# ON THE MINIMIZERS OF CERTAIN SINGULAR CONVEX FUNCTIONALS 

Hi Jun Choe

## 1.Introduction

In this paper the minimizers of singular functionals are considered. Suppose that $O$ is a bounded, open, convex subset of $R^{n}$ and $f: O \rightarrow R$ is smooth and uniformly strictly convex. Suppose further that $f \geq 0$ and

$$
\lim _{P \rightarrow \partial O} f(P)=\infty
$$

Set $f(P)=\infty$ for all $P \in R^{n} \backslash O$.
For example, $f$ can be one of the following:

$$
f(P)=\frac{1}{1-|P|^{2}}, O=\left\{P:|P|<1, P \in R^{n}\right\}
$$

or

$$
f(P)=\frac{1}{1-P_{1}^{2}}+\frac{1}{1-P_{2}^{2}}, O=(-1,1) \times(-1,1) .
$$

Consider the functional

$$
I(u)=\int_{\Omega} f(D u) d x
$$

defined for appropriate $u: \Omega \rightarrow R$, where $\Omega$ is a bounded, open subset of $R^{n}$ with smooth boundary.

Suppose that $u_{0} \in W^{1,2}(\Omega)$ and $I\left(u_{0}\right)<\infty$. Then $u_{0}$ is Lipschitz on the closure of $\Omega$ and it is relatively easy to see that there exists a unique $u \in u_{0}+W_{0}^{1,2}(\Omega)$ such that

$$
I(u) \leq I(v)
$$

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for all $v \in u_{0}+W_{0}^{1,2}(\Omega)$. Of course, $u$ is Lipschitz on the closure of $\Omega$ with $u=u_{0}$ on $\partial \Omega$ and minimizes $I$ among all such functions. The first question addressed is that of the regularity of $D u$.

Suppose that $u_{0}$ satisfies the following "bounded slope condition": there exists a constant $M$ such that for each point $x_{0} \in \partial \Omega$, there exist linear functions $\pi^{ \pm}$such that

$$
f\left(D \pi^{ \pm}\right) \leq M
$$

and

$$
\pi^{-}\left(x-x_{0}\right) \leq u_{0}(x)-u_{0}\left(x_{0}\right) \leq \pi^{+}\left(x-x_{0}\right)
$$

for all $x \in \partial \Omega$. Then it is shown that $u \in C^{1, \alpha}(\Omega)$ for any $\alpha \in(0,1)$. In fact, $f(D u)$ is bounded, and since $f$ is smooth, it follows that $u \in$ $C^{\infty}(\Omega)$.

This seems to be the first regularity result of this type, i.e., where the function $f$ exhibits this type singular behavior. The study of this question is motivated by models for hyperelastic materials (see Ball [1]) in which one is lead to consider minimizers of functionals over vector-valued mappings where the integrand exhibits a certain type of singular behavior.

In case $u_{0}$ does not satisfy the bounded slope condition given above, then the corresponding minimizer need not be in $C^{1}$. An example is given, in case $n=2$,

$$
f\left(P_{1}, P_{2}\right)=\left(1-P_{1}^{2}\right)^{-\alpha}+\left(1-P_{2}^{2}\right)^{-\alpha},(0<\alpha<1)
$$

with $\Omega$ an open ball in $R^{2}$. The minimizer fails to be in $C^{1}$ exactly on a line joining two points of $\partial \Omega$.

For systems, it is known that minimizers need not be $C^{1}$ even if $f$ is uniformly strictly convex on all of $R^{n}$ with bounded second derivatives. In case $n=1$ and $f$ depends on $u$ and $D u$, J. M. Ball and V. Mizel[2] have given examples showing that singularities can occur in the interior of $\Omega$. As far as we know the examples given here are the first in the higher-dimensional scalar case showing that singularities can occur in the interior even if $f$ depends only on $D u$.

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## 2. Existence and uniqueness

Suppose that $O$ is a bounded open convex subset of $R^{n}$ and that $f: O \rightarrow R$ is $C^{2}(O)$ and for some constant $\lambda>0$,

$$
\begin{equation*}
\frac{\partial^{2}}{\partial P_{i} \partial P_{j}} f(P) \xi_{i} \xi_{j} \geq \lambda|\xi|^{2} \tag{1}
\end{equation*}
$$

for all $P \in O, \xi \in R^{n}$. Suppose further that

$$
\begin{equation*}
\lim _{P \rightarrow \partial O} f(P)=\infty \tag{2}
\end{equation*}
$$

and $f(P)=\infty$ for all $P \in R^{n} \backslash O$.
Suppose $\Omega$ is an open connected subset of $R^{n}$. Suppose $u_{0} \in$ $W^{1,1}(\Omega ; R)$ and

$$
I\left[u_{0}\right]=\int_{\Omega} f\left(D u_{0}\right) d x<\infty
$$

Lemma 1. Let $K=\left\{v \in u_{0}+W^{1,1}(\Omega): I[v]<\infty\right\}$. Then $K$ is convex.
proof. Let $v_{1}, v_{2} \in K$, then for each $0 \leq t \leq 1, t v_{1}+(1-t) v_{2} \in$ $u_{0}+W_{0}^{1,1}$ and $I\left[v_{1}\right], I\left[v_{2}\right]<\infty$. Since $f$ is convex, we have

$$
\begin{aligned}
I\left[t v_{1}+(1-t) v_{2}\right] & =\int_{\Omega} f\left(t D v_{1}+(1-t) D v_{2}\right) d x \\
& \leq t \int_{\Omega} f\left(D v_{1}\right) d x+(1-t) \int_{\Omega} f\left(D v_{2}\right) d x<\infty
\end{aligned}
$$

So $t v_{1}+(1-t) v_{2} \in K$ and $K$ is convex.
Since $O$ is bounded, $K$ is a bounded subset of $W^{1, p}$ for all $1 \leq p \leq$ $\infty$. Since any convex function is bounded below, we assume that $f$ is nonnegative and $f(0)=0$ is the minimum of $f$ in $O$. The next theorem proves that $I$ is weakly sequentially lower semicontinuous in $W^{1,1}(\Omega)$.

