

A STUDY ON MULTIOBJECTIVE FRACTIONAL OPTIMIZATION PROBLEMS

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1. Introduction

Duality theorems for single objective fraction optimization problems have been of much intrest in the past [1,4,8,10,11,12]. Recently there has been of growing intrest in studying optimality theorems and duality theurems for multyobjective fractional optimazation problems [2,3,5,13,14,15]. In particular optimazition problem in which numerators of objective functions involves the square roots of quadratic forms and established optimality theorems and duality theorems in the framework of the Hanson-Mond classes of functions. Also Bhatia and Jain [1] entended Singh's results to a nondifferentiable multiobjective fractional optimization problem in which numerators of objective functions involves the square roots of quadratic forms.

In this paper, we consider the following nondifferentiable multiobjective optimization problem (p):

$$(P) \text{Minimize } F(X) = \left(\frac{f_1(x) + (xD_1x)^{\frac{1}{2}}}{h_1(x)}, \dots, \frac{f_k(x) + (xD_kx)^{\frac{1}{2}}}{h_k(x)} \right) \\ \text{subject to } g(x) \leq 0, x \in X,$$

where X is an open convex subset of R^n , each $f_i : \rightarrow R$, $h_i : X \rightarrow R, i = 1, \dots, K$, $g : X \rightarrow R^m$ are differentiable and $D_i, i = 1, \dots, K$ are symmetric positive semidefinite matrices. Let X_0 denote the set of feasible solutions of problem (P). We asumme that X_0 is compact and $h_i(x) > 0$ on $X_0, i = 1, \dots, K$. All vectors are considered to be column vectors. For simplicity, we avoid the use of the superscript t over a vector to label it as row vector. For instance, instead of writing

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$x_t D, x$, etc

A sufficient optimality theorem for a feasible solution of (P) to be properly efficient is given. A dual problem for (P) is considered and certain duality theorems are obtained under the ρ -convexity assumptions.

2. Preliminaries

Now we give the definitions and results needed in later in later sections.

Definition 2.1. A feasible solution $x^0 \in X_0$ is said to be an efficient solution of (P) if there exists no other feasible solution $x \in X_0$ such that

$$F_i \leq F_i(x^0), i = 1, \dots, K, F(x) \neq F(x^0).$$

Definition 2.2. A feasible solution $x^0 \in X^0$ is to be properly efficient for (P) if it is efficient for (P) and if there exists a scalar $M > 0$ such that for each i ,

$$[F_i(x^0) - F_i(x)]/[F_j(x) - F_j(x^0)] \leq M$$

for some j , $F_j(x) > F_j(x^0)$ whenever x is feasible for (P) and $F_i(x) < F_i(x^0)$.

Lemma 2.1 [6]. Let D be an n, n real, symmetric, positive semi-definite matrix. Then, for any $x \in R^n, y \in R^n$,

$$xDy \leq (xDx)^{\frac{1}{2}}(yDy)^{\frac{1}{2}}.$$

Lemma 2.2[2]. Let $x^0 \in X_0$. If (x^0, y^0) is properly efficient for the following multiobjective optimization problem (P^1) with $y = y^0$, where $y_i^0 = [f_i(x^0) + (x^0 D_i x^0)^{\frac{1}{2}}]/h_i(x_0), i = 1, \dots, K$, then x^0 is properly efficient for (P).

$$\begin{aligned} (P^1) \text{ Minimize } & [f_1(x) + (xD_1x)^{\frac{1}{2}} - y_1h_1(x), \dots, f_k(x) \\ & + (xD_kx)^{\frac{1}{2}} - y_kh_k(x)] \\ \text{subject to } & g(x) \leq 0, x \in X, y \in R^k. \end{aligned}$$

Theorem 2.1 [2]. Suppose that x^0 is properly efficient solution of (P) and the Z^0 is empty. Then there exists a $\lambda_i > 0, i = 1, \dots, k$,

$$\sum_{i=1}^k \lambda_i = 1, y_i^0 \geq 0, i = 1, \dots, k, v \in R^m, v_j^0 \geq 0, w_i^0 \in R^n, i = 1, \dots, k$$

such that

$$\begin{aligned} \sum_{i=1}^k \lambda_i [\nabla f_i(x^0) + D_i w_i^0 - \nabla y_i^0 h_i(x^0)] + \nabla v^0 g(x^0) &= 0 \\ v^0 g(x^0) &\geq 0, \\ w_i^0 D_i w_i^0 &\leq 1, i = 1, \dots, k \\ (x^0 D_i x^0)^{\frac{1}{2}} &= x^0 D_i w_i^0, i = 1, \dots, k. \end{aligned}$$

