

## CAUCHY PROBLEM FOR CARLEMAN EQUATION BY FINITE DIFFERENCE METHODS

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### 1. Introduction

We shall consider the coupled system of first order hyperbolic nonlinear equations

$$(1.1) \quad \begin{aligned} u_t + u_x &= v^2 - u^2 \\ v_t - v_x &= u^2 - v^2 \end{aligned}$$

with initial conditions

$$(1.2) \quad u(x, 0) = f(x), \quad v(x, 0) = g(x),$$

where  $f$  and  $g$  are bounded measurable functions. System (1.1) is known as the Carleman equation. It was developed to model the spatio-temporal behavior of the velocity distribution function of a gas whose molecules move parallel to the  $x$ -axis with constant and equal speed, either in the direction of increasing  $x$  or in the direction of decreasing  $x$ .

The initial value problem for the Carleman equation has been studied by various analytic methods [2,3,5,6,7]. In [6], Tartar stated the existence and uniqueness of the initial value problem (without proof) with bounded initial data using a fixed point argument. Later, Kaper and Leaf [5] treated the problem in a unified manner and improved some of the previous results by considering the abstract initial value problem associated to the Carleman equation. Decaying property of solutions in time was discussed in [3,5].

Here, we shall prove the uniqueness and existence of a solution for the problem (1.1) and (1.2) for bounded initial data by a finite difference method.

## 2. Main theorem and the proof of uniqueness

**DEFINITION 2.1.** A pair of bounded measurable function  $(u, v)$  is called a (weak) solution of the initial value problem (1.1) and (1.2), provided that (2.1) and (2.2) hold for all  $\phi$ , where  $\phi$  is a  $C^1$  function which vanishes outside of a compact subset in  $R \times [0, \infty)$ , that is,  $\text{supp}\phi \cap \{R \times [0, \infty)\} \subset D$ , for some rectangle  $D = \{(x, t) | a \leq x \leq b, 0 \leq t \leq T\}$ , so chosen that  $\phi = 0$  outside of  $D$  and on the lines  $t = T$ ,  $x = a$  and  $x = b$ :

$$(2.1) \quad \int_0^\infty \int_{-\infty}^\infty [u(\phi_t + \phi_x) + (v^2 - u^2)\phi] dx dt + \int_{-\infty}^\infty f(x)\phi(x, 0) dx = 0,$$

$$(2.2) \quad \int_0^\infty \int_{-\infty}^\infty [v(\phi_t - \phi_x) + (u^2 - v^2)\phi] dx dt + \int_{-\infty}^\infty g(x)\phi(x, 0) dx = 0.$$

Let  $C_0^1$  be the space of all  $C^1$  functions  $\phi$  such as in definition 2.1. We say that a bounded function  $f$  on  $R$  is of bounded variation if for any  $r > 0$  and any real number  $y$  there is a constant  $C(r) > 0$  such that

$$\int_{|x| \leq r} |f(x+y) - f(x)| dx \leq C(r)|y|.$$

**THEOREM 2.1.** For any initial data  $f$  and  $g$  of bounded variation with  $0 \leq f(x), g(x) \leq M$ , the initial value problem (1.1) and (1.2) has a unique (weak) solution  $u$  and  $v$  in  $L^\infty(R \times [0, \infty))$  with  $0 \leq u(x, t), v(x, t) \leq M$  on  $R \times [0, \infty)$ .

