

## A Contour-Integral Derivation of the Asymptotic Distribution of the Sample Partial Autocorrelations with Lags Greater than $p$ of an AR( $p$ ) Model<sup>+</sup>

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### ABSTRACT

The asymptotic distribution of the sample partial autocorrelation terms after lag  $p$  of an AR( $p$ ) model has been shown by Dixon(1944). The derivation is based on multivariate analysis and looks tedious. In this paper we present an interesting contour-integral derivation.

### 1. Introduction

Consider the autoregressive model of order  $p$ , AR( $p$ ),

$$\phi(B)y_t = v_t, \quad (1.1)$$

where  $\phi(B) = 1 - \phi_1 B - \dots - \phi_p B^p$ ,  $\phi_0 = 1$ ,  $B$  is the backshift operator and  $\{v_t\}$  is a sequence of independent and identically distributed random variables with  $E(v_t) = 0$ ,  $E(v_t^2) = \sigma^2$  and  $E(v_t^4) = 3\sigma^4 + k_4 (< \infty)$ . We assume that the process is stationary, i.e., the equa-

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tion  $\phi(z)=0$  has all the roots outside the unit circle. Let  $\{\sigma(l)\}$  and  $\{\rho_l\}$  be the autocovariance function, ACVF, and the autocorrelation function, ACRF, respectively. The stationarity implies that the ACRF satisfies the following Yule-Walker equations:

$$\rho_j = \phi_1 \rho_{j-1} + \dots + \phi_p \rho_{j-p}, \quad j = 1, 2, \dots, \quad (1.2)$$

$$\sum_{l=1}^p \phi_l \rho_l = -\sigma^2 / \sigma(0). \quad (1.3)$$

Henceforth we denote  $(x_n, \dots, x_1)^t$  by  $\tilde{\mathbf{x}}$  for any vector  $\mathbf{x} = (x_n, \dots, x_1)^t$ . Let  $\underline{\rho}(k) = (\rho_1, \dots, \rho_k)^t$ . For a positive integer  $k$ , we define a  $k$  by  $k$  Toeplitz matrix  $B(k)$  with  $(l, m)$  element  $\rho_{l-m}$ . Since  $B(k)$  is positive definite, we can define some vectors:

$$\begin{aligned} \underline{\phi}(k) &= B(k)^{-1} \underline{\rho}(k), \\ \theta(k) &= \rho_{k+1} - \underline{\tilde{\phi}}(k)^t \underline{\rho}(k), \\ \lambda(k) &= 1 - \underline{\rho}(k)^t \underline{\phi}(k) \end{aligned}$$

for  $k = 1, 2, \dots$ . Then,  $\underline{\phi}(k)$  is the solution vector of the Yule-Walker equations (1.2) for  $j = 1, \dots, k$ , which can be efficiently solved by the Levinson(1947) and Durbin(1960) algorithm:

$$\begin{aligned} \underline{\tilde{\phi}}(k+1) &= \begin{pmatrix} \underline{\phi}(k) - \theta(k) \underline{\tilde{\phi}}(k) / \lambda(k) \\ \theta(k) / \lambda(k) \end{pmatrix} \\ \lambda(k+1) &= \lambda(k) \{1 - \theta(k)^2 / \lambda(k)^2\}. \end{aligned}$$

The initial values are  $\theta(0) = \rho_1$  and  $\lambda(0) = 1$ . Hereafter we denote the  $l$ -th element of  $\underline{\phi}(k)$  by  $\phi_{k,l}$  and let  $\phi_{k,0} = -1$ .

For a given realization  $\{y_1, \dots, y_T\}$  we estimate the ACVF and the ACRF by

$$\hat{\sigma}(i) = \frac{1}{T} \sum_{l=1}^{T-i} (y_{l+i} - \bar{y})(y_l - \bar{y}) \quad \text{and} \quad \hat{\rho}_i = \hat{\sigma}(i) / \hat{\sigma}(0)$$

where  $\bar{y} = \Sigma y_l / T$ . When the sample ACRF is used instead of the ACRF, the solutions of the Yule-Walker equations are called the Yule-Walker estimates of the AR parameters. Throughout this note we use the sample ACRF and the Yule-Walker estimates. Other parameters are estimated by putting the sample ACVF and the Yule-Walker estimates

instead of the ACVF and the AR coefficients into their definitions.

