Joint Distribution of ESACF Arrays within Triangular Zero Boundary

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Abstract

An obvious criticism of ESACF approach for model identification by Tsay and Tiao(1984) is that the user may be confused by the elements which are in triangular but marginally larger two standard deviation values. To avoid this drawback, the joint limiting distribution of the vector whose elements are in triangular of ESACF arrays is verified and the statistics to test the nullity of the vector are suggested. We illustrate this approach with three examples.

1. Introduction

Suppose n observations are available from the ARMA(p, q) process

$$\boldsymbol{\varphi}(B)Z_t = \boldsymbol{\theta}(B) a_t$$
 where
$$\boldsymbol{\varphi}(B) = U(B) \ \boldsymbol{\phi}(B) = 1 - \boldsymbol{\varphi}_1 B - \dots - \boldsymbol{\varphi}_p B^p$$

$$U(B) = 1 - U_1(B) - \dots - U_d B^d$$

$$\boldsymbol{\phi}(B) = 1 - \boldsymbol{\phi}_1(B) - \dots - \boldsymbol{\phi}_{p-d} B^{p-d}$$

$$\boldsymbol{\theta}(B) = 1 - \boldsymbol{\theta}_1(B) - \dots - \boldsymbol{\theta}_q B^q$$

$$\{ a_t \} ; \text{ Gaussian white noise process with mean zero and variance } \sigma_a^2$$

We shall require that all the zeros of U(B) are on, those of $\phi(B)$ are outside, and those of $\theta(B)$ are on or outside the unit circle, and also that $\Phi(B)$ and $\theta(B)$ have no common factors. Further, we shall assume that Z_t starts at a finite time point t_0 if it is nonstationary.

For tentative model identification of univariate time series, several approaches have been proposed for practical uses. They can be categorized as the post-estimation method and the preestimation method. The post-estimation method such as the information criterion (AIC) by Akaike (1974), criterion autoregressive transfer function (CAT) by Parzen (1982), data dependent system (DDS) by Pandit and Wu (1983), select the model after estimation procedure.

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But the pre-estimation method such as sample autocorrelation function (SACF) and sample partial autocorrelation function (SPACF) approach by Box and Jenkins (1970), the R-and S-array by Gray, et al. (1978), the Pade table approach by Beguin, et al. (1980), and Tucker (1982), suggest the model before estimating the parameters.

Tsay and Tiao (1984) have developed the extended sample autocorrelation function (ESACF) approach which can be categorized as mixed method of post-estimation method and pre-estimation method. Based on the consistent AR estimates produced by iterated regressions, the ESACF is defined and the model is selected by its "triangular cutting off behavior." The ESA-CF approach is very powerful bacause it can handle nonstationary as well as stationary models in a much more direct manner. But the obvious criticism of ESACF approach is the user may be confused by the elements which are in triangular but marginally larger than two standard deviation value.

The main purpose of this paper is to develop the statistics which represent "composite Triangular zero behavior" and a procedure for identifing the model automatically.

Section 2 investigates the variance and covariance of the ESACF's and developes the limiting distribution of the vector whose elements are within triangular zero boundary of ESACF arrays and the statistics to test the nullity of the vector. Using the statistics in Section 2, the model identification procedure is given in Section 3 with three examples. A summary and discussions are given in Section 4.

2. Variance and Covariance of ESACF Array

We first define the autocorrelation rw(l) as

$$r_W(l) = r_1(W_l) \tag{2}$$

Then the asymptotic variance of the $r_{j(k)}$'s can be approximately obtained by using Bartelett formula. On the assumption that all the autocorrelations $r_w(l)$ are approximately zero for l > j, Barlett's approximation gives

$$Var[r_{j(k)}] \doteq [1 + 2\sum_{v=1}^{J-1} [\{r_w(l) \mid ^2]/(N-k)]$$
(3)

For ARMA (p, q) time series, the equation (3) holds when $j-q > k-p \ge 0$. If $r_{(jk)}$'s are independent, under the null hypothesis:

$$H_0 = \{ \rho_{j(k)} = 0, j-q > k-p \ge 0 \}$$

the value

$$QI_{T}(p, q) = \sum_{k=p}^{p+K} \sum_{j=q-p+k+1}^{q+K+1} \frac{\{r_{j(k)}\}^{2}}{\operatorname{Var}[r_{j(k)}]}$$
(4)

where
$$T = \sum_{k=1}^{K} k$$

converges in distribution to a Chi-square with degree of freedom T. The set $\{QIr > C_{\alpha}\}$, where C_{α} is the α -percentage point in $\chi^{2}(T)$, is an asymtotic critical region at level α for testing H_{α} .