For a feasible solution x^0 of (P), following Mond and Schechter [9], we define $Z^0 = \cup_{i=1}^K Z_i^0$, where

$$\begin{aligned} Z_i^0 = \{z : z \nabla g_j(x^0) \leq 0 \text{ for all } j \in Q \text{ and} \\ z[\nabla f_i(x^0) - \nabla y_i^0 h_i(x^0)] + z D_i x^0 / x^0 D_i x^0 < 0 \text{ if } x^0 D_i x^0 > 0, \\ z[\nabla f_i(x^0) - \nabla y_i^0 h_i(x^0)] + (z D_i z) < 0 \text{ if } x^0 D_i x^0 = 0\} \end{aligned}$$

for $i = 1, \dots, k$, where $Q = \{j : g_j(x^0) = 0\}$ and

$$y_i^0 = \frac{f_i(x^0) + (x^0 D_i x^0)^{\frac{1}{2}}}{h_i(x^0)}, i = 1, \dots, k.$$

Definition 2.3. Let f be a real valued differentiable function defined on a subset X of R^n . Then f is said to be ρ -convex if there exists some real number ρ such that for each $x, u \in X$,

$$f(x) - f(y) \geq (x - u) \nabla f(u) + \rho \|x - u\|^2.$$

3. Sufficient Optimality Theorem

Now we establish a sufficient optimality theorem for (P) under the ρ -convex assumptions

Theorem 3.1. Suppose that there exists a feasible solution x^0 of (P) and a scalar $\lambda_i > 0, i = 1, \dots, k, \sum_{i=1}^k \lambda_i = 1, i = 1, \dots, k, v^0 \in R^m, v^0 \geq 0, w_i^0 \in R^n, i = 1, \dots, k$ with

$$y_i^0 = \frac{f_i(x^0) + (x^0 D_i x^0)^{\frac{1}{2}}}{h_i(x^0)}, i = 1, \dots, k \text{ such that}$$

$$(1) \quad \sum_{i=1}^k \lambda_i [\nabla f_i(x^0) + d_i w_i^0 - \nabla y_i^0 h_i(x^0)] + \nabla v^0 g(x^0) = 0$$

$$(2) \quad v^0 g(x^0) = 0,$$

$$(3) \quad w_i^0 D_i w_i^0 \leq 1, i = 1, \dots, k,$$

$$(4) \quad (x^0 D_i x^0)^{\frac{1}{2}} = x^0 D_i w_i^0, i = 1, \dots, k.$$

Further suppose that f_i is ρ_i -convex, $-h_i$ is ρ_i^* -convex, $i = 1, \dots, K$ and g_j is ρ_j^{**} -convex, $j = 1, \dots, m$ and that

$$\sum_{i=1}^k (\lambda_i \rho_i - \lambda_i y_i^0 \rho_i^*) + \sum_{j=1}^m v_j^0 \rho_j^{**} \geq 0.$$

Then x^0 is a properly efficient solution of (P).

Proof. By (1), (5) and the ρ -convexity assumptions, we have

$$\begin{aligned} 0 &\geq \sum_{i=1}^K \lambda_i [f_i(x) - f_i(x^0)] + \sum_{i=1}^K \lambda (x - x^0) D_i w_i^0 \\ &\quad - \sum_{i=1}^K \lambda_i y_i^0 [h_i(x) - h_i(x^0)] + \sum_{j=1}^m v_j^0 [g_j(x) - g_j(x^0)]. \end{aligned}$$

By (2), $v_j^0 g_j(x^0) = 0$ and since x is feasible, $v_j g_j(x) \leq 0, j = 1, \dots, m$. Hence (6) reduces to

$$0 \geq \sum_{i=1}^K \lambda_i [f_i(x) - f_i(x^0)] + \sum_{i=1}^K \lambda (x - x^0) D_i w_i^0 - \sum_{i=1}^K \lambda_i y_i^0 [h_i(x) - h_i(x^0)].$$

By (3), (4) and Lemma2.1, we have

$$0 \leq \sum_{i=1}^K \lambda_i [f_i(x) - f_i(x^0)] + \sum_{i=1}^k \lambda_i [(x D_i x)^{\frac{1}{2}} - (x^0 D_i x^0)^{\frac{1}{2}}] \\ - \sum_{i=1}^k \lambda_i y_i^0 [h_i(x) - h_i(x^0)].$$

Hence we have

$$\sum_{i=1}^k \lambda_i [f_i(x^0) + (x^0 D_i x^0)^{\frac{1}{2}} - y_i^0 h_i(x^0)] \\ \leq \sum_{i=1}^k \lambda_i [f_i(x) + (x D_i x)^{\frac{1}{2}} - y_i^0 h_i(x)].$$

By Theorem 1 in [7], (x^0, y^0) is properly efficient for (p^1) .
By Lemma2.2, x^0 is a properly efficient solution of (P).