THEOREM 1. Suppose that $u, u_{n} \in K$ for each $n$ and $u_{n} \rightharpoonup u$ weakly in $W^{1,1}(D)$ for each $D \subset \subset \Omega$. Then

$$
\begin{equation*}
I[u] \leq \lim _{n \rightarrow \infty} \inf I\left[u_{n}\right] \tag{3}
\end{equation*}
$$

proof. Let $d=\operatorname{dist}(D, \partial \Omega)$ and $\phi$ be a nonnegative smooth function supported in the unit ball such that

$$
\int_{R^{n}} \phi(x) d x=1
$$

Define $w_{\rho}(x)$ by

$$
\begin{equation*}
w_{\rho}(x)=\frac{1}{\rho^{n}} \int_{R^{n}} \phi\left(\frac{x-y}{\rho}\right) w(y) d y \tag{4}
\end{equation*}
$$

for each function $w \in W^{1,1}(\Omega)$ and $\rho>0$. Since $D u_{\rho} \rightarrow D u$ almost everywhere in $D$ as $\rho \rightarrow 0$ and $f$ is continuous, we have

$$
f\left(D u_{\rho}\right) \rightarrow f(D u)
$$

almost everywhere in $D$ as $\rho \rightarrow 0$. Since $f$ is nonnegative,

$$
I[u: D]=\int_{D} f(D u) d x \leq \lim _{\rho \rightarrow 0} \inf \int_{D} f\left(D u_{\rho}\right) d x
$$

by Fatou's lemma. From Jensen's inequality, we have

$$
f\left(D u_{\rho}\right) \leq f(D u)_{\rho}
$$

and

$$
f\left(D u_{n, \rho}\right) \leq f\left(D u_{\boldsymbol{n}}\right)_{\rho}
$$

on $D$, for each $n$ and $\rho<d$.
So we see that

$$
I\left[u_{n, \rho}: D\right] \leq \int_{D} f\left(D u_{n}\right)_{\rho} d x \leq \int_{\Omega} f\left(D u_{n}\right) d x
$$

Since $D u_{n} \rightarrow D u$ weakly in $L^{1}\left(D^{\prime}\right)$ for each $D \subset \subset D^{\prime} \subset \subset \Omega, D u_{n, \rho} \rightarrow$ $D u_{\rho}$ pointwisely in $D \subset \subset \Omega$ as $n \rightarrow \infty$. Thus, combining the previous inequalities, we have

$$
\begin{aligned}
I\left[u_{\rho}: D\right] & =\int_{D} f\left(D u_{\rho}\right) d x \\
& =\int_{D} \lim _{n \rightarrow \infty} \inf f\left(D u_{n, \rho}\right) d x \\
& \leq \lim _{n \rightarrow \infty} \inf \int_{D} f\left(D u_{n, \rho}\right) d x \\
& \leq \lim _{n \rightarrow \infty} \inf \int_{\Omega} f\left(D u_{n}\right) d x
\end{aligned}
$$

So we have

$$
\begin{aligned}
I[u: D] & =\int_{D} f(D u) d x \\
& \leq \lim _{\rho \rightarrow 0} \inf \int_{D} f\left(D u_{\rho}\right) d x \\
& \leq \lim _{n \rightarrow \infty} \inf \int_{\Omega} f\left(D u_{n}\right) d x .
\end{aligned}
$$

Since $D$ is chosen arbitrarily, we have

$$
I[u: \Omega]=I[u] \leq \lim _{n \rightarrow \infty} \inf I\left[u_{n}\right]
$$

and $I$ is lower semicontinuous.
Now we prove the existence and uniqueness of the minimizer. The theorem follows essentially from the weak compactness of the bounded subset of $W^{1,2}(\Omega)$.

Theorem 2. Let $\mu=\inf _{v \in K} I[v]$. Then there is a unique $u \in K$ such that

$$
I[u]=\mu .
$$

proof. We note that $\mu$ is a finite number, since $I$ is convex and $u_{0} \in K$. Let $\left\{u_{n}\right\}$ be a sequence in $K$ such that $I\left[u_{n}\right] \rightarrow \mu$ as $n \rightarrow \infty$. Since $K$ is a bounded subset of $W^{1,2}(\Omega)$, there is a subsequence $\left\{u_{n_{k}}\right\}$
such that $u_{n_{k}} \rightharpoonup u$ weakly in $W^{1,2}(\Omega)$ for some $u \in W^{1,2}(\Omega)$ as $k \rightarrow \infty$. We see that $u-u_{0} \in W_{0}^{1,2}(\Omega)$. From the lower semicontinuity of $I$ we have

$$
I[u] \leq \lim _{k \rightarrow \infty} \inf I\left[u_{n_{k}}\right]=\mu
$$

So $I[u]=\mu$ from the fact that $\mu=\inf _{v \in K} I[v]$.
We prove the uniqueness by using the strict convexity of $f$ and a variational inequality which the minimizer $u$ satisfies. First we show that $u$ satisfies a variational inequality. Suppose that $v \in K$. Then $I[v]<\infty$. Since $f$ is convex,

$$
f(D v(x))-f(D u(x)) \geq \frac{f(D u(x)+t(D v(x)-D u(x)))-f(D u(x))}{t}
$$

for all $x \in \Omega$ and $0<t \leq 1$. Moreover we see that

$$
F_{t}(x)=\frac{f(D u(x)+t(D v(x)-D u(x)))-f(D u(x))}{t}
$$

is monotone decreasing as $t \rightarrow 0$ and $F_{t}(x)$ converges to $f_{P_{i}}(D u(x))$ $\left(D_{i} v-D_{i} u\right)$ for almost all $x \in \Omega$. Since $F_{t}(x) \leq f(D v(x))-f(D u(x))$ for all $x \in \Omega$ and $F_{t}$ converges to $f_{P_{i}}(D u(x))\left(D_{i} v-D_{i} u\right)$ monotonically as $t \rightarrow 0$, by the monotone convergence theorem, we have

$$
\lim _{t \rightarrow 0} \int_{\Omega} F_{t}(x) d x=\int_{\Omega} f_{P_{i}}(D u)\left(D_{i} v-D_{i} u\right) d x
$$

