# Adjustments of Dispersion Statistics in Extended Quasi-likelihood Models<sup>1)</sup>

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#### **Abstract**

In this paper we study numerical behavior of the adjustments for the variances of the Pearson and deviance type dispersion statistics in two overdispersed mixture models; negative binomial and beta-binomial distribution. They are important families of an extended quasi-likelihood model which is very useful for the joint modelling of mean and dispersion. Comparisons are done for two types of dispersion statistics for various mean and dispersion parameters by simulation studies.

#### 1. Introduction

Generalized linear models (Nelder and Wedderburn, 1972) have been widely used in regression modelling. Let the i-th response  $Y_i$  belongs to an exponential family of the canonical form

$$f(y;\theta,\phi) = \exp\{(y\theta - b(\theta))/a(\phi) + c(y,\phi)\}$$

for some specific function  $a(\cdot)$ ,  $b(\cdot)$ , and  $c(\cdot)$ , where  $\theta$  is canonical parameter and  $\phi$  is dispersion parameter. To specify the generalized linear models, we have to define a linear predictor  $\eta_i = x_i'\beta$  and a link function  $g(\cdot)$  such that  $\eta_i = g(\mu_i)$ , where  $\mu_i = E(Y_i)$  in addition to the distribution of  $Y_i$ . It is often, however, that we have limited information for the complete specification of the generalized linear model. To avoid this difficulty, Wedderburn (1974) suggested a quasi-likelihood model requiring the first two moments of the responses. To be specific, the variance of a response has been assumed to take the form

$$\mathrm{var}(\,Y_{\,i}) = \phi V(\mu_{\,i})$$

where  $Y_i$  is a response,  $\phi$  is dispersion parameter, and  $V(\mu)$  is a known

<sup>1)</sup> This research was supported by the Ministry of Education (BSRI-91-116)

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variance function. In the simplest of generalized linear models the dispersion parameter  $\phi$  is a constant, usually unknown, however, there are many cases those  $\phi$ 's vary in a systematic way with other measured covariates. To come up with these Pregibon (1984) suggested joint model specification in terms of the dependence on covariates of the first two moments. For the mean we have the usual specification

$$E(Y_i) = \mu_i, \quad \eta_{i} = g(\mu_i) = \sum_{j} x_{ij} \beta_j, \text{ var}(Y_i) = \phi_i V(\mu_i)$$

where  $\eta_i$  is the linear predictor, g is the link function,  $x_{ij}$  is the element of the  $n \times p$  design matrix. Also, for the dispersion, it is assumed that

$$E(d_i) = \phi_i, \quad \zeta_i = h(\phi_i) = \sum_j u_{ij} \gamma_j, \text{ var } (d_i) = \tau V_D(\phi_i).$$

In this specification,  $d_i$  is a suitable statistic chosen as a measure of dispersion;  $h(\cdot)$  is the dispersion link function;  $\zeta$  is the dispersion linear predictor,  $\tau$  is dispersion parameter for  $d_i$ , and  $V_D(\phi)$  is the dispersion variance function. The dispersion covariates  $u_i$  are commonly, but not necessarily, a subset of the regression covariates  $x_i$ .

Two possible choices for the dispersion statistic are the generalized Pearson contribution  $r_p^2 = (Y_{i-}\mu_i)^2/V(\mu_i)$  and the contribution to the *i*-th deviance

$$r_D^2 = 2\sum \{y_i(\tilde{\theta}_i - \hat{\theta}_i) - b(\tilde{\theta}_i) + b(\hat{\theta}_i)\}/a(\phi)$$

where  $\hat{\theta}_i$  and  $\hat{\theta}_i$  are estimates of  $\theta_i$  under the maximal model and current model, respectively. The pros and cons for the performance of  $r_p^2$  and  $r_D^2$  as goodness-of-fit measure in the generalized linear models were discussed by Pierce and Schafer (1986). If Y is normal  $d_i$  has  $\phi_i \chi_1^2$  distribution, so that a gamma model with  $V_D(\phi) = 2\phi^2$  would be chosen. If Y is non-normal, adjustments to the dispersion model may be necessary to account for the bias in  $r_D^2$  or for the excess variability of  $r_p^2$ . Recently, McCullagh and Nelder (1990) suggested adjustments of the estimating equations for the dispersion parameters in each ways that

$$var(r_p^2) = 2\phi^2(1 + \rho_4/2)$$
 (1)

and

$$var(r_D^2) = 2\phi^2 (1+b)^2$$
 (2)

where  $b = (5\rho_3^2 - 3\rho_4)/12$  is the Bartlett adjustment, and  $\rho_3$  and  $\rho_4$  denotes the standardized third and fourth cumulant, respectively. Note that the nominal variance is  $2\phi^2$ .