In general, for any nonnegative integer u and v, we define the $QI_T(u, v)$ value as (4). Sup-

pose that the ARMA process Z_t in (1) is nonstationary, that is, U(B) = 1. In this case, the values $QI_T(u, v)$, u < d, are not converge in distribution to a Chi-square, because asymtotically $r_{v+m(u)} \neq 0$, m > 1, due to remaining nonstationary part of the AR process.

Using the above result, we can eliminate the possible AR order u, u < d, by checking QIr(u, v) values.

The covariances of $r_{j(k)}$ cannot be solved easily because they are covariance of autocorrelations of different series. But we can approximate the covariances of $r_{j(k)}$'s which are in triangular whose vertex is $r_{q+1(p)}$ by following theorems and corollaries.

Theorem 1. For ARMA(p, q) time series, let $\{W_t\}$, $\{X_t\}$ and $\{Y_t\}$ be defined respectively by

$$W_{t} = \Phi_{p}^{(q)}(B) \quad Z_{t} = \sum_{m=0}^{q} \theta_{m} a_{t-m}$$

$$X_{t} = H_{j}^{(i)}(B) \quad W_{t} \qquad (j > i \ge 0)$$

$$Y_{t} = H_{l}^{(k)}(B) \quad W_{t} \qquad (l > k \ge 0)$$

where the a_i are independent $(0, \sigma^2)$ random variable with $\mathbb{E}\{a_i^4\} = \eta \sigma^4$.

Then for fixed h and g, $i+h \ge k+g$,

$$\lim_{n \to \infty} (n-k-g) \operatorname{Cov} \left\{ \gamma_X(h), \ \gamma_Y(g) \right\} = \sum_{l=-q-j}^{q+k-jl} S_{XY}(t) S_{XY}(t+jl)$$
 (5)

where
$$Sxy(t) = H_j^{(i)}(F)H_1^{(k)}(B)\gamma w(t),$$

 $h = q + j$
 $g = q + l$
 $ij = |i-l|$

Proof) See Appendix 1.

Corollary 1. Let the assumptions of Theorem 1 hold and E $\{a_t^6\}$ = $\eta \sigma^6$. Then,

$$Cov \{ rx(h), ry(g) \}$$

$$= \{ (n-k-g) \gamma_X(0) \gamma_Y(0) \}^{-1} \sum_{t=-q-i}^{q+k-j} S_{XY}(t) S_{XY}(t+j1) + O(n^{-2})$$
 (6)

where $S_{XY}(t) = H_j^{(i)}(F) H_l^{(k)}(B) \gamma_W(t)$

Proof) The estimated autocorrelations are bounded and are differentiable functions of the estimated autocovariances on a closed set containing the true parameter vector as an interior point. Furthermore, the derivations bre bounded on that set. Hence, the conditions of Thoerem 5.4.3 (Fuller, 1976) are met with $\{\tilde{\chi}(h), \tilde{\chi}(g), \tilde{\chi}(0), \tilde{\chi}(0)\}$ playing the role of $\{X_n\}$.

Since the function rx(h) and ry(g) are bounded, we take $\alpha = 1$. Expanding E $\{rx(h) - \rho x(h)\}$ [$ry(h) - \rho y(g)$] through third order terms and using Theorem 5.4.1 (Fuller, 1976) to establish that the expected value of the third order moment is $0(n^{-2})$, we have

$$Cov \{ r x(h), r y(g) \} = [\gamma x(0) \gamma y(0)]^{-1} [Cov \{ \widetilde{\gamma} x(h), \widetilde{\gamma} y(g) \}$$

$$- \rho_X(h) Cov \{ \widetilde{\gamma} x(0), \widetilde{\gamma} y(g) \} - \rho_Y(g) Cov \{ \widetilde{\gamma} x(h), \widetilde{\gamma} y(0) \}$$

$$+ \rho_X(h) \rho_Y(g) Cov \{ \widetilde{\gamma} x(0), \widetilde{\gamma} y(0) \}] + 0(n^{-2}).$$

Using Theorem 1, we have the result because $\rho_X(h)$ and $\rho_Y(g)$ are zero.

we now turn to the large sample properties of the estimated autocovariances and autocorrelations.

Theorem 2. For ARMA (p, q) time series, let $\{W_t\}$ and $X_t^{(i, j)}$ be defined respectively by

$$W_t = \boldsymbol{\Phi}_p^{(q)}(B) \ Z_t = \sum_{m=0}^M \ \theta_m a_{t-m}$$

$$X_{i}^{(i,j)} = H_{i}^{(i)}(B) \quad W_{i} \qquad (j > i \ge 0)$$

where the a_t are independent $(0, \sigma^2)$ random variables with fourth moment $\eta \sigma^4$ and sixth moment ξ .