Since $I[v]-I[u] \geq \int_{\Omega} F_{t}(x) \geq 0$ for all $0<t \leq 1$,

$$
I[v]-I[u] \geq \int_{\Omega} f_{P_{i}}(D u(x))\left(D_{i} v-D_{i} u\right) d x \geq 0
$$

for all $v \in K$.
Let $I[u]=I[v]$ for some $v \in K$. Then since $f$ is strictly convex, we
have

$$
\begin{aligned}
0= & I[u]-I[v] \\
= & \int_{\Omega}[f(D u)-f(D v)] d x \\
= & \int_{\Omega} f_{P_{i}}(D u)\left(D_{i} v-D_{i} u\right) d x \\
& +\int_{\Omega} \int_{0}^{1}(1-t) f_{P_{i} P_{j}}(D u+t(D v-D u)) d t \\
& \times\left(D_{i} v-D_{i} u\right)\left(D_{j} v-D_{j} u\right) d x \\
\geq & \frac{1}{2} \lambda \int_{\Omega}|D u-D v|^{2} d x
\end{aligned}
$$

Since $u-v \in W_{0}^{1,2}(\Omega)$, from Sobolev's inequality,

$$
\|u-v\|_{2} \leq C\|D u-D v\|_{2}=0
$$

for some $C$, where $\|u\|_{2}$ is $L^{2}(\Omega)$ norm of $u$.

## 3. Approximation

We approximate $f$ with functions $f^{\rho}$ which grow quadratically by using the implicit function theorem.

Let $E_{\rho}=\left\{P \in R^{n}: f(P) \leq \rho\right\}$. Then $E_{\rho}$ is a strictly convex, bounded and closed subset of $R^{n}$.

Now we construct a uniformly strictly convex function with quadratic growth. First we recall the Implicit Function Theorem.

LEMMA 2. Let $g \in C^{2}$ and $D_{y} g\left(x_{0}, y_{0}\right) \neq 0$. Then there exists a function $h(y)$ such that $x_{0}=h\left(y_{0}\right)$ and $g(h(y), y)=0$ in some neighborhood $U$ of $y_{0}$. Moreover $h \in C^{2}(U)$.

The following theorem is fundamental to the approximation.
THEOREM 3. Suppose $g \in C^{2}\left(R^{n}\right)$ and

$$
\begin{equation*}
g_{P_{i} P_{j}}(P) \xi_{i} \xi_{j} \geq \nu|\xi|^{2} \tag{5}
\end{equation*}
$$

for some $\nu>0$ and all $P, \xi \in R^{n}$. Suppose further that $g(0)=0$ is the minimum. Define by $r(P)>0$

$$
g\left(\frac{P}{\sqrt{r(P)}}\right)=c>0
$$

for all $P \in R^{n} \backslash\{0\}$. Then $r(P) \in C^{2}\left(R^{n} \backslash\{0\}\right)$ and

$$
\begin{equation*}
\nu_{1}|\xi|^{2} \leq r_{P_{i} P_{j}}(P) \xi_{i} \xi_{j} \leq \nu_{2}|\xi|^{2} \tag{6}
\end{equation*}
$$

for all $P, \xi \in R^{n} \backslash\{0\}$. Moreover $\nu_{1}$ and $\nu_{2}$ depend only on $c$ and $\nu$.
proof. We see that $g$ is radially strictly increasing. Since we are assuming $r>0, r(P)$ is well defined for all $P \in R^{n} \backslash\{0\}$. By differentiating $g\left(\frac{P}{\sqrt{r}}\right)$ with respect to $r$, we have

$$
\frac{\partial}{\partial r} g\left(\frac{P}{\sqrt{r}}\right)=g_{P_{i}}\left(\frac{P}{\sqrt{r}}\right) P_{i}\left(-\frac{1}{2 \sqrt{r}^{3}}\right) \neq 0
$$

for all $P \in R^{n} \backslash\{0\}$. So, from Lemma $2, r(P) \in C^{2}$ and

$$
g\left(\frac{P}{\sqrt{r(P)}}\right)=c .
$$

Define

$$
g_{i}=g_{P_{i}}\left(\frac{P}{\sqrt{r}}\right), g_{i k}=g_{P_{i} P_{k}}\left(\frac{P}{\sqrt{r}}\right), r_{i}=r_{P_{i}}\left(\frac{P}{\sqrt{r}}\right), r_{i k}=r_{P_{i} P_{k}}\left(\frac{P}{\sqrt{r}}\right) .
$$

We see that

$$
\frac{\partial}{\partial P_{i}} g\left(\frac{P}{\sqrt{r}}\right)=g_{i} \frac{1}{\sqrt{r}}-\frac{1}{2} g_{j} P_{j} \frac{r_{i}}{\sqrt{r}^{3}}=0
$$

and hence that

$$
r_{i}=2 \frac{g_{i} r}{g_{j} P_{j}} .
$$

Setting $T=g_{j} P_{j}$ and differentiating with respect to $P_{k}$,

$$
\begin{aligned}
\frac{1}{2} r_{i k} T^{2}= & T g_{i k} \sqrt{r}-\frac{1}{2} T g_{i l} P_{l} \frac{r_{k}}{\sqrt{r}}+T g_{i} r_{k} \\
& -g_{i} g_{j k} P_{j} \sqrt{r}+\frac{1}{2} g_{j l} P_{l} g_{i} P_{j} \frac{r_{k}}{\sqrt{r}}-r g_{i} g_{k}
\end{aligned}
$$

Substituting $r_{k}=\frac{2 g_{k} r}{T}$, we have

$$
\begin{aligned}
\frac{1}{2} T^{2} r_{i k} \xi_{i} \xi_{k}= & T \sqrt{r} g_{i k} \xi_{i} \xi_{k}-\sqrt{r} g_{i l} P_{l} g_{k} \xi_{i} \xi_{k}+2 r g_{i} g_{k} \xi_{i} \xi_{k} \\
& -\sqrt{r} g_{i} g_{j k} P_{j} \xi_{i} \xi_{k}+\frac{\sqrt{r}}{T} g_{j l} P_{l} P_{j} g_{i} g_{k} \xi_{i} \xi_{k}-r g_{i} g_{k} \xi_{i} \xi_{k}
\end{aligned}
$$

