

THE STRUCTURE OF MULTI-BLOCK CIRCULANTS

By J. Baker, F. Hiergeist, and G. Trapp

1. Introduction

In this paper we extend a result of Trapp [4] for block circulant matrices to multi-block circulant matrices. A 0-block circulant is simply a circulant matrix; that is, a matrix of the form

$$\begin{pmatrix} a_0 & a_1 & \cdots & a_{n-1} \\ a_{n-1} & a_0 & \cdots & a_{n-2} \\ \cdots & \cdots & \cdots & \cdots \\ a_1 & a_2 & \cdots & a_0 \end{pmatrix}$$

A 1-block circulant, or simply block circulant, is a partitioned matrix of the form

$$\begin{pmatrix} A_0 & A_1 & \cdots & A_{n-1} \\ A_{n-1} & A_0 & \cdots & A_{n-2} \\ \cdots & \cdots & \cdots & \cdots \\ A_1 & A_2 & \cdots & A_0 \end{pmatrix}$$

where all A_i , for $i=0, 1, \dots, n-1$, are circulants of the same size. In general, an m -block circulant is a partitioned matrix

$$\begin{pmatrix} M_0 & M_1 & \cdots & M_{n-1} \\ M_{n-1} & M_0 & \cdots & M_{n-2} \\ \cdots & \cdots & \cdots & \cdots \\ M_1 & M_2 & \cdots & M_0 \end{pmatrix}$$

where each M_i for $i=0, 1, \dots, n-1$, is an $(m-1)$ -block circulant and all M_i have the same size.

Circulants and multi-block circulants have many applications in physics, Fourier analysis, geometry, probability and statistics (see [2] and [3]).

Our main interest here is to describe the inverse of a multi block circulant.

2. Notation

We denote the $n_0 \times n_0$ circulant matrix

$$A(0) = \begin{pmatrix} a_0 & a_1 & \cdots & a_{n_0-1} \\ a_{n_0-1} & a_0 & \cdots & a_{n_0-2} \\ \cdots & \cdots & \cdots & \cdots \\ a_1 & a_2 & \cdots & a_0 \end{pmatrix}$$

as circ $[a_0, a_1, \dots, a_{n_0-1}]$.

Likewise we describe the $n_1 \times n_1$ 1-block circulant

$$A(1) = \begin{pmatrix} A_0(0) & A_1(0) & \cdots & A_{n_1-1}(0) \\ A_{n_1-1}(0) & A_0(0) & \cdots & A_{n_1-2}(0) \\ \cdots & \cdots & \cdots & \cdots \\ A_1(0) & A_2(0) & \cdots & A_0(0) \end{pmatrix}$$

as circ $[A_0(0), A_1(0), \dots, A_{n_1-1}(0)]$, where each $A_i(0)$, $i=0, 1, \dots, n_1-1$, is an $n_0 \times n_0$ circulant matrix. Continuing in this fashion we describe an $n_k \times n_k$ k -block circulant matrix as

$$A(k) = \text{circ} [A_0(k-1), A_1(k-1), \dots, A_{n_k-1}(k-1)],$$

where each $A_i(k-1)$, $i=0, 1, \dots, n_k-1$ is a $(k-1)$ -block circulant matrix.

For the statement of the main theorem we will need the following matrices:

1) For $k \geq 0$, $\Omega(k)$ is the $n_k \times n_k$ matrix $\Omega(k) = (p_{nk}^{ij})$ $i, j=0, 1, \dots, n_k-1$ where

$$p_{nk} = e^{\frac{2\pi i}{n_k}}$$

These elements are roots of unity.

2) For $k \geq \phi$ define $\Gamma(k)$ recursively by $\Gamma(k) = \Omega(k) \otimes \Gamma(k-1) / \text{SQRT}(n_k)$ where \otimes denotes the Kronecker product (see Davis [2], pp.22~24) and where $\Gamma(-1) = (1)$.

The diagonalization of a multi-block circulant

THEOREM 1. Let $A(m)$ be an m -block circulant matrix. Then we have $\Gamma^{-1}(m) A(m) \Gamma(m) = D(m)$ where $D(m)$ is a block diagonal matrix whose diagonal blocks $D_0(m-1), D_1(m-1), \dots, D_{n_m-1}(m-1)$ are themselves diagonal matrices. The diagonal elements of $D_i(m-1)$, for $i=0, 1, \dots, n_m-1$, are the eigenvalues of the matrix

$$\sum_{k=0}^{n_m-1} A_k(m-1) r_k^i$$

where $r_0, r_1, \dots, r_{n_m-1}$ are the n_m -th roots of unity ($r_i = p_{n_m}^i$, $i=0, 1, \dots, n_m-1$).

