## OSCILLATORY BEHAVIOUR OF SOLUTIONS OF $y^{\prime \prime}+\boldsymbol{P}(\boldsymbol{x}) \boldsymbol{y}=\boldsymbol{f}(\boldsymbol{x})$

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Abstract: This paper is a study of the oscillatory and asymptotic behaviour of solutions of the second order nonhomogeneous linear differential equation $y^{\prime \prime}+P(x) y=f(x)$, and the associated homogeneous equation. Conditions are determined, under which the nonhomogeneous equation is oscillatory if and only if the homogeneous equation is oscillatory.

## 1. Introduction

This paper is concerned with the oscillatory and asymptotic behaviour of solutions of the second order nonhomogeneous linear differential equation

$$
\begin{equation*}
y^{\prime \prime}+P(x) y=f(x), \tag{NH}
\end{equation*}
$$

in relation to the associated homogeneous equation

$$
\begin{equation*}
y^{\prime \prime}+P(x) y=0, \tag{H}
\end{equation*}
$$

where $P(x)$ and $f(x)$ are assumed to be continuous real-valued functions on the infinite half axis $[a, \infty)$, for some real number $a$. It is also assumed that $f^{\prime}(x) \leq 0, p^{\prime}(x) \geq 0$. The authors [1-8], as example, have obtained results for these equations. This paper will extend their work.

DEFINITIONS. (1) We say a solution of (NH) is oscillatory on $I=[a, \infty)$ if it has on infinite number of zeros on $[\alpha, \infty)$ for every $\alpha \geq 0$. A solution is said to be nonoscillatory on $I$ if it has only a finite number of zeros on $I$ for some $x \geq a$. Further, the equation (NH) is oscillatory if it has at least one oscillatory solution and is nonoscillatory if all solutions are nonoscillatory.
(2) A solution of $(H)$ is oscillatory if it has an infinite number of zeros on $I$ and is nonoscillatory if it has only a finite number of zeros on $I$. As for $(N H)$, the equation $(H)$ is oscillatory if it has at least one oscillatory solution and is nonoscillatory if no solution of $(H)$ is oscillatory on $I$. By the Strum interlacing theorem, $(H)$ is oscillatory if and only if all solutions are oscillatory.
(3) A solution of $(H)$ is called quickly oscillatory if it is oscillatory and sequence of zeros $\left\{x_{n}\right\}$ is such that $\lim _{n \rightarrow \infty}\left(x_{n+1}-x_{n}\right)=0$.

The difference between an oscillatory solution of $(H)$ and an oscillatory solution of $(N H)$ is illustrated by the simple equation $y^{\prime \prime}(x)=f(x)$, where

$$
f(x)=\left\{\begin{array}{cr}
0 & , x=0 \\
\left(20 x^{3}-x\right) \sin \frac{1}{x}-8 x^{2} \cos \frac{1}{x}, & x \in(0, \infty)
\end{array}\right.
$$

It is easily verified that $y(x)=x^{5} \sin \left(\frac{1}{x}\right)$ is a solution of this equation. Moreover, this solution has infinitely many zeros on $[0,1]$, and yet this solution is nonzero on $[1, \infty)$. Such a solution, we wish to call nonoscillatory. This behaviour does not occur in equation $(H)$ since the only solution of $(H)$ having infinitely many zeros on a finite interval is the trivial solution (i.e. the identically zero solution). However, one can show that if $f(x) \neq 0$ on any finite interval, then any solution of $(N H)$ has only a finite number of zeros on that intervals.

Let $u(x)$ and $v(x)$ be any two functions of $C^{1}$-class, the Wronskian $W[u, v](x)$ $=u(x) v^{\prime}(x)-u^{\prime}(x) v(x)$. If $\{u(x), v(x)\}$ is a solution basis for (H) on $I$, it follows that $W[u, v](x)=k$, where $k$ is nonzero constant. The solution basis will be called a normalized solution basis for $(H)$ if $k=1$.

Throughout this paper, we will use frequently the following lemma (Burton [2], Leighton [5]).

LEMMA A. If $W[u, v](x) \neq 0$ on $[a, \infty)$, then the zeros of $u(x)$ and $v(x)$ separate each other on $I$.