Let $S=g_{i} \xi_{i}$. Then, by using $g_{i k}=g_{k i}$, we have

$$
r_{i k} \xi_{i} \xi_{k}=2 \frac{\sqrt{r}}{T} g_{i k}\left(\xi_{i}-\frac{S}{T} P_{i}\right)\left(\xi_{k}-\frac{S}{T} P_{k}\right)+2 r \frac{S^{2}}{T^{2}}
$$

We have for some $M_{1}, M_{2}$ and $M_{3}$, which depend only on $c$,

$$
\left|g_{i}\right|,\left|g_{i k}\right| \leq M_{3}
$$

and

$$
0<M_{1} \leq \frac{T}{\sqrt{r}} \leq M_{2}
$$

for all $P \in R^{n} \backslash\{0\}$. Thus we have

$$
r_{i k} \xi_{i} \xi_{k} \leq \nu_{2}|\xi|^{2}
$$

for all $P, \xi \in R^{n}$ where $\nu_{2}$ depends on $c$.
Now we define $h(\xi)$ and $\bar{h}(\xi)$ by

$$
h(\xi)=r_{i k} \xi_{i} \xi_{k}=|\xi|^{2} \bar{h}(\xi)
$$

Since $g$ is strictly convex,

$$
\bar{h} \geq \frac{2}{M_{2}} \nu\left|\frac{\xi}{|\xi|}-\frac{S}{T} \frac{P}{|\xi|}\right|^{2}+\frac{2}{M_{2}^{2}}\left(\frac{S}{|\xi|}\right)^{2}
$$

Let $m=\max _{g(P)=c}|P|$. Then

$$
\frac{|S P|}{|\xi| T} \leq \frac{S m}{|\xi| M_{1}}
$$

for all $P \in R^{n} \backslash\{0\}$. If $\frac{S}{|\xi|} \geq \frac{M_{1}}{2 m}$, then

$$
\bar{h} \geq \frac{M_{1}^{2}}{2 m^{2} M_{2}^{2}}
$$

On the other hand, if $\frac{S}{|\xi|} \leq \frac{M_{1}}{2 m}$, then

$$
\bar{h} \geq \frac{\nu}{M_{2}} .
$$

Thus

$$
h(\xi) \geq \nu_{1}|\xi|^{2},
$$

where $\nu_{1}=\min \left(\frac{M_{1}^{2}}{2 m^{2}}, \frac{\nu}{M_{2}}\right)$, which depends only on $\nu$ and $c$.
Now we approximate $f$. Let $\psi: R \rightarrow R$ be $C^{\infty}$ such that

$$
\psi(t)=1
$$

for $t \in(-\infty, 0]$ and

$$
\psi(t)=0
$$

for $t \in[1, \infty)$.
Define $r(P)$ by

$$
f\left(\frac{P}{\sqrt{r(P)}}\right)=\rho+\frac{\delta}{2} .
$$

From the definition of $E_{\rho+\frac{\delta}{2}}$ and $r(P)$, we see that

$$
\partial E_{\rho+\frac{\delta}{2}}=\{P: r(P)=1\}
$$

and $r(P) \in C^{2}$. Let $b(P)=(r(P)-1)^{+}$. Then

$$
b(P)=0
$$

if $P \in E_{\rho+\frac{\delta}{2}}$ and

$$
b(P)=r(P)-1
$$

if $P \in R^{n} \backslash E_{\rho+\frac{\delta}{2}}$.
Now we regularize $b(P)$ with $\epsilon^{\prime}$ as (4) and get $b_{\epsilon^{\prime}}(P) \in C^{\infty}$. Then we see that $b_{\epsilon^{\prime}}(P)$ satisfies the same growth condition as $r(P)$ if $|P|$ is large enough. So $b_{\epsilon^{\prime}}(P)$ grows quadratically. Moreover $b_{\epsilon^{\prime}}(P)=0$ for $P \in E_{\rho}$ and

$$
\nu_{1}|\xi|^{2} \leq b_{\epsilon^{\prime}, P_{i} P_{j}}(P) \xi_{i} \xi_{j} \leq \nu_{2}|\xi|^{2}
$$

for all $P \in R^{n} \backslash E_{\rho+\delta}$ for some $\nu_{1}$ and $\nu_{2}$ if $\epsilon^{\prime}$ is small enough.
THEOREM 4. Suppose that $f^{\rho}$ is defined by

$$
\begin{equation*}
f^{\rho}(P)=\psi\left(\frac{f(P)-\rho-\delta}{\delta}\right) f(P)+\mu b_{\epsilon^{\prime}}(P) \tag{7}
\end{equation*}
$$

for all $P \in R^{n}$ and for some $\mu>0$. If $\mu$ is sufficiently large, then $f^{\rho}$ satisfies the following ellipticity condition

$$
\begin{equation*}
\lambda_{1}|\xi|^{2} \leq f_{P_{i} P_{j}}^{\rho}(P) \xi_{i} \xi_{j} \leq \lambda_{2}|\xi|^{2} \tag{8}
\end{equation*}
$$

for all $P, \xi \in R^{n}$ and for some $\lambda_{1}, \lambda_{2}>0$ and $f^{\rho}(P)=f(P)$ for $P \in E_{\rho}$. proof. We note that $b_{\epsilon^{\prime}}(P)=0$ and $\psi\left(\frac{f(P)-\rho-\delta}{\delta}\right)=1$ for $P \in E_{\rho}$. So $f^{\rho}(P)=f(P)$ for $P \in E_{\rho}$. By differentiating $f^{\rho}$ with respect to $P_{i}$, we have

$$
f_{P_{i}}^{\rho}=\frac{1}{\delta} \psi_{t} f f_{P_{i}}+\psi f_{P_{i}}(P)+\mu b_{\epsilon^{\prime}, P_{i}}(P)
$$

and

$$
\begin{aligned}
f_{P_{i} P_{j}}^{\rho}=\frac{1}{\delta^{2}} \psi_{t t} f f_{P_{i}} f_{P_{j}} & +\frac{1}{\delta} f \psi_{t} f_{P_{i} P_{j}}+\frac{2}{\delta} \psi_{t} f_{P_{i}} f_{P_{j}} \\
& +\psi f_{P_{i} P_{j}}+\mu b_{\epsilon^{\prime}, P_{i} P_{j}}(P)
\end{aligned}
$$