The proof is by induction on m . The case $m=1$ has been proven by Trapp [4] and Chao [1].

Assume the theorem is true for all $(m-1)$ -block circulant matrices. Consider an m -block circulant matrix $A(m) = \text{circ} [A_0(k), A_1(k), \dots, A_{n_m-1}(k)]$ where $k=m-1$ and $A_i(k)$ is a k -block circulant for each $i=0, 1, \dots, n_m-1$.

Let $Q=Q(m)$ and $\Gamma=\Gamma(k)$ where the matrices $\Gamma(k)$ and $Q(m)$ have been described previously. The matrix $A(m)$ can be written as

$$A(m) = I \otimes A_0(k) + T \otimes A_1(k) + T^2 \otimes A_2(k) + \dots + T^{n_m-1} \otimes A_{n_m-1}(k)$$

where T is the $n_m \times n_m$ permutation matrix that corresponds to the cyclic permutation

$$\begin{bmatrix} 0 & 1 & \dots & i & \dots & n_m-1 \\ 1 & 2 & \dots & i+1 & \dots & 0 \end{bmatrix}$$

$$\begin{aligned} \text{We have } \Gamma(m)^{-1}A(m)\Gamma(m) &= (Q \otimes \Gamma)^{-1}A(m)(Q \otimes \Gamma) \\ &= (Q^{-1} \otimes \Gamma^{-1}) (I \otimes A_0(k) + T \otimes A_1(k) + \dots + T^{n_m-1} \otimes A_{n_m-1}(k)) (Q \otimes \Gamma) \\ &= (Q^{-1}I \otimes Q) \otimes (\Gamma^{-1}A_0(k)\Gamma) + (Q^{-1}T \otimes Q) \otimes (\Gamma^{-1}A_1(k)\Gamma) \\ &\quad + \dots + (Q^{-1}T^{n_m-1} \otimes Q) \otimes (\Gamma^{-1}A_{n_m-1}(k)\Gamma) \end{aligned}$$

Since $A_i(k)$ is a k -block circulant, the induction hypotheses gives, $\Gamma^{-1}A_i(k)\Gamma = E_i$, where E_i is a diagonal matrix. Since $A_i(k)$ is similar to a diagonal matrix, E_i , the eigenvalues of $A_i(k)$ are the diagonal entries of E_i .

Each T^i , $i=0, 1, \dots, n_m-1$, is an $n_m \times n_m$ circulant matrix. By Chao [1]

$$\begin{aligned} Q^{-1}T^iQ &= \text{diag} \{P_{n_m}^0, P_{n_m}^i, P_{n_m}^{2i}, \dots, P_{n_m}^{(n_m-1)i}\} \\ &= \text{diag} \{r_i^0, r_i, r_i^2, \dots, r_i^{n_m-1}\} = R_i \end{aligned}$$

Now

$$\begin{aligned} (Q \otimes \Gamma)^{-1}A(m)(Q \otimes \Gamma) &= I \otimes (\Gamma^{-1}A_0(k)\Gamma) + (Q^{-1}T \otimes Q) \otimes (\Gamma^{-1}A_1(k)\Gamma) \\ &\quad + \dots + (Q^{-1}T^{n_m-1} \otimes Q) \otimes (\Gamma^{-1}A_{n_m-1}(k)\Gamma) \\ &= I \otimes E_0 + R_1 \otimes E_1 + R_2 \otimes E_2 + \dots + R_{n_m-1} \otimes E_{n_m-1} \\ &= \text{diag} \left\{ \sum_{i=0}^{n_m-1} E_i, \sum_{i=0}^{n_m-1} r_i E_i, \sum_{i=0}^{n_m-1} r_i^2 E_i, \dots, \sum_{i=0}^{n_m-1} r_i^{n_m-1} E_i \right\} \\ &= \text{diag} \{D_0(k), D_1(k), \dots, D_{n_m-1}(k)\} \end{aligned}$$