In our analysis we shall frequently employ the following identity which may be verified by differentiation,

$$
\begin{equation*}
W[u, \quad y](x)=\int_{a}^{x} f(t) u(t) d t \tag{1.1}
\end{equation*}
$$

where $y(x)$ is the solution of (NH) and $u(x)$ is any solution of $(H)$. The particular solution $y_{p}$ of $(N H)$ can be written in the form

$$
y_{p}=\int_{0}^{x}\left|\begin{array}{cc}
u(x) & v(x) \\
u(t) & v(t)
\end{array}\right| f(t) d t,
$$

where $\{u, v\}$ is normalized solution basis for $(H)$, and hence the solution $y$ of $(N H)$ has the form

$$
y(x)=\left[C_{1}-\int_{a}^{x} f(t) v(t) d t\right] u(x)+\left[C_{2}+\int_{a}^{x} f(t) u(t) d t\right] v(x),
$$

where $C_{1}$ and $C_{2}$ are arbitrary constants.

## 2. Main results

Now, we are able to study the oscillatory and asymptotic behaviour of solutions of $(\mathrm{NH})$ and $(H)$.

THEOREM 1. The function $W[u, y](x) \neq 0$ on $I$ if and only if $y(x)$ has only simple zeros and the zeros of $y(x)$ and $u(x)$ separate each other on $I$.

PROOF. Lemma A implies that if $W[u, y](x) \neq 0$ on $I$, then the zeros of $y(x)$ are simple and the zeros of $y(x)$ and $u(x)$ separate each other on $I$ independent of $f(x)$. Now, assume that $x_{1}$ and $x_{2}$ are any two consecutive zeros of $y(x)$, $x_{3}$ and $x_{4}$ are two consecutive zeros of $u(x)$, such that, $x_{1}<x_{3}<x_{2}<x_{4}$.

We can assume, without loss of generality $y(x)>0$ on $\left(x_{1}, x_{2}\right)$ and $u(x)<0$ on $\left(x_{3}, x_{4}\right)$. It follows that $W\left[u\left(x_{i}\right), y\left(x_{i}\right)\right]>0, i=1,2,3,4$. We have, from (1.1), $W[u, y](x)=\int_{a}^{x} f(t) u(t) d t$. If there exists a point $\xi \in\left(x_{1}, x_{3}\right)$ such that $W[u, y](\xi)=0$, then there must exist a point $\eta \in\left(x_{1}, x_{3}\right)$ such that $W^{\prime}[u, y](\eta)$ $=0$. This implies $f(\eta) u(\eta)=0$ or $u(\eta)=0$ contradicting the separation of zeros of $u(x)$ and $y(x)$. Then, it follows that $W[u, y] \neq 0$ on $\left(x_{1}, x_{3}\right)$ and similarly $W[u, y] \neq 0$ on $\left(x_{3}, x_{4}\right)$. This completes the proof of the theorem.

THEOREM 2. If $f(x)$ is a solution of $(H)$, then (NH) is oscillatory if and only if $(H)$ is oscillatory.

PROOF. From (1.1) we obtain $W[f, y](x)=\int_{a}^{x} f^{2}(t) d t$. It follows that $W^{\prime}[f$, $y] \geq 0$. Since $f(x) \neq 0$ on any subinterval of $I$, then $W[f, y]$ has at most one zero on $[a, \infty)$ and the result follows.

THEOREM 3. If $(H)$ is oscillatory, then all nonoscillatory solutions of $(N H)$ are eventually of the same sign. Moreover, if $f(x) \neq 0$ for large $x$, then all nonoscillatory solutions of $(N H)$ are eventually of the same sign as $f(x)$.

PROOF. Let $(H)$ be oscillatory, and suppose that $y_{1}$ and $y_{2}$ are nonoscillatory solutions of $(N H)$ such that the $\operatorname{sign} y_{1}(x) \neq \operatorname{sign} y_{2}(x)$ for large $x$. Then, $y_{1}-$ $y_{2}$ is nonoscillatory solution of $(H)$ which is a contradiction to the hypothesis. Suppose that $f(x) \neq 0$ on $I$ and that $y(x)$ is nonoscillatory solution of (NH) such that $\operatorname{sign} y(x) \neq \operatorname{sign} f(x)$ on $[b, \infty), b \geq a$. It follows that $y$ is a solution of the homogeneous equation $\omega^{\prime \prime}+(p-f / y) \omega=0$.

By Strum comparison theorem, this implies $(H)$ must be nonoscillatory, which is a contradiction. Hence, $\operatorname{sign} y=\operatorname{sign} f$ for large $x$. This completes the proof.