Since $b_{\epsilon^{\prime}}$ is convex,

$$
b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j} \geq 0
$$

for all $P \in R^{n}$. Let $P \in E_{\rho+\delta}$. Then $\psi=1, \psi_{t}=0$ and $\psi_{t t}=0$. Hence we have

$$
f_{P_{i} P_{j}}^{\rho}(P) \xi_{i} \xi_{j}=f_{P_{i} P_{j}} \xi_{i} \xi_{j}+\mu b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j} \geq \lambda|\xi|^{2}
$$

for all $\xi \in R^{n}$. Since $\left|f_{P_{i} P_{j}}(P)\right| \leq M$ for some $M$ and for all $P \in E_{\rho+\delta}$, we have

$$
f_{P_{i} P_{j}} \xi_{i} \xi_{j} \leq C|\xi|^{2}
$$

for all $\xi \in R^{n}$, where $C$ depends on $\mu$ and $M$.
Let $P \in E_{\rho+2 \delta} \backslash E_{\rho+\delta}$. Then we have

$$
\nu_{1}|\xi|^{2} \leq b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j} \leq \nu_{2}|\xi|^{2}
$$

for all $\xi \in R^{n}$. If $P \in E_{\rho+2 \delta} \backslash E_{\rho+\delta}$, then

$$
\left|(\psi f)_{P_{i} P_{j}}\right| \leq M
$$

for some $M$. Hence if $\mu$ is large enough, we have that for all $P \in$ $E_{\rho+2 \delta} \backslash E_{\rho+\delta}$

$$
\mu b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j}+(\psi f)_{P_{i} P_{j}} \xi_{i} \xi_{j} \geq C_{2}|\xi|^{2}
$$

for some $C_{2}$ which depends on $M$ and $\mu$.
Since $\mu b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j} \leq \mu \nu_{2}|\xi|^{2}$ and $\left|(\psi f)_{P_{i} P_{j}}\right| \leq M$ for all $P \in$ $E_{\rho+\delta} \backslash E_{\rho}$, we have

$$
\mu b_{\epsilon^{\prime}, P_{i} P_{j}} \xi_{i} \xi_{j}+(\psi f)_{P_{i} P_{j}} \xi_{i} \xi_{j} \leq C_{3}|\xi|^{2}
$$

where $C_{3}$ depends on $M$ and $\mu$.
If $P \in R^{n} \backslash E_{\rho+2 \delta}$, then $\psi=0$ and $f^{\rho}(P)=\mu b_{\epsilon^{\prime}}(P)$. Hence by Theorem 3 we have

$$
f_{P_{i} P_{j}}^{\rho} \xi_{i} \xi_{j} \leq \mu \nu_{2}|\xi|^{2}
$$

for all $P, \xi \in R^{n}$.

## 4. Regularity

By using a maximum principle and existence theorem for quasilinear elliptic equations due to P. Hartman and G. Stampaccia [3] we obtain $C^{1, \alpha}(\bar{\Omega})$ regularity for a minimizer if $\left(u_{0}, \partial \Omega\right)$ satisfies a certain bounded slope condition.

THEOREM 5. Suppose that $\Omega$ is a bounded open connected subset of $R^{n}$ with $\partial \Omega \in C^{1,1}$. Moreover suppose that $u_{0}$ satifies the following "bounded slope condition" : there exists a constant $M$ such that for each point $x_{0} \in \partial \Omega$, there exist linear functions $\pi_{x_{0}}^{ \pm}$such that

$$
f\left(D \pi_{x_{0}}^{ \pm}\right) \leq M
$$

and

$$
\begin{equation*}
\pi_{x_{0}}^{-}\left(x-x_{0}\right) \leq u_{0}(x)-u_{0}\left(x_{0}\right) \leq \pi_{x_{0}}^{+}\left(x-x_{0}\right) \tag{9}
\end{equation*}
$$

for all $x \in \partial \Omega$. Then the minimizer $u$ with respect $K$ is $C^{1, \alpha}(\bar{\Omega})$ for all $0 \leq \alpha<1$.
J. Moser observed in [4] that if $v$ is a solution of a linear elliptic equation

$$
\begin{equation*}
D_{i}\left(a_{i j}(x) D_{j} u\right)=0 \tag{10}
\end{equation*}
$$

with $a_{i j}$ measurable and

$$
c_{0}|\xi|^{2} \leq a_{i j} \xi_{i} \xi_{j} \leq c_{1}|\xi|^{2}
$$

for some positive constants $c_{0}$ and $c_{1}$, then for any convex function $h, h(u)$ is a subsolution of (10). We prove a similar theorem for the derivatives of solutions of quasilinear elliptic equations.

THEOREM 6. Suppose that $A_{i} \in C^{1}\left(R^{n}\right)$ satisfies the following ellipticity condition :

$$
\begin{equation*}
c_{0}|\xi|^{2} \leq A_{i, P_{j}}(P) \xi_{i} \xi_{j} \leq c_{1}|\xi|^{2} \tag{11}
\end{equation*}
$$

for all $P, \xi \in R^{n}$ and for some positive constants $c_{0}$ and $c_{1}$. Moreover suppose that $g: R \rightarrow R$ is nonincreasing and in $C^{1}$.

Let $v \in W^{1,2}(\Omega)$ be a solution to the quasilinear equation

$$
\begin{equation*}
D_{i}\left(A_{i}(D v)\right)+g(v)=0 . \tag{12}
\end{equation*}
$$

Suppose that $G \in C^{2}\left(R^{n} ; R\right)$ is a convex function with $G(0)=0$ as minimum. Then $G(D v)$ is a subsolution to

$$
\begin{equation*}
D_{i}\left(A_{i, P_{j}}(D v) D_{j} w\right)=0 \tag{13}
\end{equation*}
$$

proof. First we prove that $v \in W_{l o c}^{2,2}(\Omega)$ by difference quotient argument.

