

NON-ORIENTABLE MANIFOLDS WITH A TOTAL ACTION

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0. Introduction

In section 1, we are going to study two types of those 4-manifolds with a T^2 action which we encounter in a classifying problem. As a standard technique, by investigating the orbit spaces, we will get some informations of the total spaces.

J. Pak classified, in [P], $(n+1)$ -orientable manifolds with a T^2 action. Since it is not found in any literature for the nonorientable case, we gave the complete solution in section 2.

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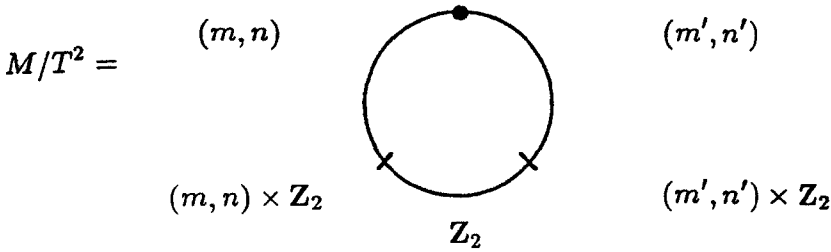
1. 4-Manifolds with a T^2 action

Throughtout the paper, we adopt the following notation. Let S^1 be the set of all complex numbers whose absolute value is 1, we denote $\exp 2\pi i\phi$ as a point of S^1 , where ϕ is a real number and \exp is the exponential function. Let S^2 be the unit sphere in the 3 - dimensional Euclean space R^3 . We will use $(\rho \exp 2\pi i\theta, z)$ or ν as a point of S^2 , where $0 \leq \rho \leq 1$, $-1 \leq z \leq 1$, since R^3 can be identified with the product of the complex plane \mathbb{C} and R^1 . Let T^n be the n times product of S^1 . Every manifold is smooth and closed.

DEFINITION 1.1. Let f be a function from R^2 to the 2 - dimensional complex plance \mathbb{C}^2 defined by $f(x, y) = (\exp 2\pi ix, \exp 2\pi iy)$. Given relatively prime integers m, n , we define the image of the straight line $mx + ny = 0$ in R^2 under f to be (m, n) .

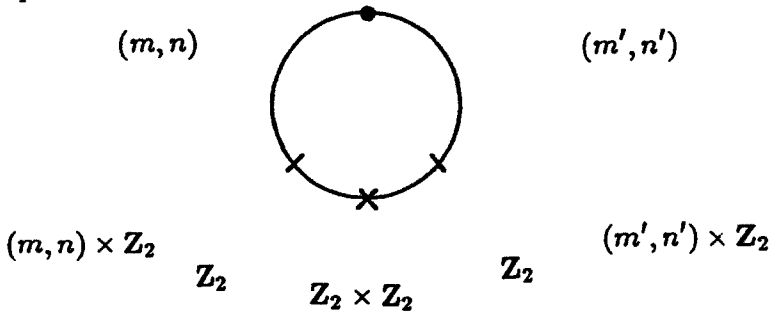
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DEFINITION 1.2. A group G action on M is effective if $gx = x$, for all x in M , implies g is the identity element in G . We denote the quotient space (i.e. orbit space with "weights") by M/G . For example,