It is well-known that the partial autocorrelation at lag  $k$  is equal to  $\phi_{k,k}$ . Thus we can redefine it as follows.

**Definition 1.1** The partial autocorrelation at lag  $k$  is defined by

$$\phi_{k,k} = \theta(k-1) / \lambda(k-1), \quad k = 1, 2, \dots.$$

It is known (Dixon [1944] and Quenouille[1949]) that if the underlying process is from an AR( $p$ ) model then  $\phi_{k,k}$ 's,  $k > p$ , are asymptotically independent and identical random variables. The purpose of this paper is to present a neat derivation of the asymptotic distribution using complex analysis.

## 2. The contour integral derivation

The nonsingularity of  $B(k)$  and the consistency of the sample ACRF imply the following property. (See, e.g., Tsay and Tiao[1984].)

**Property 2.1** If the underlying process is from the AR( $p$ ) model in (1.1), then the following holds for  $k(\geq p)$ .

- (a)  $\hat{\phi}(k) = (\phi_1, \dots, \phi_p, 0, \dots, 0)^t$ .
- (b)  $\hat{\phi}_{k,l} = \phi_l + O_p(T^{-1/2})$ , where  $\phi_l$  is understood to be 0 for  $l > p$ .
- (c)  $\hat{\lambda}(k)$  is consistent to  $\sigma^2/\sigma(0)$ .

The following asymptotic property of the sample ACRF is due to Bartlett(1946).

**Property 2.2** If  $\{y_1, \dots, y_T\}$  is a  $T$ -realization of the AR( $p$ ) process in (1.1), the random variables  $T^{1/2}(\hat{\rho}_1 - \rho_1), \dots, T^{1/2}(\hat{\rho}_n - \rho_n)$  have asymptotic normal distributions with means 0 and covariances

$$\begin{aligned} & \lim_{T \rightarrow \infty} T \text{COV}(\hat{\rho}_g, \hat{\rho}_h) \\ &= \frac{4\pi}{\sigma^2(0)} \int_{-\pi}^{\pi} (\cos \lambda h - \rho_h) (\cos \lambda g - \rho_g) S^2(\lambda) d\lambda \end{aligned}$$

where  $S(\lambda)$  is the spectral density of the AR process, i.e.,

$$S(\lambda) = \frac{\sigma^2}{2\pi} |\phi(e^{i\lambda})|^{-2}.$$

**Theorem.** If  $\{y_1, \dots, y_T\}$  is from the AR(p) model in (1.1), then, for  $k > p$ ,  $T^{1/2} \hat{\phi}_{k,k}$ 's are asymptotically independent normal random variables with means 0 and variances 1.

**Proof.** If we let  $\phi_{k-1,0} = -1$ , then the sampled version of the Yule-Walker equations imply that

$$\hat{\theta}(k-1) = -\sum_{r=0}^{k-1} \sum_{s=0}^{k-1} \hat{\phi}_{k-1,r} \hat{\phi}_{k-1,s} \hat{\rho}_{k-r-s}.$$

Then, Property 2.1(b) implies that  $\hat{\theta}(k-1)$  equals

$$\begin{aligned} & -\sum_{r=0}^{k-1} \sum_{s=0}^{k-1} \{\phi_r + O_p(T^{-1/2})\} \{\phi_s + O_p(T^{-1/2})\} \hat{\rho}_{k-r-s} \\ & = -\sum_{r=0}^p \sum_{s=0}^p \phi_r \phi_s \hat{\rho}_{k-r-s} + O_p\left(\frac{1}{T}\right). \end{aligned}$$

Thus,  $T^{1/2} \hat{\theta}(k-1)$  has the same asymptotic distribution as

$$V_k = -T^{1/2} \sum_{r=0}^p \sum_{s=0}^p \phi_r \phi_s \hat{\rho}_{k-r-s}.$$

We are going to show that, for  $k > p$ , the random variables  $V_k$ 's are asymptotically independently and normally distributed with means 0 and variances

$$\lim_{T \rightarrow \infty} \text{Var}(V_k) = \{\sigma^2 / \sigma(0)\}^2.$$

It is known (see, e.g., Anderson[1971, p.217]) that the random variables  $V_k$  and  $V_j$  are asymptotically normally distributed. The consistency of the sample ACRF and the Yule-Walker equations imply that their means are zeroes. Property 2.2 implies that the asymptotic covariance is

