatrix} 1 & 0 & r_1 \cos \theta_2 + ir_2 \sin \theta \\ & a & a(r_1 \sin \theta_2 + ir_2 \cos \theta) \\ & & a(r_1^2 + r_2^2) \end{bmatrix}.$$

But  $S(\mathbf{xx}^*) \geq 0$  for all  $r_1, r_2 \geq 0, \theta, \theta_2 \in \mathbf{R}$  and hence we must have  $a \geq 1$ , i.e.  $a = 1$ . Therefore,  $S = T$ .

**LEMMA 3.4.** *Let*

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 I & r_1 r_3 (\mathbf{u}_1 \cos \theta_2 + \mathbf{u}_2 \sin \theta_2) + ir_2 r_3 (\mathbf{u}_2 \cos \theta + \mathbf{u}_1 \sin \theta) \\ & r_1^2 + r_2^2 \end{bmatrix}$$

with  $\mathbf{u}_1^T = (\cos \tau, \sin \tau), \mathbf{u}_2^T = (-\sin \tau, \cos \tau)$  for some  $\tau \in \mathbf{R}$ , then there exists a unitary operator  $W$  such that  $S \circ W = T$ .

*Proof.* Let  $W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & e^{i2\tau} & 0 \\ 0 & 0 & e^{i\tau} \end{bmatrix}$  then

$$W \begin{bmatrix} a & \alpha & \beta \\ & b & d \\ & & c \end{bmatrix} W^* = \begin{bmatrix} a & \alpha e^{-2i\tau} & \beta i^{-i\tau} \\ & b & \gamma e^{i\tau} \\ & & c \end{bmatrix}$$

and hence we have

$$S(E_{13}) = T(\cos \tau E_{13} - \sin \tau \tilde{E}_{13}) = \begin{bmatrix} 0 & \cos \tau \mathbf{u}_1 - \sin \tau \mathbf{u}_2 \\ & 0 \end{bmatrix} = \begin{bmatrix} 0 & \mathbf{e}_1 \\ & 0 \end{bmatrix}.$$

Similarly, we get

$$\begin{aligned} S(\tilde{E}_{13}) &= \begin{bmatrix} 0 & \mathbf{e}_2 \\ & 0 \end{bmatrix}, \quad S(E_{23}) = \begin{bmatrix} 0 & i\mathbf{e}_2 \\ & 0 \end{bmatrix}, \\ S(\tilde{E}_{23}) &= \begin{bmatrix} 0 & i\mathbf{e}_1 \\ & 0 \end{bmatrix}, \quad S(E_{12}) = S(\tilde{E}_{12}) = 0. \end{aligned}$$

Therefore,  $S$  is of the desired form.

LEMMA 3.5. *Let*

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 P & r_1 r_3 (\xi_1 \cos \theta_2 + \xi_2 \sin \theta_2) + r_2 r_3 (\eta_1 \cos \theta + \eta_2 \sin \theta) \\ & a_1 r_1^2 + b r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}.$$

If  $0 \leq S \leq T$  then  $P = \lambda I$  for some  $0 \leq \lambda \leq 1$ .

*Proof.* Since  $P \geq 0$ , we can take an orthonormal set of eigenvectors of  $P$ . We may take  $\mathbf{u}_1, \mathbf{u}_2$  such that  $\mathbf{u}_1^T = (\cos \tau, e^{i\lambda} \sin \tau)$ ,  $\mathbf{u}_2^T = (-\sin \tau, e^{i\mu} \cos \tau)$ . From  $\mathbf{u}_1^* \mathbf{u}_2 = 0$ , we have  $e^{i\lambda} = e^{i\mu}$ . Let  $U_0 = (\mathbf{u}_1, \mathbf{u}_2)$ ,  $U = \begin{bmatrix} U_0 & 0 \\ & 1 \end{bmatrix}$ , then we have

$$\begin{aligned} U \circ T(\mathbf{xx}^*) &= \begin{bmatrix} r_3^2 I & r_1 r_3 (\mathbf{u}_1 \cos \theta_2 + \mathbf{u}_2 \sin \theta) + i r_2 r_3 (\mathbf{u}_2 \cos \theta + \mathbf{u}_1 \sin \theta) \\ & r_1^2 + r_2^2 \end{bmatrix} \\ U \circ S(\mathbf{xx}^*) &= \begin{bmatrix} r_3^2 D & r_1 r_3 (\xi'_1 \cos \theta_2 + \xi'_2 \sin \theta_2) + r_2 r_3 (\eta'_1 \cos \theta + \eta'_2 \sin \theta) \\ & a r_1^2 + b r_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}. \end{aligned}$$