Let $\Omega^{\prime} \subset \subset \Omega$ and $d<\operatorname{dist}\left(\Omega^{\prime}, \partial \Omega\right)$. Let $h \leq \frac{1}{4} d$ and $e_{k}$ be $k$-th direction unit coordinate vector for $k=1, \ldots, n$. Let $\psi \in C^{\infty}(\Omega)$, $|D \psi| \leq \frac{c}{d}$ for some $c$ and $\operatorname{supp}(\psi) \pm \frac{1}{4} d e_{k} \subset \Omega$. We apply $\left(v\left(x+h e_{k}\right)-\right.$ $v(x)) \psi^{2}(x)$ as a test function to (12). Hence we have that

$$
\begin{gathered}
\int_{\Omega}\left[A_{i}\left(D v\left(x+h e_{k}\right)\right)-A_{i}(D v(x))\right] D_{i}\left[\left(v\left(x+h e_{k}\right)-v(x)\right) \psi^{2}(x)\right] d x \\
-\int_{\Omega}\left[g\left(v\left(x+h e_{k}\right)\right)-g(v(x))\right]\left[\left(v\left(x+h e_{k}\right)-v(x)\right) \psi^{2}(x)\right] d x=0
\end{gathered}
$$

for all $k=1, \ldots, n$. Since $g$ is nonincreasing, we have that

$$
\left[g\left(v\left(x+h e_{k}\right)\right)-g(v(x))\right]\left[v\left(x+h e_{k}\right)-v(x)\right] \psi^{2}(x) \leq 0
$$

for all $x \in \Omega$ and $k=1, \ldots, n$. By using the ellipticity of $A_{i}$ and the equation we have

$$
\begin{aligned}
& \frac{c_{0}}{h^{2}} \int_{\Omega}\left|D v\left(x+h e_{k}\right)-D v(x)\right|^{2} \psi^{2} d x \\
\leq & \frac{1}{h^{2}} \int_{\Omega}\left[A_{i}\left(D v\left(x+h e_{k}\right)\right)-A_{i}(D v(x))\right]\left[D_{i} v\left(x+h e_{k}\right)-D_{i} v(x)\right] \psi^{2} d x \\
\leq & -\frac{2}{h^{2}} \int_{\Omega}\left[A_{i}\left(D v\left(x+h e_{k}\right)\right)-A_{i}(D v(x))\right] \\
& \times\left[v\left(x+h e_{k}\right)-v(x)\right] D_{i} \psi(x) \psi(x) d x \\
\leq & 2 c_{1} \int_{\Omega}\left|\frac{D v\left(x+h e_{k}\right)-D v(x)}{h}\right|\left|\frac{v\left(x+h e_{k}\right)-v(x)}{h}\right||D \psi(x)| \psi(x) d x
\end{aligned}
$$

Now by using Holder's inequality on the right hand side of the last inequality, we have

$$
\int_{\Omega^{\prime}}\left|\frac{D v\left(x+h e_{k}\right)-D v(x)}{h}\right|^{2} d x \leq \frac{c}{d^{2}} \int_{\Omega^{\prime \prime}}\left|\frac{v\left(x+h e_{k}\right)-v(x)}{h}\right|^{2} d x
$$

for some $\Omega^{\prime} \subset \Omega^{\prime \prime} \subset \Omega$, for all $0<h<\frac{1}{4} d$ and $k$. So $v \in W_{l o c}^{2,2}(\Omega)$ and we can differentiate formally with respect to $x_{k}$ to obtain

$$
D_{i}\left(A_{i, P_{j}}(D v) D_{j} D_{k} v\right)+g^{\prime}(v) D_{k} v=0
$$

for each $k$. Let $\eta$ be a nonnegative $C_{0}^{\infty}(\Omega)$ function. Then

$$
\int_{\Omega} A_{i, P_{j}}(D v) D_{j} G(D v) D_{i} \eta d x=\int_{\Omega} A_{i, P_{j}}(D v) G_{P_{k}}(D v) D_{j} D_{k} v D_{i} \eta d x
$$

Since

$$
D_{i}\left(G_{P_{k}}(D v) \eta\right)=G_{P_{k} P_{i}} D_{i} D_{l} v \eta+G_{P_{k}}(D v) D_{i} \eta
$$

and $G_{P_{k}}(D v) \eta \in W_{0}^{1,2}(\Omega)$, we have

$$
\begin{aligned}
& \int_{\Omega} A_{i, P_{j}} G_{P_{k}}(D v) D_{j} D_{k} v D_{i} \eta d x \\
= & \int_{\Omega} A_{i, P_{j}} D_{j} D_{k} v D_{i}\left(G_{P_{k}}(D v) \eta\right) d x \\
& -\int_{\Omega} A_{i, P_{j}} G_{P_{k} P_{i}}(D v) D_{j} D_{k} v D_{i} D_{l} v \eta d x \\
= & \int_{\Omega} g^{\prime}(v) D_{k} v G_{P_{k}}(D v) \eta d x-\int_{\Omega} A_{i, P_{j}} G_{P_{k} P_{l}}(D v) D_{j} D_{k} v D_{i} D_{l} v \eta d x .
\end{aligned}
$$

Since $G$ is radially increasing and $g^{\prime} \leq 0$,

$$
\int_{\Omega} g^{\prime}(v) D_{k} v G_{P_{k}}(D v) \eta d x \leq 0
$$

Since $A_{i, P_{j}}$ and $G_{P_{k} P_{l}}$ are positive definite matrices,

$$
A_{i, P_{j}} G_{P_{k} P_{l}}(D v) D_{j} D_{k} v D_{i} D_{l} v \geq 0
$$

Therefore we have

$$
\int_{\Omega} A_{i, P_{j}}(D v) D_{j} G(D v) D_{i} \eta d x \leq 0
$$

for all nonnegative $\eta \in C_{0}^{\infty}(\Omega)$. Hence $G(D v)$ is a subsolution to

$$
D_{i}\left(A_{i, P_{j}} D_{j} w\right)=0
$$

and this completes the proof.
We have the following lemma for the solutions of homogeneous equations.