where, for each $i=0, 1, \dots, n_m-1$, $D_i(k)$ is a diagonal matrix whose diagonal elements are the eigenvalues of $\sum_{j=0}^{n_m-1} r_j^i A_j(k)$. Hence

$$\Gamma^{-1}(m)A(m)\Gamma(m)=D(m)=\text{diag}\{D_0(m-1), D_1(m-1), \dots, D_{n_m-1}(m-1)\}$$

where $D_i(m-1)$, for each $i=0, 1, \dots, n_m-1$, is a diagonal matrix whose diagonal entries are the eigenvalues of

$$\sum_{k=0}^{n_m-1} r_k A_k(m-1)^i$$

Our next theorem describes how to "recover" an m -block circulant from a diagonal matrix.

THEOREM 2. *Given a square diagonal matrix whose size is $n_m \cdot n_{m-1} \cdots n_1 \cdot n_0$, then $\Gamma(m)D\Gamma^{-1}(m)$ is an m -block circulant matrix.*

PROOF. The proof proceeds by induction on m . The case $m=1$ has been proven by Trapp [4] and Chao [1].

Let $D=\text{diag}\{D_0, D_1, \dots, D_{n_m-1}\}$ where D_i , for each $i=0, 1, \dots, n_m-1$ is a square diagonal matrix whose size is $n_0 \cdot n_1 \cdots n_{m-1}$. Again let $Q=Q(m)$ and

$\Gamma=\Gamma(m-1)$, $\Gamma(m)D\Gamma^{-1}(m)$ can be written as

$$\begin{aligned} \Gamma(m)D\Gamma^{-1}(m) &= (Q \otimes \Gamma) D (Q \otimes \Gamma)^{-1} \\ &= (Q \otimes \Gamma) (\text{diag}(1, 0, \dots, 0) \otimes D_0 + \text{diag}(0, 1, 0, \dots, 0) \otimes D_1 \\ &\quad + \dots + \text{diag}(0, 0, \dots, 0, 1) \otimes D_{n_m-1}) (Q^{-1} \otimes \Gamma^{-1}) \\ &= (Q \text{diag}(1, 0, \dots, 0) Q^{-1}) \otimes (\Gamma D_0 \Gamma^{-1}) \\ &\quad + (Q \text{diag}(0, 1, 0, \dots, 0) Q^{-1}) \otimes (\Gamma D_1 \Gamma^{-1}) \\ &\quad + \dots + (Q \text{diag}(0, 0, \dots, 0, 1) Q^{-1}) \otimes (\Gamma D_{n_m-1} \Gamma^{-1}) \end{aligned}$$

For each $i=0, 1, \dots, n_m-1$, the induction hypothesis shows that $\Gamma D_i \Gamma^{-1}$ is an $(m-1)$ -block circulant. We also have the (i, j) entry of $Q \text{diag}(0, \dots, 0, 1, 0, \dots, 0) Q^{-1} = r^{ik}(\bar{r})^{jk}$, here the one in the diagonal matrix is in the k -th position. The (i, j) block of $\Gamma(m)D\Gamma^{-1}(m)$ is

$$\sum_{k=0}^{n_m-1} r^{ik}(\bar{r})^{jk} A_k(m-1)$$

and the $(i+1, j+1)$ block of $\Gamma(m)D\Gamma^{-1}(m)$ is

$$\begin{aligned}
 & \sum_{k=0}^{n_m-1} r^{(i+1)k} (\bar{r})^{(j+1)k} A_k(m-1) \\
 &= \sum_{k=0}^{n_m-1} r^{ik} (\bar{r})^{jk} (r\bar{r})^k A_k(m-1) \\
 &= \sum_{k=0}^{n_m-1} r^{ik} (\bar{r})^{jk} A_k(m-1)
 \end{aligned}$$

Hence the (i, j) block equals the $(i+1, j+1)$ block. This equality also holds if i or j is n_m-1 and we take $i+1$ or $j+1$ modulo n_m .

Hence $\Gamma(m)D\Gamma^{-1}(m)$ is an m -block circulant matrix.

Our final result is a direct consequence of the above two theorems.

THEOREM 3. *If $A(m)$ is non-singular and an m -block circulant matrix, then $A^{-1}(m)$ is also an m -block circulant matrix.*

West Virginia University
Morgantown, W. V. 26506
U.S.A.

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