*Proof of uniqueness :* Let  $(u_1, v_1)$  and  $(u_2, v_2)$  be 2 sets of the solution as in theorem 2.1, and set  $u = u_1 - u_2$  and  $v = v_1 - v_2$ . Then, we have

$$(2.3) \quad \int_0^\infty \int_{-\infty}^\infty u(\phi_t + \phi_x) + (v_1^2 - v_2^2 - u_1^2 + u_2^2) dx dt = 0,$$

$$(2.4) \quad \int_0^\infty \int_{-\infty}^\infty v(\phi_t + \phi_x) + (u_1^2 - u_2^2 - v_1^2 + v_2^2) dx dt = 0.$$

Adding (2.3) and (2.4) gives

$$(2.5) \quad \int_0^\infty \int_{-\infty}^\infty (u + v)(\phi_t + \phi_x) dx dt = 0.$$

Since, for any given  $\psi \in C_0^1$ , we can solve  $\phi_t + \phi_x = \psi$  for  $\phi \in C_0^1$ ,  $u + v = 0$  a.e. for  $t \geq 0$ . Then,  $u = v = 0$  a.e. for  $t \geq 0$  since  $u \geq 0$  and  $v \geq 0$  for  $t \geq 0$ .

### 3. Approximate solutions by a finite difference method

For any fixed  $T > 0$  and a positive integer  $n$ , let  $h = \frac{T}{n}$  and  $Q_T = R \times [0, T]$ .

First we shall construct an approximate solution on  $Q_T$  by using a finite difference scheme.

Define  $f_k(x)$  and  $g_k(x)$  for  $0 \leq k \leq n$  inductively as :

$$(3.1) \quad f_0(x) = f(x), \quad g_0(x) = g(x)$$

$$(3.2) \quad f_{k+1}(x) = f_k(x - h) + h[g_k^2(x - h) - f_k^2(x - h)]$$

$$(3.3) \quad g_{k+1}(x) = g_k(x + h) + h[f_k^2(x + h) - g_k^2(x + h)].$$

Define approximate solutions  $u_n(x, t)$  and  $v_n(x, t)$  on  $Q_T$  as

$$(3.4) \quad u_n(x, t) = f_k(x), \quad kh \leq t < (k + 1)h$$

$$(3.5) \quad v_n(x, t) = g_k(x), \quad kh \leq t < (k + 1)h, \quad 0 \leq k \leq n - 1.$$

LEMMA 3.1. If  $n$  is so large that  $2Mh \leq 1$ , then for  $0 \leq k \leq n$ ,

$$(3.6) \quad 0 \leq f_k(x), g_k(x) \leq M.$$

*Proof.* It follows immediately from (3.2) and (3.3) by induction on  $k$ . From now on, we always assume that  $2Mh \leq 1$  and that  $f$  and  $g$  are the same as in Theorem 2.1.

**LEMMA 3.2.** *The function  $f_k(x)$  and  $g_k(x)$  are also of bounded variation. Moreover, for each  $r > 0$ , there is a constant  $C(r) > 0$  (independent of  $k$  and  $n$ ) such that*

$$(3.7) \quad \int_{|x| \leq r} |f_k(x+h) - f_k(x)| dx \leq C(r)h$$

$$(3.8) \quad \int_{|x| \leq r} |g_k(x+h) - g_k(x)| dx \leq C(r)h.$$

*Proof.* For each  $r > 0$ , let  $C_0(r) > 0$  be such that

$$C_0(r) > \max \left\{ \sup_{y \neq 0} \frac{1}{|y|} \int_{|x| \leq r} |f(x+y) - f(x)| dx, \right. \\ \left. \sup_{y \neq 0} \frac{1}{|y|} \int_{|x| \leq r} |g(x+y) - g(x)| dx \right\}.$$

We claim that for  $0 \leq k \leq n$

$$(3.9) \quad \int_{|x| \leq r} |f_k(x+h) - f_k(x)| dx, \int_{|x| \leq r} |g_k(x+h) - g_k(x)| dx \\ \leq C_0(r)h(1 + 4Mh)^k.$$

When  $k = 0$ , it is obvious. Assume that it is true up to  $k$ . From (3.2) and (3.6), we get

$$|f_{k+1}(x+h) - f_k(x)| \leq |f_k(x) - f_k(x-h)| + 2Mh|g_k(x) - g_k(x-h)| \\ + 2Mh|f_k(x) - f_k(x-h)|$$

from which  $(3.9)_{k+1}$  follows immediately for  $f$  and so similarly for  $g$ . Since  $(1 + 4Mh)^k \leq (1 + 4MT/n)^n \leq \exp(4MT)$ ,  $0 \leq k \leq n$ , we may take  $C(r) = C_0(r) \exp(4MT)$ .