Equation (NH) can be written in the form:

$$
y^{\prime \prime}=p(x)[h(x)-y(x)]
$$

where $h(x)=f(x) / p(x), p(x) \neq 0$ for every $x \in[a, \infty), h(x) \in C^{2}$. We note that $y(x)$ is a solution of $(N H)$ then $\omega(x)=y(x)-h(x)$ is a solution of $\omega^{\prime \prime}+p(x) \omega=$ $-h^{\prime \prime}(x)$. If an integration by parts is performed on the left hand member of (1.1) we get

$$
\begin{equation*}
\int_{a}^{x} h^{\prime}(t) u^{\prime}(t) d t=\left[y^{\prime}(t) u(t)-(y(t)-h(t)) u^{\prime}(t)\right]_{a}^{x} . \tag{2.1}
\end{equation*}
$$

THEOREM 4. Suppose $(H)$ is oscillatory and $h(x) \in C^{2}$
(i) If $h(t)$ is an increasing function and bounded above, then no solution stays above $h(x)$ on $I$.
(ii) If $h(x)$ is a decreasing function and bounded below, then no solution stays above $h(x)$ on $I$.

PROOF. We shall prove (ii), the proof of (i) straightforward. Let $h(x)$ be the solution of $(H)$ such that $u(a)>0, u^{\prime}(a)=0$. It follows that there exists a point $b>a$ such that $u^{\prime}(b)=0$ and $u^{\prime}(x)<0$ on $(a, b)$. If $y(x)$ is a solution of $(N H)$ with $y(a)>h(a)$, then either $y^{\prime}(a) \leq 0$ or by using identity (2.1) with $x=b$, $y^{\prime}(b)<0$. In either case, since $y^{\prime}(x)<0$ for $y(x)>h(x)$, it follows that $y(x)$ must cut $h(x)$. This completes the proof.

THEOREM 5. Let $f(x)$ change sign on every interval $(b, \infty), b \geq a$. If belween every pair of succesive sign change points $b_{1}, b_{2}$, (with $\left(b_{1}<b_{2}\right)$ ), of $f(x)$, there exists a nontrivial solution of $(H)$ such that $u\left(b_{1}\right)=0$ and $u(c)=0$ for $C \in\left[b_{1}, b_{2}\right]$, then $(N H)$ is oscillatory.

PROOF. Suppose that $y(x)$ is nonoscillatory. Consider the cases:
(i) Assume $y(x)>0$ for $x \geq d, d>a$, and let $b_{1}$ and $b_{2}$ be consecutive sign change points of $f(x)$ with $b_{2}>b_{1}>d$. Rewrite (1.1) in the form

$$
\begin{equation*}
W[y, u]=\int_{b_{1}}^{c} f(t) u(t) d t \tag{2.2}
\end{equation*}
$$

Our hypothesis allows us to assume that $f(x) \leq 0$ in $\left[b_{1}, b_{2}\right]$ and $u>0$ in ( $b_{1}$, $c)$. It follows, from (2.2) that $y(c) u^{\prime}(c)>y\left(b_{1}\right) u^{\prime}\left(b_{1}\right)>0$, which contradicts that fact that $y(c) u^{\prime}(c)<0$.
(ii) Assume that $y(x)<0$ for $x \geq d, d>a$, then we can find consecutive sign change points $b_{1}$ and $b_{2}$ of $f(x)$ such that $f(x) \geq 0$ on $\left[b_{1}, b_{2}\right]$ and a solution $u(t)$ of $(H)$ with $u\left(b_{1}\right)=u(c)=0$ and $u>0$ on ( $b, c$ ) for some $c \in\left[b_{1}, b_{2}\right] \subset I$. Again by (2.2) we arrive at a contradiction. This completes the proof.

THEOREM 6. Suppose that $(H)$ is oscillatory and let the distance between consecutive sign change points of $f(x), b_{1}, b_{2}$ with $b_{2}>b_{1}$ be bounded below by $a$ constant $M>0$. If for any solution $u(x)$ of $(H)$ every pair consecutive zeros $x_{1}$, $x_{2}$ are such that $\left|x_{1}-x_{2}\right| \leq M$, then $(N H)$ is oscillatory.

PROOF. Assume that $u\left(b_{1}\right)=0$ and $u^{\prime}\left(b_{1}\right)>0$. Our hypothesis implies $u(x)$ to have another zero in $\left(b_{1}, b_{2}\right]$. By applying arguments used to prove theorem 5 , and then result follows.