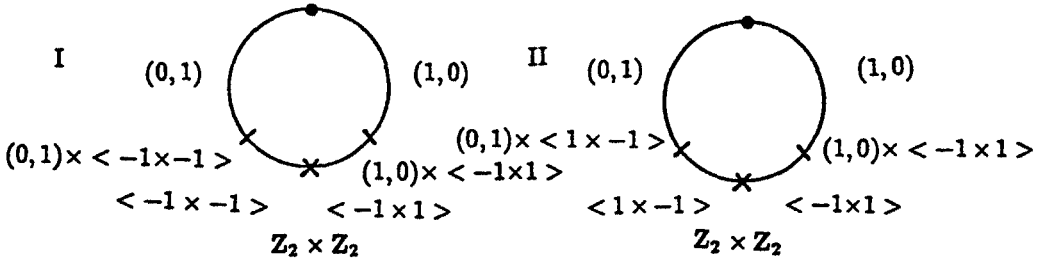


is a weighted disk. The weight at each interior point is the identity, while we have divided up the boundary into 3 arcs. The 3 end points of the arcs correspond to a fixed point, $(m, n) \times \mathbb{Z}_2$ and $(m', n') \times \mathbb{Z}_2$. The interior of the arcs correspond to orbits whose stabilizers are (m, n) , (m', n') and \mathbb{Z}_2 . A \mathbb{Z}_2 group is generated by, for example, -1×1 in T^2 . We denote it by $\langle -1 \times 1 \rangle$.

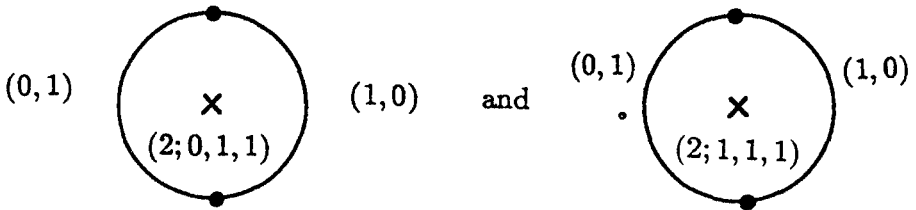
Consider nonorientable 4-manifolds with an effective T^2 -action whose orbit spaces are



Then, by results in [K], [OR II] and [Pa], there exists only one manifold corresponding to each orbit space, up to T^2 -equivariant diffeomorphism. Note that "weights" changes, in orbit spaces, by reparametrization of T^2 do not affect the total spaces. By the effectiveness and differentiability, the total space is diffeomorphic to one of two manifolds whose orbit spaces are



If we let M_1, M_2 be manifolds corresponding to I and II, according to [B], that the orientable double covers \tilde{M}_1, \tilde{M}_2 have the induced T^2 -action and their orbit spaces are

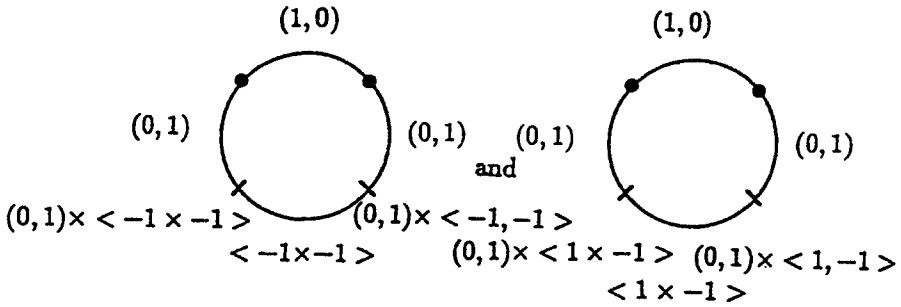


According to Pao, \tilde{M}_1 is diffeomorphic to $(S^2 \times S^2) / \langle \phi \rangle$ and \tilde{M}_2 is diffeomorphic to $(S^2 \times S^2) / \langle \psi \rangle$, where ϕ and ψ are involutions of $S^2 \times S^2$ defined by

$$\begin{aligned} \phi((x, y, z), (x', y', z')) &= ((-x, -y, -z), (-x', y', z')) \\ \psi((x, y, z), (x', y', z')) &= ((-x, -y, -z), (-x', -y', -z')) \end{aligned}$$

and $\langle \phi \rangle$ and $\langle \psi \rangle$ are \mathbb{Z}_2 groups generated by ϕ and ψ respectively.