LEMMA 3.3. For each  $r > 0$ , there is a constant  $d(r) > 0$  such that

$$(3.10) \quad \int_{|x| \leq r} |f_{k+1}(x) - f_k(x)| dx \leq d(r)h$$

$$(3.11) \quad \int_{|x| \leq r} |g_{k+1}(x) - g_k(x)| dx \leq d(r)h.$$

*Proof.* For example, (3.10) follows easily from (3.2), (3.6) and (3.7) with  $d(r) = C(r) + 4M^2r$ , where  $C(r)$  is the constant found in Lemma 3.2.

#### 4. Convergence of approximate solutions

Let us consider the space  $L^1_{loc}(R)$  with the metric

$$d(\phi, \psi) = \sum_{j=1}^{\infty} 2^{-j} \frac{\|\phi - \psi\|_j}{1 + \|\phi - \psi\|_j}$$

where  $\|\phi\|_j = \int_{|x| \leq j} |\phi(x)| dx$  so that a sequence  $\{\phi_j(x)\}$  converges to  $\phi$  in  $L^1_{loc}(R)$  iff it converges to  $\phi$  in  $L^1(K)$  for every compact subset  $K$  of  $R$ . We need the following elementary facts (cf. [1,4]).

LEMMA 4.1. If  $H$  is a bounded subset of  $L^\infty(R)$  satisfying for each  $r > 0$

$$(4.1) \quad \limsup_{h \rightarrow 0} \sup_H \int_{|x| \leq r} |\phi(x+h) - \phi(x)| dx = 0$$

then  $H$  is precompact in  $L^1_{loc}(R)$ .

LEMMA 4.2. Let  $X$  be a separable space and  $Y$  a complete metric space with metric  $d$ . If a sequence  $\{\phi_j\} : X \rightarrow Y$  of continuous functions satisfy

- (a) for any  $p$  in  $X$  and  $\epsilon > 0$ , there is an integer  $N$  and a neighborhood  $U(p)$  of  $p$  such that

$$d(\phi_j(p), \phi_j(q)) < \epsilon \text{ if } j \geq N \text{ and } q \in U(p)$$

- (b) for any fixed  $p$  in  $X$ , the set  $\{\phi_j(p) \mid j \geq 1\}$  is precompact in  $Y$ , then there is a subsequence of  $\{\phi_j\}$  which converges to a continuous function on  $X$  uniformly on any compact subset of  $X$ .

For  $n$  large so that  $2Mh \leq 1$ , consider the sequence of approximate solutions  $\{u_n(x, t)\}$  and  $\{v_n(x, t)\}$ . We may view (cf. Lemma 3.3)  $u_n(x, t) = u_n(t)(x)$  and  $v_n(x, t) = v_n(t)(x)$  as continuous functions on  $[0, T]$  valued in  $L^1_{loc}(R)$ .

LEMMA 4.3. The sequences  $\{u_n(t)\}$  and  $\{v_n(t)\}$  satisfy the conditions (a) and (b) of Lemma 4.2.

*Proof.* (a): For any  $\epsilon > 0$ , choose  $N$  so large that  $\sum_{j>N} 2^{-j} < \frac{\epsilon}{2}$ . Then by Lemma 3.3, we have

$$\begin{aligned} d(u_n(t), u_n(s)) &\leq \sum_{j=1}^N 2^{-j} \|u_n(t) - u_n(s)\|_j + \frac{\epsilon}{2} \\ &\leq \|u_n(t) - u_n(s)\|_N + \frac{\epsilon}{2} \\ &\leq d(N)|t - s| + \frac{\epsilon}{2}. \end{aligned}$$

Hence, it's enough to require  $d(N)|t - s| < \epsilon/2$ .