In this paper, we study numerical behavior of the adjustments for  $var(r_p^2)$  and  $var(r_D^2)$  in two over-dispersed mixture models; negative binomial distribution and beta-binomial distribution which are standard mixture of Poisson and binomial distribution when the overdispersion exist. Also, they are important classes of an extended quasi-likelihood models (Nelder and Pregibon, 1987). Definition and examples of overdispersion can be found in Cox(1983), Efron(1986), Jorgensen(1987) and Gelfand and Dalal(1990).

#### 2. Model Specification

We assume that, conditional on the sampling mean  $\theta_i$ , the data  $y_i$  have independent distributions belonging to a natural exponential family (NEF) with quadratic function (Morris, 1982, 1983), and that the means  $\theta_i$  are independent with conjugate mixture (CM) distributions. Let  $[\mu, V(\mu)]$  denote a distribution with mean  $\mu$  and variance function  $V(\mu)$ .

## 2.1 Negative binomial distribution

When we have gamma-Poisson mixture, the resulting marginal distribution is negative binomial. To be more specific, let

$$y|\theta \sim \text{Poisson}(\theta) = \text{NEF}[\theta, \theta],$$
  
 $\theta \sim \Gamma\left(\frac{\mu}{\phi}, \phi\right) = \text{CM}[\mu, \phi\mu],$   
 $V(\mu) = \mu,$ 

and

$$y \sim NB\left(\frac{\mu}{\phi}, \frac{\phi}{1+\phi}\right) = marg \left[\mu, (1+\phi)\mu\right]$$

where  $\Gamma(\alpha,\beta)$  denotes a gamma distribution with parameters  $\alpha$  and  $\beta$ , and NB( $\alpha,\beta$ ) denotes a negative binomial distribution with probability function

$$p(y) = {\alpha + y - 1 \choose y} \beta^{y} (1 - \beta)^{\alpha}, y = 0, 1, \dots$$

and  $y \sim \text{marg}[\theta_1, \theta_2]$  denotes the random variable y has mean  $\theta_1$  and variance  $\theta_2$  marginally. In this set up, two types of dispersion statistics are

$$r_p^2 = (y_i - \hat{\mu})^2 / \hat{\mu}$$

and

$$r_D^2 = -2\{ (y_i \log \hat{\mu} - \hat{\mu}) - (y_i \log y_i - y_i) \}.$$

Also, the adjusted variances for  $r_D^2$  and  $r_p^2$  given by McCullagh and Nelder (1990) are

$$var(r_p^2) = 2(1+\phi)^2 \left(1 + \frac{1+\phi}{2\mu}\right)$$

and

$$var(r_D^2) = 2(1+\phi)^2 \left(1 + \frac{1+\phi}{6\mu}\right)^2$$

respectively. Note that the nominal variance is just  $2(1+\phi)^2$ .

#### 2.2 Beta-binomial distribution

A beta-binomial mixture can be specified as follows;

$$y|\theta \sim \frac{1}{m}$$
 Binomial  $(m,\theta) = NEF \left[\theta, \frac{\theta(1-\theta)}{m}\right]$ 

$$\theta \sim \text{Beta}(\psi \mu, \psi(1-\mu)) = \text{CM}[\mu, \phi \mu(1-\mu)]$$

where  $\psi = 1/\phi - 1$ , and the variance function is

$$V(\mu) = \mu(1-\mu)$$
.

Then, the marginal distribution of y becomes

$$y \sim \frac{1}{m} BB(m, \psi \mu, \psi (1-\mu)) = marg [\mu, \mu (1-\mu)/w]$$

where BB( $m, \alpha, \beta$ ) denotes a beta-binomial random variable with probability function

$$p(r) = {m \choose r} \frac{\Gamma(\alpha+\beta)\Gamma(r+\alpha)\Gamma(m+\beta-r)}{\Gamma(\alpha)\Gamma(\beta)\Gamma(m+\alpha+\beta)}, r = 0, 1, ..., m$$

and  $w=m/(1+(m-1)\phi)$ . In this situation.