$$\begin{aligned} & \lim \text{COV}(V_j, V_k) \\ & = \lim_{T \rightarrow \infty} T \sum_{r=0}^p \sum_{s=0}^p \phi_r \phi_s \sum_{u=0}^p \sum_{v=0}^p \phi_u \phi_v \text{Cov}(\hat{\rho}_{k-r-s}, \hat{\rho}_{j-u-v}) \\ & = \frac{2\pi}{\sigma^2(0)} \int_{-\pi}^{\pi} \sum_{r=0}^p \sum_{s=0}^p \sum_{u=0}^p \sum_{v=0}^p \phi_r \phi_s \phi_u \phi_v e^{i\lambda(k+j-r-s-u-v)} S^2(\lambda) d\lambda \\ & \quad + \frac{2\pi}{\sigma^2(0)} \int_{-\pi}^{\pi} \sum_{r=0}^p \sum_{s=0}^p \sum_{u=0}^p \sum_{v=0}^p \phi_r \phi_s \phi_u \phi_v e^{i\lambda(k-j-r-s+u+v)} S^2(\lambda) d\lambda \end{aligned}$$

$$\begin{aligned}
& -\frac{8\pi}{\sigma^2(0)} \int_{-\pi}^{\pi} \sum_{r=0}^p \sum_{s=0}^p \sum_{u=0}^p \sum_{v=0}^p \phi_r \phi_s \phi_u \phi_v \rho_{j-u-v} e^{i\lambda(k-r-s)} S^2(\lambda) d\lambda \\
& + \frac{4\pi}{\sigma^2(0)} \int_{-\pi}^{\pi} \sum_{r=0}^p \sum_{s=0}^p \sum_{u=0}^p \sum_{v=0}^p \phi_r \phi_s \phi_u \phi_v \rho_{k-r-s} \rho_{j-u-v} S^2(\lambda) d\lambda .
\end{aligned}$$

If we let  $Z=\exp(i\lambda)$ , then the first integral of the RHS equals

$$\left(\frac{\sigma^2}{2\pi}\right)^2 \oint_C Z^{k+j} \left\{ \frac{\phi(Z^{-1})}{\phi(Z)} \right\}^2 \frac{1}{iz} dz$$

where  $C$  is the unit circle with its center at the origin. Since  $\phi(z)$  has all the zeroes outside the unit circle, and since  $j+k$  is greater than  $2p$ , the integrand has no poles inside or on the simple closed curve  $C$ . Cauchy's integral formula yields that the first integral is zero. The third integrand equals

$$\left\{ \sum_{r=0}^p \sum_{s=0}^p \phi_r \phi_s e^{i\lambda(k-r-s)} \right\} \left\{ \sum_{u=0}^p \sum_{v=0}^p \phi_u \phi_v \rho_{j-u-v} \right\} S^2(\lambda)$$

Its second factor is equal to zero by (1.2), because  $j > 0$ . Similarly we can show that the fourth integrand is zero. The second integral equals

$$\begin{aligned}
& \int_{-\pi}^{\pi} e^{i\lambda(k-j)} \phi^2(\bar{e}^{-i\lambda}) \phi^2(e^{i\lambda}) \left\{ \frac{\sigma^2}{2\pi} \frac{1}{|\phi(e^{i\lambda})|^2} \right\}^2 d\lambda \\
& = \left(\frac{\sigma^2}{2\pi}\right)^2 \int_{-\pi}^{\pi} e^{i\lambda(k-j)} d\lambda \\
& = \left(\frac{\sigma^4}{2\pi}\right) \delta_{k,j} ,
\end{aligned}$$

where  $\delta_{k,j}$  is the Kronecker delta. Thus,

$$\lim_{T \rightarrow \infty} \text{COV}(V_k, V_j) = \{\sigma^2/\sigma(0)\}^2 \delta_{k,j}.$$

We know that  $T^{1/2} \hat{\phi}_{k,k} = T^{1/2} \hat{\theta}(k-1) / \hat{\lambda}(k-1)$ . Since Property 2.1(c) says that the denominator  $\hat{\lambda}(k-1)$  is consistent to  $\sigma^2/\sigma(0)$ ,  $T^{1/2} \hat{\phi}_{k,k}$ 's are asymptotically independently normally distributed with means 0 and variances 1. ■

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