And we let $\alpha_1, \alpha_2, \ldots, \alpha_T$ be the elements of finite subset $\{\tilde{\gamma}_{q+j(p+i)}, i > i \ge 0\}$.

Then the limiting distribution of $n^{1/2}(\alpha_1, \alpha_2, ..., \alpha_T)$ is multivariate normal with mean zero and covariance matrix V where the elements of V are defined by Theorem 1.

Proof) See Appendix 2.

Corollary 2. Let the assumptions of Corolly 1 hold, and β_1 , β_2 , ..., β_T be the elements of finite subset $\{r_{q+j(p+i)}, j > i \ge 0\}$.

Then the limiting distributing of $n^{1/2}(\beta_1, \beta_2, ..., \beta_T)$ is multivariate normal with mean zero and covariance matrix G where the elements of G can be derived by Corollary 1.

Proof) Since the $r_{q+j(p+i)}$ are continuous differentiable functions of the $\widehat{\gamma}_{q+j(p+1)}$, the result follows immediately from Theorem 5.1.4 (Fuller, 1976), Corrollary 1 and Theorem 2.

Using the above result, under the null hypothesis:

$$H_o = \{ \rho_{q+j(p+i)} = 0, j > i \ge 0 \}$$

the quadratic form

$$QD_{T}(p, q) = n(\beta_{1}, \beta_{2}, ..., \beta_{T})' G^{-1}(\beta_{1}, \beta_{2}, ..., \beta_{T})$$
(7)

converges in distribution to $\chi^2(T)$. The set $\{QD_T > C_{\alpha}\}$, where C_{α} is the α -percentage point in $\chi^2(T)$ is an asymtotic critical region at level α for testing H_0 .

3. Model Identification Procedure

To indentify the ARMA (p, q) model tentatively, the ESACF table and indicator symbol are examined to check the "triangular cutting off behavior". The obvious criticism of the ESACF table and its indicator symbol is that the user may be confused by the elements which are in triangular but marginally larger than two standard deviation values.

To avoid this drawback, the QIr and QDr values defined in Section 2 can be used to check the "composite triangular zero behavior" for the model indentification. That is, we search the North-West coordinate (i, j) whose QIr(i, j) and QDr(i, j) values are less than C_a , where C_a is the α -percentage of $\chi^2(T)$, and tentatively identify (i, j) as an order of the model.

We illustrate this approach at T=6 and $\alpha=0.05$ with three examples which were also demonstrated by Tsay and Tiao (1984). The elements of ESACF array used to calculate $Q_6(i, j)$ value are shown in Table 1.

	MA							
AR	0	1	•••	i	j+1	j+2	•••	
0	Y1 (0)	Y2(0)	•••	<i>Yj</i> +1(0)	Yj+2(0)	γ _{j+3} (0)	•••	
1	7 1(1)	Y2(1)	•••	$\gamma_{j+1(1)}$	$\gamma_{j+2(1)}$	$\gamma_{j+3(1)}$	•••	
:	÷	:		÷	:	:		
i	$\gamma_{1(i)}$	Y2 (i)	••••	$\gamma_{j+1(i)}$	$\gamma_{j+2(i)}$	γ _{j+3 (i)}		
i+1	$\gamma_{1(i+1)}$	$\gamma_{2(i+1)}$	•••	Yj+1(i+1)	<i>r</i> _{j+2} (i+1)	γ _{j+3 (i+1)}	•••	
<i>i</i> +2	Y1 (i+2)	$\gamma_{2(i+2)}$	•••	$\gamma_{j+1(i+1)}$	Yj+2(i+2)	Yj+3(i+2)	•••	
:	:	:		:	:	:		

Example 1. For the series C in Box and Jenkins (1970), Tsay and Tiao (1984) suggested an AR(2) model by the "triangular cutting off" behavior of the indicator symbols.

Table II gives the QI_6 and QD_6 arrays and justifies AR(2) model because $QI_6(2, 0)$ and $QD_6(2, 0)$ are less than theoretical $\chi^2(6, 0.05)$ value.