(b): For any fixed  $t$  in  $[0, T]$ ,  $\{u_n(t)\}$  is a bounded subset of  $L^\infty(R)$  by (3.4) and (3.6). Hence, by Lemma 4.1, it suffices to show (4.1) for  $\{u_n(t)\}$ . But it is immediate from (3.7) since  $u_n(t)(x) = f_k(x)$  for some  $k$  for any fixed  $t$ . The proof for  $\{v_n(t)\}$  is the same as that of  $\{u_n(t)\}$ .

Hence, by Lemma 4.2, we may assume that the sequences  $\{u_n\}$  and  $\{v_n\}$  converge to  $u(x, t)$  and  $v(x, t)$  in  $L^1_{loc}(Q_T)$  respectively and so

$$0 \leq u(x, t), v(x, t) \leq M \text{ a.e. in } Q_T$$

by choosing subsequences if necessary.

Since  $T > 0$  is arbitrary, the function  $u$  and  $v$  are in fact defined on  $R \times [0, \infty)$  as bounded locally integrable functions.

Finally, we shall prove that the pair  $(u, v)$  is a solution of (1.1) and (1.2) although it's quite standard at this moment. Let  $\phi$  be any function

in  $C_0^1$  and choose  $T > 0$  so large that  $\text{supp } \phi \cap \{t \geq 0\} \subset Q_T$ . Multiply (3.3) by  $\phi(x, kh)$  to get

$$(4.2) \quad \begin{aligned} & f_{k+1}(x) \frac{\phi(x, (k+1)h) - \phi(x, kh)}{h} + f_k(x-h) \frac{\phi(x, kh) - \phi(x-h, kh)}{h} \\ & + (g_k^2(x-h) - f_k^2(x-h))\phi(x, kh) \\ & + \frac{1}{h} [f_k(x-h)\phi(x-h, kh) - f_{k+1}(x)\phi(x, (k+1)h)] = 0 \end{aligned}$$

Multiply (4.2) by  $h$ , sum over  $k = 0, \dots, n-1$  and then integrate with respect to  $x$  over  $R$ .

$$(4.3) \quad \begin{aligned} & \int_{-\infty}^{\infty} \sum_{k=0}^{n-1} h f_{k+1}(x) \frac{\phi(x, (k+1)h) - \phi(x, kh)}{h} dx \\ & + \int_{-\infty}^{\infty} \sum_{k=0}^{n-1} h f_k(x-h) \frac{\phi(x, kh) - \phi(x-h, kh)}{h} dx \\ & + \int_{-\infty}^{\infty} \sum_{k=0}^{n-1} h (g_k^2(x-h) - f_k^2(x-h))\phi(x, kh) dx \\ & + \int_{-\infty}^{\infty} \sum_{k=0}^{n-1} [f_k(x-h)\phi(x-h, kh) \\ & \quad - f_{k+1}(x)\phi(x, (k+1)h)] dx = 0 \end{aligned}$$

Since  $\phi(x, nh) = \phi(x, T) = 0$ , the last term in (4.3) becomes

$$\int_{-\infty}^{\infty} f(x)\phi(x, 0)dx. \text{ Since } \phi \text{ is smooth, } \phi(x, t) = 0 \text{ for } t \geq T \text{ and}$$

$$h f_k(x) = \int_{kh}^{(k+1)h} u_n(x, t) dt, \text{ (4.3) may be rewritten as}$$

$$(4.4) \quad \int_0^{\infty} \int_{-\infty}^{\infty} [u_n(\phi_t + \phi_x) + (v_n^2 - u_n^2)\phi] dx dt + \int_{-\infty}^{\infty} f(x)\phi(x, 0)dx + \delta(h) = 0$$

where  $\delta(h) \rightarrow 0$  as  $h \rightarrow 0$ , i.e.,  $n \rightarrow \infty$ . Noting that the integrations in (4.4) are in fact carried over compact sets, we get (2.1) as  $n \rightarrow \infty$ . Similarly, we can also get (2.2).

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