Lemma 3. Let $v \in W^{1,2}(\Omega)$ be a solution to

$$
D_{i}\left(A_{i}(D v)\right)=0
$$

where $A_{i}: R^{n} \rightarrow R$ satisfies the ellipticity condition (12). Let $G:$ $R^{n} \rightarrow R$ be convex and in $C^{1}$. Then $G(D v)$ is a subsolution to

$$
D_{i}\left(A_{i, P_{j}}(D v) D_{j} w\right)=0 .
$$

Since $G(D v)$ is a subsolution of a linear elliptic equation, we have a maximum principle.
lemma 4. Let $G$ and $v \in C^{1}(\bar{\Omega})$ satisfy the same conditions as in Theorem 6. Then we have the following maximum principle

$$
\begin{equation*}
\max _{\Omega} G(D v) \leq \max _{\partial \Omega} G(D v) \tag{14}
\end{equation*}
$$

proof. Let $M=\max _{\partial \Omega} G(D v)$ and $w=(G(D v)-M-\epsilon)^{+}$for some $\epsilon>0$. Then we see $w \in W_{0}^{1,2}$. So by using $w$ as a test function to (13), we have

$$
\int_{\{x: M+\epsilon \leq G(D v(x))\}} A_{i, P_{j}} D_{i}(G(D v)) D_{j}(G(D v)) d x \leq 0
$$

and

$$
\int_{\{x \in \Omega: G(D v(x)) \geq M+\epsilon\}}|D(G(D v))|^{2} d x=0 .
$$

By using Sobolev inequality we have meas $\{x \in \Omega: M+\epsilon \leq G(D v(x))\}$ $=0$ for all $\epsilon>0$.

Now we prove Theorem 5 by using monotone operator theory as in [3].
proof of Theorem 5. Let $f^{\rho}$ be the approximation of $f$ in the theorem 4 such that $f^{\rho}(P)=f(P)$ for all $P \in\{P: f(P) \leq \rho\} \cup\left\{P: f^{\rho}(P) \leq\right.$ $\rho\}$ and let $f^{\rho}$ satisfy the quadratic growth condition. Let $u^{\rho}$ be the minimizer of

$$
I^{\rho}\left[u^{\rho}\right]=\int_{\Omega} f^{\rho}\left(D u^{\rho}\right) d x
$$

with respect to $K^{\rho}=\left\{v \in W^{1,2}: v-u_{0} \in W_{0}^{1,2}\right\}$.
From section 2.1, we know that there exists a unique minimizer $u^{\rho}$ for each $\rho$. Fix $L \geq 2 M$, where $M$ is the constant defined in the bounded slope condition of Theorem 5 . We know that $u^{L}$ satisfies the Euler-Lagrange equation

$$
\begin{equation*}
D_{i}\left(f_{P_{i}}^{L}\left(D u^{L}\right)\right)=0 \tag{15}
\end{equation*}
$$

with $u^{L}-u_{0} \in W_{0}^{1,2}$. We see that $\left(u_{0}, \partial \Omega\right)$ has the ordinary bounded slope condition and

$$
\left|D \pi_{x_{0}}^{ \pm}\right| \leq C
$$

for all $x \in \partial \Omega$, where $C$ is independent of $x_{0}$.
Since $u_{0}$ is Lipschitz and ( $\left.u_{0}, \partial \Omega\right)$ satisfies the bounded slope condition, there exists a $w^{L} \in C^{1, \alpha}(\bar{\Omega})$ for all $0 \leq \alpha<1$ which satisfies the Euler-Lagrange equation (15) by the Theorem 13.1 and 14.1 in [3]. By the uniqueness, $u^{L}=w^{L}$. Since $f^{L}$ is convex, from the maximum principle (Lemma 4), we see that

$$
\max _{\Omega} f^{L}\left(D u^{L}\right) \leq \max _{\partial \Omega} f^{L}\left(D u^{L}\right)
$$

Since $u^{L}=u_{0}$ on $\partial \Omega$ and $\pi_{x_{0}}^{-}(x) \leq u^{L}(x) \leq \pi_{x_{0}}^{+}(x)$ for all $x \in \Omega$,

$$
\frac{\partial}{\partial \eta} u^{L}\left(x_{0}\right)=\frac{\partial}{\partial \eta} u_{0}\left(x_{0}\right)
$$

for all tangent vector $\eta$ to $\partial \Omega$ at $x_{0}$ and

$$
\frac{\partial}{\partial \tau} \pi_{x_{0}}^{+} \leq \frac{\partial}{\partial \tau} u^{L}\left(x_{0}\right) \leq \frac{\partial}{\partial \tau} \pi_{x_{0}}^{-}
$$

for all outward normal vector $\tau$ to $\partial \Omega$ at $x_{0}$. So we see that

$$
D u^{L}\left(x_{0}\right)=t D \pi_{x_{0}}^{+}+(1-t) D \pi_{x_{0}}^{-}
$$

for some $0 \leq t \leq 1$ and

$$
f^{L}\left(D u^{L}\left(x_{0}\right)\right) \leq t f^{L}\left(D \pi_{x_{0}}^{+}\right)+(1-t) f^{L}\left(D \pi_{x_{0}}^{-}\right) \leq M
$$

for all $x_{0} \in \partial \Omega$. So

$$
\max _{\Omega} f^{L}\left(D u^{L}\right) \leq M
$$

Since $f^{L}(P)=f(P)$ if $f^{L}(P) \leq L$, we conclude that $f\left(D u^{L}\right)=$ $f^{L}\left(D u^{L}\right)$ for all $x \in \Omega$ and hence $u^{L} \in K$. From the uniqueness of the $\operatorname{minimizer}, u^{L}=u$ and $u$ is $C^{1, \alpha}(\bar{\Omega})$ for all $0 \leq \alpha<1$.

## 5. Counterexamples

In this section we construct some counterexamples which exhibit that if the boundary data do not satisfy the bounded slope condition. Then a minimizer may not have a continuous derivative.