THEOREM 7. If $(H)$ is quick oscillatory and $f(x)$ change sign on $(b, \infty)$ for each $b \geq a$ and if the distance between consecutive sign change points bounded below, then $(N H)$ is oscillatory.

PROOF. Since $(H)$ is quickly oscillatory and the distance between consecutive zeros of $(H)$ is eventually less than the lower bound of the consecutive sign change points of $f(x)$. By applying theorem 6 , the result follows.

THEOREM 8. If $\lim _{x \rightarrow \infty} P(x)=\infty$ and $f(x)$ changes sign on $(b, \infty)$ for each $b>a$ such that the distance between consecutive sign change points is bounded below, then $(H)$ is oscillatory.

PROOF. The hypothesis $\lim _{x \rightarrow \infty} P(x)=\infty$ implies $(H)$ is quickly oscillatory and the results follow from theorem 7.

THEOREM 9. If $(H)$ is oscillatory, then every pair of nonosillatory solutions of $(N H)$ eventually has the same sign.

PROOF. Suppose $y_{1}(x)$ and $y_{2}(x)$ are nonoscillatory solutions of (NH). It follows $u(x)=y_{1}(x)-y_{2}(x)$ is a solution of $(H)$. The assumption that $(H)$ is oscillatory implies that $(H)$ is oscillatory implies that there exists an infinite sequence $\left\{x_{n}\right\}$ of zeros of $u(x)$. It follows that $y_{1}\left(x_{n}\right)=y_{2}\left(x_{n}\right)$ for all $n$. Thus, $y_{1}(x)$ and $y_{2}(x)$ have the same sign for large $x$.

THEOREM 10. If $\int_{a}^{\infty} p(x) d x=\infty$, then every pair of nonoscillatory solutions on $(N H)$ eventually have the same sign.

PROOF. The hypothesis implies $(H)$ is oscillatory. The result follows by applying theorem 9 .

To derive further properties for $(N H)$ we require the following theorem of Keener [6].

THEOREM A. If $f(x)>0, f^{\prime}(x) \geq 0, p^{\prime}(x) \leq 0$ for $x \in[a, b]$ and if $f(x)$ and $p(x)$ are not constant on a common subinterval, then a solution $y$ of $(N H)$ such that $y(a)=y^{\prime}(a)=0$ is positive on interval $(a, b]$.

This theorem enables us to compare the solution of

$$
\begin{align*}
& y^{\prime \prime}+p(x) y=f_{1}(x)  \tag{2.3}\\
& z^{\prime \prime}+p(x) z=f_{2}(x) \tag{2.4}
\end{align*}
$$

where $f_{1}(x), f_{2}(x)$ and $p(x)$ are of $C^{1}$-class on $[a, b]$.
THEOREM 11. Let $f_{1}>f_{2}, f_{1}^{\prime} \geq f_{2}^{\prime}, p^{\prime} \leq 0$ on $[a, b]$.
Assume also $f_{3}=f_{1}-f_{2}$ and $p(x)$ are not constants on common subinterval. If $y(x)$ and $z(x)$ are solutions of (2.3) and (2.4) respectively and satisfies $y(a)=$ $z(a)=y^{\prime}(a)=z^{\prime}(a)=0$, then $y(x)>z(x)$ for $x \in(a, b]$.

PROOF. Subtracting (2.4) from (2.3) we have

$$
\omega^{\prime \prime}+p(x) \omega=f_{3}(x)
$$

where $\omega=y-x$. Since $f_{3}(x)>0, f^{\prime}(x) \geq 0$ and since $\omega$ has a double zero at $x=a$. Applying theorem A it follows that $\omega(x)>0$ for ( $a, b]$.

We remark that if $f_{3}(x)$ and $p(x)$ are not constants on common subinterval, the conclusion of theorem 11 follows i. e. $y(x)>z(x), x \in(a, b]$. This completes the proof.

As example consider the equations

$$
y^{\prime \prime}+y=1+e^{-x} \text { and } z^{\prime \prime}+z=e^{-x}
$$

with $a=0$. The solutions are

$$
y=1+\frac{1}{2}\left(e^{-x}+\sin x-3 \cos x\right)
$$

and

$$
z=\frac{1}{2}\left(e^{-x}+\sin x-\cos x\right)
$$

satisfy the conditions $y(0)=y^{\prime}(0)=z(0)=z^{\prime}(0)=0$ we have

$$
y-z=1-\cos x \geq 0 \text { on }[0, \infty)
$$

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