4. Duality Theorems

Now we give the dual problem (D) for (P). Maximize
 $G(s, v, y, w_1, \dots, w_k) = y = (y_1, \dots, y_k)$ subject to

$$(7) \quad \sum_{i=1}^k \lambda_i [\nabla f_i(s) + D_i w_i - \nabla y_i h_i(s)] + \nabla v^t g(s) = 0,$$

$$(8) \quad f_i(s) + (s D_i s)^{\frac{1}{2}} - y_i h_i(s) \geq 0, i = 1, \dots, k,$$

$$(9) \quad w_i D_i w_i \leq 1, i = 1, \dots, k,$$

$$(10) \quad (s D_i s)^{\frac{1}{2}} = s D_i w_i, i = 1, \dots, k$$

$$(11) \quad v g(s) \geq 0,$$

$$(12) \quad v \geq 0, y \geq 0,$$

where $\lambda_i > 0, i = 1, \dots, k$ and $\sum_{i=1}^k \lambda_i = 1$.

Theorem 4.1. Let be any feasible solution of (P) and $(s, v, y, w_1, \dots, w_k)$ be any feasible solution of (D) for any $\lambda > 0$. Suppose that f_i is ρ_i -convex, $-h_i$ is ρ_i^* -convex, $i = 1, \dots, k$, and g_j is ρ_j^{**} -convex, $j = 1, \dots, m$ and that

$$\sum_{i=1}^k (\lambda_i \rho_i - \lambda_i y_i \rho_i^*) + \sum_{j=1}^m v_j \rho_j^{**} \geq 0.$$

Then the following does not holds;

$$\frac{f_i(x) + (xD_i x)^{\frac{1}{2}}}{h_i(x)} \leq y_i \quad \text{for all } i = 1, \dots, k$$

and

$$\frac{f_j(x) + (xD_j x)^{\frac{1}{2}}}{h_j(x)} < y_j \quad \text{for some } j.$$

Proof. Suppose that the following holds;

$$\frac{f_i(x) + (xD_i x)^{\frac{1}{2}}}{h_i(x)} \leq y_i \quad \text{for all } i = 1, \dots, k$$

and

$$\frac{f_j(x) + (xD_j x)^{\frac{1}{2}}}{h_j(x)} < y_j \quad \text{for some } j.$$

Then by (8), (11) and (12), we have

$$\begin{aligned}
 0 &> \sum_{i=1}^k \lambda_i [f_i(x) + (xD_i x)]^{\frac{1}{2}} - y_i h_i(x) \\
 &\quad - \sum_{i=1}^k \lambda_i [f_i(s) + (sD_i s)]^{\frac{1}{2}} - y_i h_i(s) + v g(x) - v g(s) \\
 &\geq \sum_{i=1}^k \lambda_i [(x-s) \nabla f_i(s) + \rho_i \|x-s\|^2] \\
 &\quad - \sum_{i=1}^k \lambda_i [(x-s) \nabla y_i h_i(s) + \rho_i^* \|x-s\|^2] \\
 &\quad + \sum_{j=1}^m [(x-s) \nabla v_j g_j(s) + v_j^{**} \rho_j \|x-s\|^2] \\
 &\quad + \sum_{i=1}^k \lambda_i [(xD_i x)^{\frac{1}{2}} - (sD_i s)^{\frac{1}{2}}] \\
 &\quad \text{(by the } \rho \text{-convexity assumptions)} \\
 &\geq - \sum_{i=1}^k \lambda_i (x-s) D_i w_i + \sum_{i=1}^k \lambda_i [(xD_i x)^{\frac{1}{2}} - (sD_i s)^{\frac{1}{2}}] \\
 &\quad + [\sum_{i=1}^k (\lambda_i \rho_i - \lambda_i y_i \rho_i^*) + \sum_{j=1}^m v_j \rho_j^{**}] \|x-s\|^2 \\
 &\quad \text{(by (7), (9), (10) and Lemma 2.1)} \\
 &\geq [\sum_{i=1}^k (\lambda_i \rho_i - \lambda_i y_i \rho_i^{**}) + \sum_{j=1}^m v_j \rho_j^{**}] \|x-s\|^2 \\
 &\geq 0.
 \end{aligned}$$

This is a contradiction. Hence the result holds.

Theorem 4.2. Suppose that x^0 is a properly efficient solution of (P) and the set Z^0 is empty. Then exists a feasible solution $(x^0, v^0, w_1^0, \dots, w_k^0)$ of (D) for some $\lambda > 0$. Furthermore suppose that f_i is ρ_i -convex, $-h_i$ is ρ_i^* -convex, $i = 1, \dots, k$, and ρ_j^{**} -convex, $j = 1, \dots, m$

and that

$$\sum_{i=1}^k (\lambda_i \rho_i - \lambda_i y_i \rho_i^*) + \sum_{j=1}^m v_j \rho_j^{**} \geq 0.$$

Then $(x^0, v^0, y^0, w_1^0, \dots, w_k^0)$ is a properly efficient solution of (D) and their respective extreme values are equal.

Proof. By Theorem 2.1, $(x^0, v^0, y^0, w_1^0, \dots, w_k^0)$ is feasible for (D). By Theorem 4.1, their respective extreme values are equal. Following Theorem 4 in [15], $(x^0, v^0, y^0, w_1^0, \dots, w_k^0)$ is a properly efficient solution of (D).

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