	MA							
AR	0	1	2	3	4	5	6	
	a.	The QI ₆ arr	ay					
0	391. 2	169. 8	106. 6	74. 5	55. 4	40. 7	33. 5	
1	214. 3	83. 4	44. 7	29. 2	21.6	15. 6	14.8	
2	4. 5*	9.4*	6. 3*	1. 1*	1. 3*	1.8*	7. 2*	
3	79. 7	6. 8*	5. 6 *	2.8*	. 3*	. 4*	3. 6*	
4	50. 2	27. 7	4. 1*	3. 2 *	. 5*	. 4*	2. 6*	
5	94. 3	21. 5	22. 9	2. 1*	. 8*	. 6 *	2.0*	
6	31. 2	27. 9	29. 4	14. 2	. 4*	. 5*	1. 7*	
	b.	The QD ₆ ar	ray					
0	_	_	_	8703. 6	3408. 5	2140. 3	2006. 5	
1	1121. 2	_	_	5072. 5	3888. 8	2451. 1	2038. 2	
2	5. 9 *	469. 0	_	212. 8	91. 0	39. 9	286. 4	

3	_	74.5	600.4	_	426.3	432. 2	2. 3*
4		93. 7	******		_	. 0*	79. 7
5	_	_	230. 1	134. 2	_	_	37. 5
6	3057.7	443.5	1006.6	_	_	461.5	105. 9

(*: less than χ^2 (6, 0.05) value

Example 2. Tsay and Tiao (1984) generated one hundred observations from the ARMA (4, 1) model and analyze the ESACF table. The QI_6 and QD_6 arrays are shown in Table III and we can determine ARMA (4, 1) model as suggested by them.

For this example, it is of interest to examine the $QI_6(i, j)$ values when i is less than the order of the nonstationary part of the AR process. For the values $QI_6(i, j)$, i < 4, are all greater than $\chi^2(0.05, 6)$, we can eliminate nonstationary factor of the AR process.

Example 3. for the series A in Box and Jenkins (1970), ARMA (1, 1) model was suggested by Tiao and Tsay (1984).

The QI_6 and QD_6 arrays given in Table IV also confirmed ARMA(1, 1) model. In this case, we can see this procedure is not confused by the ESACF elements whose values are marginally larger than the two standard deviation values.

	MA							
AR	1	0	2	3	4	5	6	
	a.	The QI ₆ Ar	ray					
0	173. 6	125. 4	77.8	35. 8	37. 2	53. 0	41. 4	
1	92. 0	88. 8	86. 9	45. 2	27. 2	45. 7	48. 9	
2	93. 2	57. 5	61. 7	45. 3	25. 6	30. 7	33. 6	
3	84. 3	31.0	18. 1	15. 9	15. 9	16.8	13.7	
4	24. 5	. 7*	. 3*	. 6 *	1. 4*	3.4*	3. 9*	
5	18. 0	11. 3*	. 3*	. 3*	. 5*	. 9*	. 8*	
6	31. 1	6. 4*	7.0*	. 2*	. 5*	. 6*	. 4*	
	b.	The QD ₆ A	rray					
0	_	4013. 2	1076. 2	1986. 1	1490. 2	631. 1	803. 7	
1	_	1520.5	3064.4	1341.7	290.7	1186.3	1200.7	
2		_	3. 6*	1524. 9	2883. 0	621.8	. 1*	

^{-:} greater than 9999.9)

3	1571. 6	4605. 7	1557. 9	203. 4	524. 1	432. 4	465. 2
4	1534. 5	. 4*	_	28. 1	5700.3	45. 8	177. 8
5	421. 8	122. 5			4.6*	115. 1	2.5*
6		572. 6		_	_	_	5065. 1

(* : less than χ^2 (6, 0.05) value

-: greater than 9999.9)

	MA							
AR	0	1	2	3	4	5	6 6	
	a.	The QI ₆ arr	ay					
0	109. 0	54. 5	33. 4	26. 8	33, 9	28. 1	21. 4	
1	45. 9	1.1*	1.5*	1. 1*	13. 4	9. 2*	5. 9 *	
2	32. 1	15. 3	. 7*	. 7*	12. 6	9. 5 *	7.1*	
3	54. 7	2. 5*	4. 2*	. 5 *	9. 3 *	7.9*	6. 9*	
4	83. 9	4. 3*	11. 4	3.4*	5. 9 *	6. 1 *	4.7*	
5	70. 4	58. 9	23. 7	11. 6*	12. 6	3. 9*	,3. 2*	
6	51. 9	34. 4	53. 2	20. 5	19. 5	11.0*	2. 7*	
	b.	The QD_6 as	rray					
0	1409. 8	9555. 7	4725. 7	1910. 9	1514.8	2739. 9	1016. 3	
1	8529. 2	6.8*	5. 5 *	113. 1	1880. 1	138. 0	262. 6	
2	4876. 6	6463.6	6773. 0		6. 4 *	_	. 4*	
3	_	36. 0	399. 3	25. 4	25. 2	28. 3	591. 5	
4	_		. 0*	204. 5	2. 3*	17. 7	`247. 2	
5	_	645. 5	6376. 7	44. 8	397. 6	369. 3	2424.7	
6	_		2494.3	1550. 9	. 0*	3687. 9	. 2*	

(* : less than $\chi^2(6, 0.05)$ value

-: greater than 9999.9)

4. Conclusion

In this paper we have investigated the limiting distribution of the vector whose elements are within triangular boundaries of the ESACF array and the statistics, the QIr and QDr arrays, to test the nullity of the vector.