He showed that \tilde{M}_1 is not homotopy equivalent to \tilde{M}_2 , so we can conclude that M_1 is not homotopy equivalent to M_2 . It is an interesting fact that there are nonorientable double covers M'_1 and M'_2 for M_1 and M_2 whose orbit spaces are

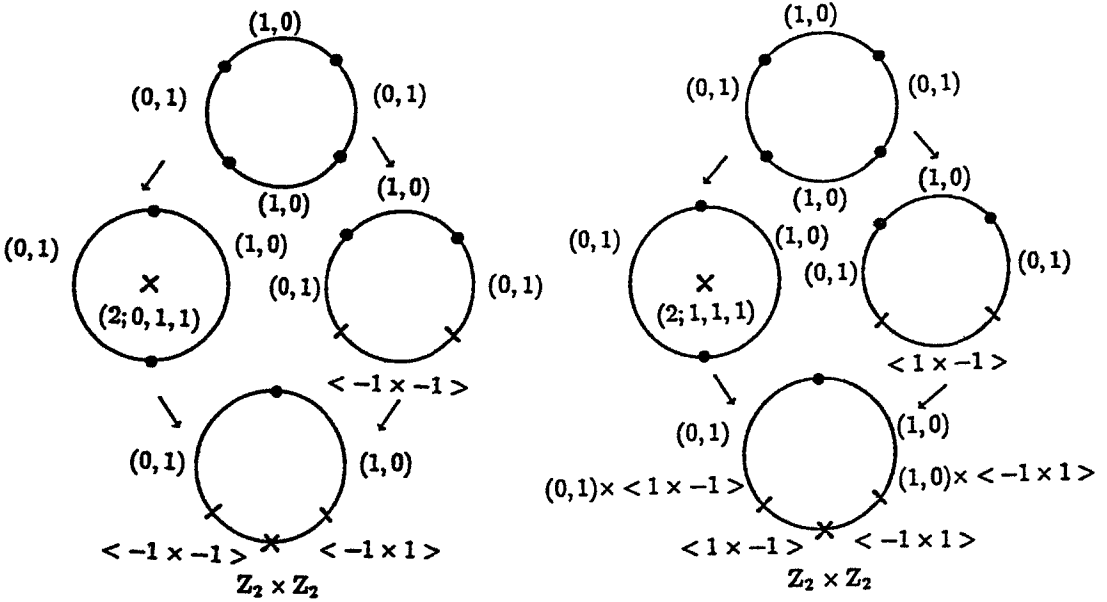


From [K], $M'_1 = (S^2 \times S^2) / \langle \varphi \rangle$ and $M'_2 = (S^2 \times S^2) / \langle h \rangle$, where φ and h are involutions of $S^2 \times S^2$ defined by

$$\varphi((x, y, z), (x', y', z')) = ((-x, -y, -z), (-x', -y', z'))$$

$$h((x, y, z), (x', y', z')) = ((-x, -y, -z), (x', y', z')).$$

Furthermore, we have the following diagrams of orbit spaces.

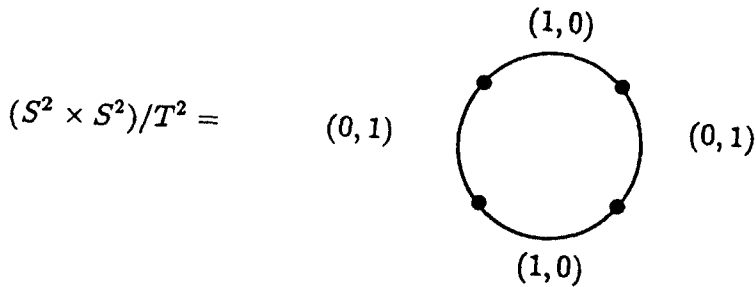


Thus $M_1 = (S^2 \times S^2) / \langle \varphi, \phi \rangle$ and $M_2 = (S^2 \times S^2) / \langle \psi, h \rangle$. We obtain $\pi_1(M_1) = \pi_1(M_2) = \mathbb{Z}_2 \times \mathbb{Z}_2$ and $\pi_i(M_1) = \pi_i(M_2) = \mathbb{Z} \times \mathbb{Z}$ for $i \geq 2$ by

the homotopy exact sequence. We can give appropriate T^2 -actions on M_1 and M_2 which produce the given orbit spaces as follows:

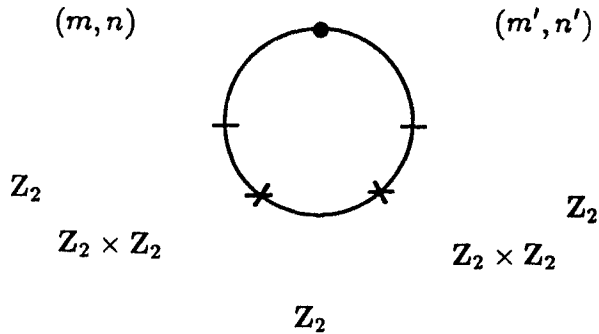
$$T^2 \times S^2 \times S^2 \longrightarrow S^2 \times S^2$$

$$(\exp(2\pi i\alpha), \exp(2\pi i\beta)) \{(\rho_1 \exp(2\pi i\theta_1), z_1), (\rho_2 \exp(2\pi i\theta_2), z_2)\} \longrightarrow \{(\rho_1 \exp(2\pi i(\theta_1 + \alpha)), z_1), (\rho_2 \exp(2\pi i(\theta_2 + \beta)), z_2)\}. \text{ Then}$$

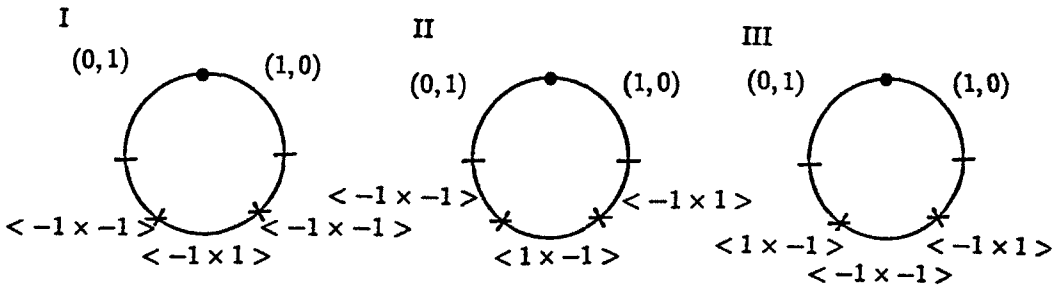


It can be checked that φ, ϕ, h and ψ commute with the T^2 -action, and the induced effective T^2 -actions on $(S^2 \times S^2)/\langle \varphi, \phi \rangle$ and $(S^2 \times S^2)/\langle h, \psi \rangle$ give the orbit spaces of I and II respectively.

Similarly, by considering closed 4-manifolds with an effective T^2 -action whose orbit spaces are of the following type



as in the previous case, the manifolds are diffeomorphic to one of the three manifolds whose orbit spaces are



Let M_1, M_2 and M_3 be the manifolds corresponding to I, II and III respectively. By looking at their orientable covers, and using the results in [Pa](Theorem VI.1), M_1 and M_3 are not homotopy equivalent to M_2 , but it is not known whether M_1 is diffeomorphic to M_3 or not. The slice theorem and simple observations prove that $\pi_1(M_1) = \pi_1(M_2) = \pi_1(M_3) = \langle \alpha, \beta, r \mid \alpha^2 = \beta^2 = r^2 = e, \alpha\beta = \beta\alpha, \beta r = r\beta \rangle$

2. (N + 1)-Manifolds with T^{n+1} action

In this section, we are going to show that if, M is a $(n + 1)$ -dimensional non-orientable manifold with an effective T^n -action, then M is diffeomorphic to $RP^2 \times T^{n-1}, K \times T^{n-1}, S^{1\sim} \times S^2 \times T^{n-2}$ or $KS \times T^{n-2}, n \geq 2$.