Let  $V = \begin{bmatrix} 1 & 0 & 0 \\ 0 & e^{i\lambda} & 0 \\ 0 & 0 & 1 \end{bmatrix}$ , then

$$V \circ U \circ T(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 I & r_1 r_3 (\mathbf{u}'_1 \cos \theta_2 + \mathbf{u}'_2 \sin \theta_2) + i r_2 r_3 (\mathbf{u}'_2 \cos \theta + \mathbf{u}'_1 \sin \theta) \\ & r_1^2 + r_2^2 \end{bmatrix}$$

where  $\mathbf{u}_1'^T = (\cos \tau, \sin \tau)$ ,  $\mathbf{u}_2'^T = (-\sin \tau, \cos \tau)$ , and  $V \circ U \circ S(\mathbf{xx}^*) =$

$$\begin{bmatrix} r_3^2 D & r_1 r_3 (\xi_1'' \cos \theta_2 + \xi_2'' \sin \theta_2) + r_2 r_3 (\eta_1'' \cos \theta + \eta_2'' \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f' \cos \theta_1 + g' \sin \theta_1) \end{bmatrix}$$

Now, we apply Lemma 3.4 to  $V \circ U \circ T$  to find a unitary  $W$  such that  $V \circ U \circ T \circ W = T$ . Then with  $S' = V \circ U \circ S \circ W$ , we have  $0 \leq S' \leq T$  and

$$S'(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 D & r_1 r_3 (\xi_1''' \cos \theta_2 + \xi_2''' \sin \theta_2) + r_2 r_3 (\eta_1''' \cos \theta + \eta_2''' \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f'' \cos \theta_1 + g'' \sin \theta_1) \end{bmatrix}$$

Finally we apply Lemma 3.3 to conclude  $D = \lambda I$ . Therefore,  $P = U_0^* D U_0 = \lambda U_0^* U_0 = \lambda I$ .

LEMMA 3.6. *Let*

$$S(\mathbf{xx}^*) = \begin{bmatrix} dr_3^2 I & r_1 r_3 (\xi_1 \cos \theta_2 + \xi_2 \sin \theta_2) + r_2 r_3 (\eta_1 \cos \theta + \eta_2 \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}.$$

If  $0 \leq S \leq T$ , then  $S = dT$ .

*Proof.* We apply Lemma 3.1 to  $T - S$  where  $0 \leq T - S \leq T$  to obtain

- (1)  $(\mathbf{e}_1 - \xi_1)^*(\mathbf{e}_1 - \xi_1) = (\mathbf{e}_2 - \xi_2)^*(\mathbf{e}_2 - \xi_2) = (1 - a)(1 - d)$
- (2)  $(i\mathbf{e}_2 - \eta_1)^*(i\mathbf{e}_2 - \eta_1) = (i\mathbf{e}_1 - \eta_2)^*(i\mathbf{e}_1 - \eta_2) = (1 - b)(1 - d)$
- (3)  $(\mathbf{e}_1 - \xi_1)^*(i\mathbf{e}_2 - \eta_1) + (i\mathbf{e}_2 - \eta_1)^*(\mathbf{e}_1 - \xi_1) = -f(1 - d)$   
 $(\mathbf{e}_2 - \xi_2)^*(i\mathbf{e}_1 - \eta_2) + (i\mathbf{e}_1 - \eta_2)^*(\mathbf{e}_2 - \xi_2) = -f(1 - d)$
- (4)  $(\mathbf{e}_1 - \xi_1)^*(i\mathbf{e}_1 - \eta_2) + (i\mathbf{e}_1 - \eta_2)^*(\mathbf{e}_1 - \xi_1) = g(1 - d)$   
 $(\mathbf{e}_2 - \xi_2)^*(i\mathbf{e}_2 - \eta_1) + (i\mathbf{e}_2 - \eta_1)^*(\mathbf{e}_2 - \xi_2) = -g(1 - d)$ .

We expand (1) and apply Lemma 3.1 to  $S$  so that we have  $\mathbf{e}_1^* \xi_1 + \xi_1^* \mathbf{e}_1 = a + d$ ,  $\mathbf{e}_2^* \xi_2 + \xi_2^* \mathbf{e}_2 = a + d$ . Thus, we have  $\frac{1}{2}(a + d) = \operatorname{Re}(\xi_1^* \mathbf{e}_1) \leq |\xi_1^* \mathbf{e}_1| \leq |\xi_1| = \sqrt{ad}$ . Therefore, we obtain  $a = d$ ,  $\operatorname{Re}(\xi_1^* \mathbf{e}_1) = |\xi_1| = d$ , i.e.  $\frac{\xi_1}{|\xi_1|} = \mathbf{e}_1$ . From the second relation of (1), we obtain similarly that  $\frac{\xi_2}{|\xi_2|} = \mathbf{e}_2$ .

We repeat the same process on (2) to obtain  $b = d$ ,  $\mathbf{e}_1 = \frac{-i\eta_2}{|\eta_2|}$ ,  $\mathbf{e}_2 = \frac{-i\eta_1}{|\eta_1|}$ . Using these relations, we find from (3) that  $f = 0$  since  $\eta_1^* \eta_2 = 0$ . Similarly, from the second relation of (4), we have  $\frac{i}{|\eta_1|}(\eta_1^* \eta_1 - \eta_1^* \eta_1) = -g$  where we have used the relation  $\xi_2^* \eta_1 + \eta_1^* \xi_2 = gd$ . Thus,  $g = 0$  and hence  $S = dT$ .