$$r_p^2 = (y_i - \hat{\mu})^2 / \hat{\mu} (1 - \hat{\mu})$$

and

$$r_D^2 = -2\left\{y_i \log\left(\frac{\hat{\mu}}{1-\hat{\mu}}\right) + \log\left(1-\hat{\mu}\right) - y_i \log\left(\frac{y_i}{1-y_i}\right) - \log\left(1-y_i\right)\right\},\,$$

and the corresponding adjusted variances are

$$var(r_p^2) = \frac{2}{w^2} \left( 1 + \frac{1}{2mw} \frac{1 - 6\mu(1 - \mu)}{\mu(1 - \mu)} \right)$$

and

$$var(r_D^2) = \frac{2}{w^2} \left( 1 + \frac{1}{6mw} \cdot \frac{1 - \mu(1 - \mu)}{\mu(1 - \mu)} \right)^2.$$

Also, note that the nominal variance is  $2/w^2$ .

### 3. Simulation

In the negative binomial distribution simulations are done for n=100,1000;  $\mu = 1(1)10$ ;  $\phi = 0.1, 0.2$ , and 1000 replications are allowed. To be more specific, we generate a sample of size n for a given  $\mu$  and  $\phi$  from the IMSL library (GGDA), and repeat 1000 times to obtain true variances (TV; i.e., average of 1000 sample variances) of  $r_p^2$  and  $r_D^2$ , and compared them with the nominal variance (NV) and their adjusted variances (AV). Figure 1 shows the simulation result for n=100, and Figure 2 shows them for n=1000. When n=100,  $r_D^2$  is overly adjusted for  $\mu \le 2$ , while  $r_p^2$  is properly adjusted. When n=1000,  $r_p^2$  is under-adjusted especially for  $\phi = 0.2$  case while  $r_D^2$  is almost perfectly adjusted except  $\mu \leq 2$ . Simulation for other n, u, and o than listed showed similar results. Based on these results, we note that

- i) True variances of  $r_p^2$  and  $r_D^2$  are away from their nominal variance  $2\phi^2$ , unless  $\mu$  is large (at least  $\mu \geq 5$  in our experience) regardless of the sample size n. Therefore, adjustment is necessary.
- ii) For small sample size adjustment of  $r_p^2$  is better than that of  $r_D^2$ , and the converse is true for the large sample size.
- iii) As the overdispersion parameter  $\phi$  increases, adjustment of  $r_D^2$  shows better performance unless  $\mu$  is too small.

For fixed sample size n=1000, simulations are done for m=5,10;  $\mu=.05(.05).50$ ;  $\phi=.01,.02$ , and 1000 replications are allowed in the beta-binomial distribution. Simulation results are given in Figure 3 and 4 for m=5 and m=10, respectively. As shown in these Figures both adjustments for m=5 are too small to explain the actual variances. Adjustment of  $r_D^2$  is so bad in the sense that the actual variance increases while the adjusted variance decreases. In  $r_D^2$  case both decreasing, however, the adjustment should be made larger than it is. For m=10, the discrepancies become much smaller but similar phenomenon to m=5 case occur. We note that

- i) Adjustment of  $r_D^2$  is very poor.
- ii) Adjustment of  $r_p^2$  is smaller than it should be.

#### 4. Remarks and Further Studies

Conclusively, adjustments for the variances of the dispersion statistics are necessary, but the existing adjustments are not good enough to be used safely in every situation. We have done simulations on other situations than listed in this paper, and they showed similar trend. It is therefore required that refined adjustments must be studied. Also, as pointed by referees, analytic form of adjustments might be possible and application to real data sets improve and rectify this study.

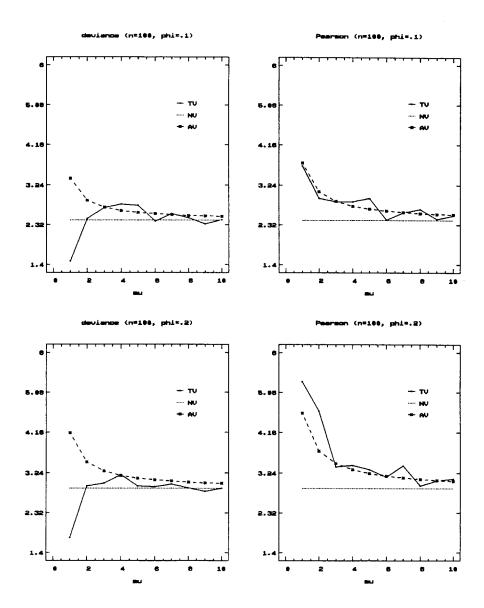


Figure 1. Simulations for the variances of dispersion statistics  $r_D^2$  and  $r_P^2$  with their nominal and adjusted variances with respect to  $\mu$  when n=100,  $\phi=.1$ , .2 in negative binomial distribution.

