Pusan-Kyongnam Math. J. 7(1991), No 1, pp. 19-22

SOME *Hp*-THEOREMS FOR HYPERSURFACES

CHANG-RIM JANG

Let $M^n, n \geq 2$, be an orientable compact *n*-dimensional manifold without boundary and assume $x : M^n \to R^{n+1}$ is an isometric immersion. Sometimes, x will be considered as the position vector of M^n . For a globally defined unit normal vector field ν of M^n , we call $p = \langle x, \nu \rangle$ a support fuction of M^n . Rotondaro Giovanni [2] proved that if Hp has a constant value n, then M^n is a standard sphere centered at 0.(Here, H is the mean curvature function of M^n .) In this short note, we will prove Giovanni's theorem by some different methods. Some of the calculation in this note was inspired by computation in a paper by Gerhard Huisken[2].

1. Preliminaries

We need some definitions and lemmas. Many of them are due to [5]. $\overline{\nabla}$ denotes covariant differentiation on \mathbb{R}^{n+1} , and ∇ denotes covariant differentiation on M^n .

DEFINITIONS.

- (1) $h(X,Y) = -\langle \overline{\nabla}_x Y, \nu \rangle$ for X, Y sections of TM^n . h is the second fundamental form of the immersion. <,> means the usual inner product of \mathbb{R}^{n+1} .
- (2) For an orthonormal framing (e_1, \dots, e_n) of TM^n , $H = \sum h(e_i, e_i)$. This definition of H is independent of the framing.
- (3) The Coddazi equations, for X, Y, Z sections in TM^n , are

$$(\nabla_{\boldsymbol{x}} h)(\boldsymbol{Y}, \boldsymbol{Z}) = (\nabla_{\boldsymbol{y}} h)(\boldsymbol{X}, \boldsymbol{Z}),$$

where

$$(\nabla_x h)(Y, Z) = \nabla_x h(Y, Z) - h(\nabla_x Y, Z) - h(Y, \nabla_x Z).$$

Received January 8, 1991.

Chang-Rim Jang

- (4) The Laplacian Δf of a function f on M^n is given by $\Delta f = \sum_{i} g^{ij} \nabla_{xi} \nabla_{xj} f$, where (x_1, \dots, x_n) is a framing of M^n and $(g^{ij}) = (g_{ij})^{-1}$.
- (5) The norm of second fundamental form $|A|^2$ is given by

$$|A|^{2} = \sum g^{ij} g^{kl} h(x_{i}, x_{k}) h(x_{j}, x_{l}).$$

LEMMA 1.1. If $M^n \subset \mathbb{R}^{n+1}$ is immersed, then $n|A|^2 \geq H^2$. Equality holds if and only if M^n is a sphere.

Proof. See [5].

LEMMA 1.2 (HOPF'S MAXIMUM PRINCIPLES). If a C^2 -function f defined on $M^n \subset \mathbb{R}^{n+1}$ has a strict maximum (resp. minimum) value at $p \in M^n$, then $(\Delta f)(p) < 0$). (resp. $(\Delta f)(p) > 0$.)

Proof. See [1].

2. Proofs of *Hp*-theorem

If $M^n \subset \mathbb{R}^{n+1}$ satisfies the equation Hp = n, then we may assume H > 0 and p > 0.

THEOREM 2.1. If M^n is compact and satisfies the equation Hp = n, then M^n is a standard shere centered at 0.

Proof. We differentiate the equation $p = \langle x, \nu \rangle$ in an orthonormal frame e_1, e_2, \cdots, e_n on M^n . Then

(1)

$$\nabla_{e_i} p = \langle \overline{\nabla}_{e_i} x, \nu \rangle + \langle x, \overline{\nabla}_{e_i} \nu \rangle$$

$$= \langle e_i, \nu \rangle + \langle x, \sum h_{li} e_l \rangle$$

$$= \sum \langle x, e_l \rangle h_{li} \quad (\text{ where } h_{ij} = h(e_i, e_j))$$

(2)

$$\nabla_{e_j} \nabla_{e_i} p = \sum_{i=1}^{n} \langle \overline{\nabla}_{e_j} x, e_l \rangle h_{li} + \sum_{i=1}^{n} \langle x, \overline{\nabla}_{e_j} e_l \rangle h_{li} + \sum_{i=1}^{n} \langle x, e_l \rangle \nabla_j h_{li} + \sum_{i=1}^{n} \langle x, e_l \rangle h_{li} + \sum_{i=1}^{n} \langle x, e_l \rangle \nabla_l h_{ji} + \sum_{i=1}^{n} \langle x, e_l \rangle \nabla_l h_{ji} + \sum_{i=1}^{n} \langle x, e_l \rangle \nabla_l h_{ji} + \sum_{i=1}^{n} \langle x, e_l \rangle \nabla_l h_{ji}$$

20

Here we used again $p = \langle x, \nu \rangle$ and the Coddazi equation. (We assume $\nabla_{e_i} e_j = 0$ for all i, j.)

From (2) we obtain

$$\begin{split} \Delta p &= H - p|A|^2 + \sum \langle x, e_l \rangle \nabla_l H \\ &= H - (n|A|^2/H) + \sum \langle x, e_l \rangle \nabla_l H \\ &= (H^2 - n|A|^2)/H + \sum \langle x, e_l \rangle \nabla_l H \\ &\leq \sum \langle x, e_l \rangle \nabla_l H \end{split}$$

Since M^n is compact, p has a minimum at some point $q \in M^n$. And H has a maximum value at q. Applying the Hopf's maximum principles, we conclude that p is constant and $H^2 = n|A|^2$. This implies M^n is a standard sphere centered at 0.

REMARK 1. If $M^n \subset R^{n+1}$ is embedded and satisfies the equation Hp = n, then we can directly derive the result by using Ros' inequality[4] $\int n/H \, dA \ge nV$ and the formula $\int p \, dA = nV$.

REMARK 2. If $M^2 \subseteq R^3$ is noncompact and satisfies the equation Hp = n, we expect M is cylinder.

REMARK 3. Gerhard Huisken[2] proved that if $M^n \subset \mathbb{R}^{n+1}$ satisfies the equation H = p, then M^n is a standard sphere with radius \sqrt{n} . His computation may be applicable in several directions.

References

- 1. D. Gilbarg and N. S. Trudinger, Elliptic partial differential equations of second order, Springer, 1983.
- R. Giovanni, On the H_p-theorem for hypersurfaces, Comm. Math. Univ Carolin 30(1989), 385-387.
- G. Huisken, Asymptotic behavior for singularities of the mean carvature flow, J. Diff. Geometry 31(1990), 285-299.
- 4. A. Ros, Compact hypersurfaces with constant scalar curvature and a congruence theorem, J. Diff. Geometry 27(1988), 215-220
- 5. M. Spivak, A comprehensive introduction to differential geometry, Publish or Perish Inc., 1970.

Chang-Rim Jang

Department of Mathematics University of Ulsan Ulsan 680-749, Korea

22