NOTATION 2.1. Let RP^2 be the projective plane. So we denote a point of RP^2 by $[\rho \exp 2\pi i\theta, z]$, where $[\]$ means the equivalence relation. In $S^{1\sim} \times S^2, \sim$ means every point $(\exp 2\pi i\theta, \nu)$ in $S^1 \times S^2$ is identified with $(-\exp 2\pi i\theta, -\nu)$. Let T^n be the n times product of S^1 . K denote the Klein bottle, and KS denote the total space of the non-trivial S^1 -principal bundle over K .

When $n = 2, W. Newman$ obtained the result (cf. [N]). So we will give a proof by using techniques in [OR] and prove the general case.

LEMMA 2.2. *Let M be a 3-dimensional manifold with an effective T^2 -action. Then M is diffeomorphic to $K \times S^1, S^{1\sim} \times S^2, RP^2 \times S^1$ or KS .*

Proof. By the slice theorem, and by using an automorphism of T^2 , we can see that M^* must be one of the following four orbit spaces which

are the intervals with "weights".

$$(i) \begin{matrix} (0,1) \\ \langle -1 \times 1 \rangle \end{matrix} \quad (ii) \begin{matrix} (0,1) \\ \langle -1 \times -1 \rangle \end{matrix} \quad (iii) \begin{matrix} \langle -1 \times 1 \rangle \\ \langle -1 \times 1 \rangle \end{matrix} \quad (iv) \begin{matrix} \langle -1 \times 1 \rangle \\ \langle -1 \times -1 \rangle \end{matrix}$$

where, on the interior of the intervals, the stabilizer is trivial and at the end points the stabilizer is a circle subgroup or, a Z_2 . By applying the same method in [K], we can show that there exist a cross section x such that $\pi \circ x = id$. So, by the cross section theorem (see [K]), we have only to construct spaces with T^2 -actions whose orbit spaces are as above.

$$\begin{aligned} (i) \quad & T^2 \times RP^2 \times S^1 \longrightarrow RP^2 \times S^1 \\ & (\exp 2\pi i \alpha, \exp 2\pi i \beta) \times ([\rho \exp 2\pi i \theta, z], \exp 2\pi i \phi) \\ & \longrightarrow ([\rho \exp 2\pi i (\theta + \alpha), z], \exp 2\pi i (\theta + \beta)) \\ (ii) \quad & T^2 \times S^{1\sim} \times S^2 \longrightarrow S^{1\sim} \times S^2 \\ & (\exp 2\pi i \alpha, \exp 2\pi i \beta) \times [\exp 2\pi i \phi, (\rho \exp 2\pi i \theta, z)] \\ & \longrightarrow [\exp 2\pi i (\phi + \beta), (\rho \exp 2(\theta + \alpha), z)] \\ (iii) \quad & T^2 \times S^{1\sim} \times S^1 \times S^1 \longrightarrow S^{1\sim} S^1 \times S^1 \\ & (\exp 2\pi i \alpha, \exp 2\pi i \beta) \times [x, y, w] \\ & \longrightarrow [x \exp 2\pi i \alpha, y, w \exp 2\pi i \beta] \end{aligned}$$

Recall that K is $S^{1\sim} \times S^1$ where every point (x, y) in $S^1 \times S^1$ is identified with $(-x, \bar{y})$, x, y are complex numbers and \bar{y} is the conjugate of y .

$$\begin{aligned} (iv) \quad & T^2 \times (S^1 \times S^1 \times S^1) / \simeq \longrightarrow (S^1 \times S^1 \times S^1) / \simeq \\ & (\exp 2\pi i \alpha, \exp 2\pi i \beta) \times [x, y, w] \\ & \longrightarrow [x \exp 2\pi i \alpha, y \exp 2\pi i \beta, w] \end{aligned}$$

Here \simeq means every point (x, y, w) in $S^1 \times S^1 \times S^1$ is identified with $(-x, y, \bar{w}), (-x, -y, -\bar{w})$ and $(x, -y, -w)$.

To finish the proof, it remains to show that $(S^1 \times S^1 \times S^1) / \simeq$ is KS . To show this, we are going to give S^1 -action on the space above and obtain a orbit space. Then, by this orbit space and results in [OR], we can see that KS is $(S^1 \times S^1 \times S^1) / \simeq$.