Let $0<\theta<1$ and $O=(-1,1) \times(-1,1)$.
Let $f: R^{2} \rightarrow R$ be a function such that

$$
f(P)=\left(1-P_{1}^{2}\right)^{-\theta}+\left(1-P_{2}^{2}\right)^{-\theta}
$$

for all $P \in O$ and

$$
f(P)=\infty
$$

for $P \in R^{2} \backslash O$.
By direct computation, we have

$$
\begin{gathered}
f_{P_{1}}(P)=2 \theta P_{1}\left(1-P_{1}^{2}\right)^{-\theta-1}, \\
f_{P_{2}}(P)=2 \theta P_{2}\left(1-P_{2}^{2}\right)^{-\theta-1}, \\
f_{P_{1} P_{1}}(P)=2 \theta\left(1-P_{1}^{2}\right)^{-\theta-2}\left(1+(2 \theta+1) P_{1}^{2}\right), \\
f_{P_{1} P_{2}}(P)=0, \\
f_{P_{2} P_{2}}(P)=2 \theta\left(1-P_{2}^{2}\right)^{-\theta-2}\left(1+(2 \theta+1) P_{2}^{2}\right)
\end{gathered}
$$

and we can see

$$
f_{P_{i} P_{j}}(P) \xi_{i} \xi_{j} \geq 2 \theta|\xi|^{2}
$$

for all $P \in O$ and $\xi \in R^{2}$.
Suppose $\Omega=\left(0, \frac{1}{4}\right) \times(-1,1), \Omega_{1}=\left(0, \frac{1}{4}\right) \times(0,1)$ and $\Omega_{2}=\left(0, \frac{1}{4}\right) \times$ $(-1,0)$.

We define $I[v]$ by

$$
I[v]=\int_{-1}^{1} \int_{0}^{\frac{1}{4}} f(D v) d x d y
$$

for all $v \in W^{1, \infty}$. Let $u_{1}(x, y)=x(1-y)$ in $\bar{\Omega}_{1}=\left[0, \frac{1}{4}\right] \times[0,1]$. Now reflect $u_{1}$ with respect to $x$ axis and set $u_{2}=x(1+y)$ in $\bar{\Omega}_{2}=$ $\left[0, \frac{1}{4}\right] \times[-1,0]$. Define $u=u_{1}$ in $\bar{\Omega}_{1}$ and $u=u_{2}$ in $\bar{\Omega}_{2}$.
lemma 5. Let $w$ be any admissible function for $I$ (i.e., $w=u$ on $\partial \Omega)$ and $I[w]<\infty)$. Then

$$
w(x, 0)=x
$$

for all $0 \leq x \leq \frac{1}{4}$.
proof. We prove by contradiction. First we note that $w$ is a Lipschitz function. Suppose that the lemma is false and we assume that $w\left(x_{0}, 0\right)>x_{0}$ for some $x_{0}$, where $0<x_{0}<\frac{1}{4}$. Define $\delta=w\left(x_{0}, 0\right)-x_{0}$. We regularize $w$ with $\epsilon$ as (4). Then $\boldsymbol{w}_{\epsilon} \rightarrow w$ uniformly for all $x \in$ $\Omega^{\prime} \subset \subset \Omega$ and by Jensen's inequality,

$$
f\left(D w_{\epsilon}\right) \leq f(D w)_{\epsilon}<\infty
$$

for all $x \in \Omega^{\prime}$ if $\epsilon$ is sufficiently small.
Let $\delta_{1}>0$ be so small that

$$
w\left(\delta_{1}, 0\right)<\frac{\delta}{5}
$$

and let $\epsilon$ be so small that

$$
\left|w_{\epsilon}\left(\delta_{1}, 0\right)-w\left(\delta_{1}, 0\right)\right| \leq \frac{\delta}{5}
$$

and

$$
\left|w_{\epsilon}\left(x_{0}, 0\right)-w\left(x_{0}, 0\right)\right| \leq \frac{\delta}{5}
$$

Then we see that

$$
\frac{w_{\epsilon}\left(x_{0}, 0\right)-w_{\epsilon}\left(\delta_{1}, 0\right)}{x_{0}-\delta_{1}} \geq 1+\delta_{2}
$$

for some $\delta_{2}>0$ independently for all small $\epsilon$. So for some $\delta_{1} \leq x_{1} \leq x_{0}$

$$
\frac{\partial w_{\epsilon}}{\partial x}\left(x_{1}, 0\right)>1
$$

and

$$
f\left(D w_{\epsilon}\left(x_{1}, 0\right)\right)=\infty
$$

This contradicts the fact that

$$
f\left(D w_{\epsilon}\right)<\infty
$$

for all $x \in \Omega^{\prime} \subset \subset \Omega$.

THEOREM 7. $u$ is a minimizer and $D u$ is not continuous.
proof. By direct computation, we see that $I[u]<\infty$ and $u$ is an admissible function. Moreover for all $\psi \in C_{0}^{\infty}\left(\Omega_{1}\right)$,

$$
\begin{aligned}
& \int_{\Omega_{1}} f_{P_{1}}(D u) \frac{\partial \psi}{\partial x}+f_{P_{2}}(D u) \frac{\partial \psi}{\partial y} d x d y \\
= & -\int_{\Omega_{1}} f_{P_{1} P_{1}}(D u) \frac{\partial^{2} u}{\partial x \partial x} \psi+2 f_{P_{1} P_{2}}(D u) \frac{\partial^{2} u}{\partial x \partial y} \psi d x d y \\
& +f_{P_{2} P_{2}}(D u) \frac{\partial^{2} u}{\partial y \partial y} \psi d x d y
\end{aligned}
$$

We have, by direct computation,

$$
\frac{\partial^{2} u}{\partial x \partial x}=\frac{\partial^{2} u}{\partial y \partial y}=0
$$

and

$$
f_{P_{1} P_{2}}=0
$$

We see that $u$ satisfies the Euler-Lagrange equation in $\Omega_{1}$. Similarly we see that $u$ satisfies the Euler-Lagrange equation in $\Omega_{2}$. Since every admissible function must have the same data on the line $y=0$, we conclude that $u$ is a minimizer.

Since

$$
\frac{\partial u}{\partial y}=-x
$$

in $\Omega_{1}$ and

$$
\frac{\partial u}{\partial y}=x
$$

in $\Omega_{2}, D u$ is not continuous on the line $y=0$.

REMARK. We note that the minimizers do not have the unique continuation property.

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Department of Mathematics
POSTECH,
Pohang 790-330, Korea