**THEOREM 3.7.**  $T$  is an extreme poitive linear operator.

*Proof.* Let  $S$  be an arbitrary positive linear operator with  $0 \leq S \leq T$ . By Lemma 2.1,  $S$  is of the form

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 P & r_1 r_3 (\xi_1 \cos \theta_2 + \xi_2 \sin \theta_2) + r_2 r_3 (\eta_1 \cos \theta + \eta_2 \sin \theta) \\ & ar_1^2 + br_2^2 + r_1 r_2 (f \cos \theta_1 + g \sin \theta_1) \end{bmatrix}$$

Now, by Lemma 3.5,  $P = \lambda I$  for some  $0 \leq \lambda \leq 1$ . Therefore, by Lemma 3.6,  $S = \lambda T$ .

#### 4. Examples of Non-Extreme Positive Linear Operators

**EXAMPLE 4.1.** Let

$$S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 I & r_1 r_3 \cos \theta_2 - ir_2 r_2 \sin \theta \\ & r_1 r_3 \sin \theta_2 + ir_2 r_3 \cos \theta \\ & r_1^2 + r_2^2 \end{bmatrix},$$

then  $S$  is not extreme.

*Proof.* We difine

$$S_1(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 & ir_3^2 & r_3(r_1 e^{i\theta_2} - r_2 e^{i\theta}) \\ & r_3^2 & -ir_3(r_1 e^{i\theta_2} - r_2 e^{i\theta}) \\ & & r_1^2 + r_2^2 - 2r_1 r_2 \cos \theta_1 \end{bmatrix}$$

$$S_2(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 & -ir_3^2 & r_3(r_1 e^{i\theta_2} + r_2^{-i\theta}) \\ & r_3^2 & ir_3(r_1 e^{-i\theta_2} + r_2 e^{-i\theta}) \\ & & r_1^2 + r_2^2 + 2r_1 r_2 \cos \theta_1 \end{bmatrix}$$

then we clearly have  $S_1, S_2 \geq 0, S = \frac{1}{2}(S_1 + S_2)$ .

**EXAMPLE 4.2.** Let  $S(\mathbf{xx}^*) = \begin{bmatrix} r_1^2 + r_2^2 & 0 & r_1 r_3 \cos \theta_2 + ir_2 r_3 \sin \theta \\ & r_1^2 + r_2^2 & r_1 r_3 \sin \theta_2 + ir_2 r_3 \cos \theta \\ & & r_3^2 \end{bmatrix},$

then  $S$  is not extreme.

*Proof.* We define  $S_1(\mathbf{xx}^*) =$

$$\begin{bmatrix} r_1^2 + r_2^2 + 2r_1 r_2 \cos \theta_1 & i(r_1^2 - r_2^2) + 2r_1 r_2 \sin \theta_1 & r_1 r_3 e^{i\theta_2} + r_2 r_3 e^{i\theta} \\ & r_1^2 + r_2^2 - 2r_1 r_2 \cos \theta_1 & -i(r_1 r_3 e^{i\theta_2} - r_2 r_3 e^{i\theta}) \\ & & r_3^2 \end{bmatrix},$$

and  $S_2(\mathbf{xx}^*) =$

$$\begin{bmatrix} r_1^2 + r_2^2 - 2r_1r_2\cos\theta_1 & -i(r_1^2 - r_2^2) - 2r_1r_2\sin\theta_1 & r_1r_3e^{-i\theta_2} - r_2r_3e^{-i\theta} \\ & r_1^2 + r_2^2 + 2r_1r_2\cos\theta_1 & i(r_1r_3e^{-i\theta_2} - r_2r_3e^{-i\theta}) \\ & & r_3^2 \end{bmatrix}$$

then it is routine to verify that  $S_1, S_2 \geq 0$  and  $S = \frac{1}{2}S_1 + \frac{1}{2}S_2$ .

EXAMPLE 4.3. Let  $S(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 I & r_1r_3\cos\theta_2 + ir_2r_3\sin\theta \\ & ir_1r_3\sin\theta_2 + r_2r_3\cos\theta \\ & & r_1^2 + r_2^2 \end{bmatrix}$ , then

$S$  is not extreme.

*Proof.* We define

$$S_1(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 & r_3^2 & r_1e^{i\theta_2} + r_2e^{i\theta} \\ & r_3^2 & r_1e^{i\theta_2} + r_2e^{i\theta} \\ & & r_1^2 + r_2^2 + 2r_1r_2\cos\theta_1 \end{bmatrix},$$

$$S_2(\mathbf{xx}^*) = \begin{bmatrix} r_3^2 & -r_3^2 & r_1r_3e^{-i\theta_2} - r_2r_3e^{-i\theta} \\ & r_3^2 & -r_1r_3e^{-i\theta_2} + r_2r_3e^{-i\theta} \\ & & r_1^2 + r_2^2 - 2r_1r_2\cos\theta_1 \end{bmatrix}$$

then we clearly have  $S_1, S_2 \geq 0, S = \frac{1}{2}S_1 + \frac{1}{2}S_2$ .

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