To give a S^1 -action, we need the following identification:

$$\begin{aligned} \psi : (S^1 \times S^1 \times S^1)/\simeq &\longrightarrow (S^1 \times S^1 \times S^1)/\sim \\ [x, y, w] &\longrightarrow [x, y^2, yw] \end{aligned}$$

Here, \sim mean every point (x, u, w) in $S^1 \times S^1 \times S^1$ is identified with $(x, y, y\tilde{w})$.

Then we can give a S^1 -action naturally by the complex multiplication on the first coordinate of $(S^1 \times S^1 \times S^1)/\sim$. The orbit space is the Möbius strip with Z_2 stabilizer on the boundary. By [OR](see Theorem 5), we can conclude that $(S^1 \times S^1 \times S^1)/\sim$ is KS . This completes the proof.

REMARK. By the homotopy exact sequence, $\pi_1(S^1 \times S^2) = \mathbb{Z}$. We see that the four spaces above are topologically different, since they have different fundamental groups (see [N]).

Before we go to the general case, we need the following:

Any circle subgroup of T^n can be expressed as

$$\{(x^{a_1}, x^{a_2}, \dots, x^{a_n}) \mid x \in S^1\}$$

where the a_i 's are relatively prime. We denote the circle subgroup by (a_1, a_2, \dots, a_n) . The following lemma supposes to be well-known.

LEMMA 2.3. Given a vector $A = (a_1, a_2, \dots, a_n)$ is \mathbb{Z}^n such that the a_i 's are relatively prime, then we can choose

$$\{(b_{1j}, b_{2j}, \dots, b_{nj}) = B_j \mid j = 1, 2, \dots, n-1\}$$

so that $A, B_1, B_2, \dots, B_{n-1}$ consist of a basis of \mathbb{Z}^n , where \mathbb{Z}^n is the n times direct sum of \mathbb{Z} .

REMARK. Given a following orbit space

$$\begin{array}{c} (a_1, a_2, \dots, a_n) \\ \Big| \\ \mathbb{Z}_2 \end{array}$$

by lemma 2.3 above, we may assume

$$\begin{array}{c} (1, 0, \dots) \\ \Big| \\ \mathbb{Z}_2 \end{array}$$

where \mathbb{Z}_2 is generated by $-1 \times 1 \times \dots \times 1$ or $1 \times -1 \times 1 \times \dots \times 1$.

Now we are ready to prove the theorem.

THEOREM 2.4. *Suppose that M is a closed non-orientable $(n + 1)$ -dimensional differential manifold with an effective T^n -action. Then M is diffeomorphic to $RP^2 \times T^{n-1}, K \times T^{n-2}, S^1 \times S^2 \times T^{n-2}$ or $KS \times T^{n-2}, n \geq 3$.*

Proof. By the slice theorem, lemma 2.3, and remark above, we have following four orbit spaces:

$$(i) \begin{array}{l} (1,0,\dots,0) \\ \left| \begin{array}{l} \\ \langle -1 \times 1 \times \dots \times 1 \rangle \end{array} \right. \end{array} \quad (ii) \begin{array}{l} (1,0,\dots,0) \\ \left| \begin{array}{l} \\ \langle 1 \times -1 \times \dots \times 1 \rangle \end{array} \right. \end{array} \quad (iii) \begin{array}{l} \langle -1 \times 1 \times \dots \times 1 \rangle \\ \left| \begin{array}{l} \\ \langle -1 \times 1 \times \dots \times 1 \rangle \end{array} \right. \end{array} \quad (iv) \begin{array}{l} \langle -1 \times 1 \times \dots \times 1 \rangle \\ \left| \begin{array}{l} \\ \langle 1 \times -1 \times \dots \times 1 \rangle \end{array} \right. \end{array}$$

Then, as in the lemma 2.2, we can give T^n -actions on the four spaces whose orbit spaces are exactly same as above. This completes the proof.

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