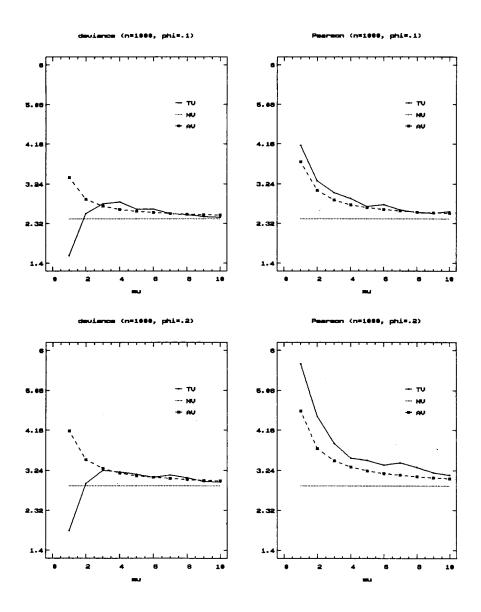


Figure 2. Simulations for the variances of dispersion statistics  $r_D^2$  and  $r_P^2$  with their nominal and adjusted variances with respect to  $\mu$  when n=1000,  $\phi=.1$ , .2 in negative binomial distribution.

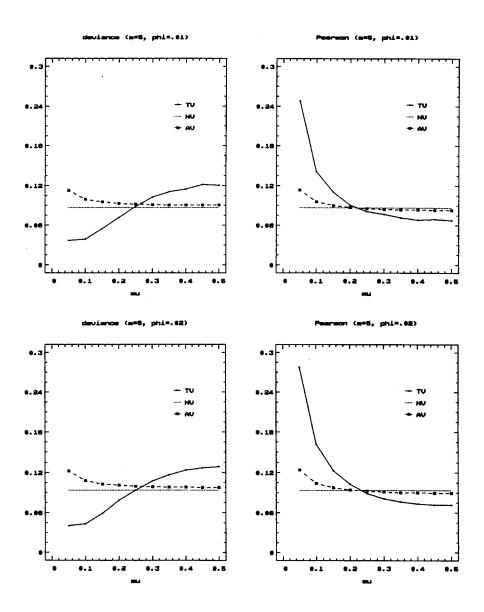


Figure 3. Simulations for the variances of dispersion statistics  $r_D^2$  and  $r_P^2$  with their nominal and adjusted variances with respect to  $\mu$  when m=5,  $\phi=.01$ , .02 in beta-binomial distribution.

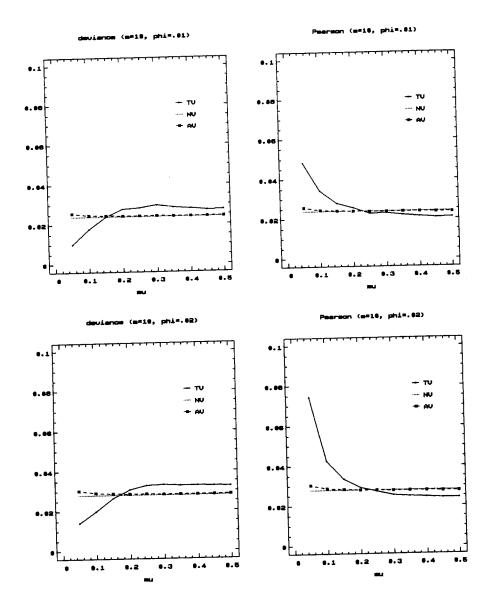


Figure 4. Simulations for the variances of dispersion statistics  $r_D^2$  and  $r_P^2$  with their nominal and adjusted variances with respect to  $\mu$  when m=10,  $\phi=.01$ , .02 in beta-binomial distribution.

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# 준우도 함수의 분산치 교정1)

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요 약

본 논문에서는 과산포 혼합 모형인 음이항 분포와 배타이항 분포에서 피어슨 형태 및 데비언스 형태의 분산치 교정에 대한 효과를 수리적으로 비교했다. 이들 과산포 혼합 모형은, 평균과 분산을 동시에 모형화 하는데 매우 유용한 준우도함수의 증요한 구성원이다. 모의실험을 통해서 분산치의 교정이 평균, 산포모수에 따라 어떻게 달라지는지 비교 연구하였다.

<sup>1)</sup> 본연구는 교육부 기초과학연구소 특성화 (BSRI-91-116) 연구비에 의해 수행되었음.

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