The major advantage of model identification procedure using those statistics is that it can avoid the difficulties of manual checking the triangular cutting off behavior of ESACF array, which was the problem of the ESACF approach.

All examples considered were nonseasonal in nature. A study of other seasonal examples is needed in the future.

Appendix 1. (Proof of Theorem 1)

Let $\theta_m^{j(i)} = H_j^{(i)}(B)$ θ_m , then the sequence $\{\theta_m^{j(i)}\}$ is finite and absolutely summable, because θ_m is zero for m > q + i and m < 0.

From definition,

$$X_t = H_j^{(i)}(B)$$
 $W_t = \sum_{m=-\infty}^{\infty} \theta_m^{j(i)}$ a_{t-m}

$$Y_t = H_l^{(k)}(B) \ W_t = \sum_{m=-\infty}^{\infty} \ \theta_m^{l(k)} \ a_{t-m}$$

and

$$\begin{array}{l} \mathbb{E} \ \, \{ \, X_{t} \, X_{t+h} \, Y_{t+h+f} \, Y_{t+h+f+g} \, \} \\ = (\eta - 3) \, \sigma^{4} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \theta_{m}^{j(\,i)} \, \, \theta_{m+h}^{j(\,i)} \, \, \theta_{m+h}^{l(\,k)} \, \, \theta_{m+h+f}^{l(\,k)} \, \, \theta_{m+h+f+g}^{l(\,k)} \, \} \\ + \, \sigma^{4} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \theta_{m}^{j(\,i)} \, \, \theta_{m+h}^{j(\,i)} \, \, \} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \theta_{w+h+f}^{l(\,k)} \, \, \theta_{m+h+f+g}^{l(\,k)} \, \} \\ + \, \sigma^{4} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \, \theta_{m}^{j(\,i)} \, \, \, \theta_{m+h+f}^{l(\,k)} \, \, \} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \, \theta_{m+h}^{j(\,i)} \, \, \theta_{m+h+f}^{l(\,k)} \, \} \\ + \, \sigma^{4} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \, \, \theta_{m}^{j(\,i)} \, \, \, \theta_{m+h+f+g}^{l(\,k)} \, \} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \, \, \theta_{m+h}^{j(\,i)} \, \, \, \theta_{m+h+f}^{l(\,k)} \, \} \\ = (\eta - 3) \, \sigma^{4} \, \sum_{m = -\infty}^{\infty} \, \{ \, \, \, \, \theta_{m}^{j(\,i)} \, \, \, \, \theta_{m}^{j(\,i)} \, \, \, \, \theta_{m+h+f+g}^{l(\,k)} \, \} \\ + \, \gamma_{X}(h) \, \, \gamma_{Y}(g) \, + \, S_{XY}(h+f) \, S_{XY}(f+g) \, + \, S_{XY}(h+f+g) \, S_{XY}(f) \\ \text{where } \, S_{XY}(t) = H_{i}^{(\,i)} \, (F) \, H_{i}^{(\,k)} \, (B) \, \gamma_{W}(h) \end{array}$$

Thus,

$$E \{ \gamma_{X}(h) \gamma_{Y}(g) \} - \gamma_{X}(h) \gamma_{Y}(g)$$

$$= \frac{1}{(n-i-h)(n-k-g)} \{ \sum_{s=1}^{n-k-g} \sum_{t=1}^{n-i-h} E(X_{t} X_{t+h} Y_{s} Y_{s+g}) \} - \gamma_{X}(h) \gamma_{Y}(g)$$

$$= \frac{(\eta-3)\sigma^{4}}{(n-i-h)(n-k-g)} \sum_{s=1}^{n-k-g} \sum_{t=1}^{n-i-h} \{ \theta_{m}^{i(i)} \theta_{m+h}^{i(i)} \theta_{m+s-t}^{i(k)} \theta_{m+s-t+g}^{i(k)} \}$$

$$+ \frac{1}{(n-i-h)(n-k-g)} \sum_{s=1}^{n-k-g} \sum_{t=1}^{n-i-h} \{ Sxy(s-t) Sxy(s-t-h+g)$$

$$+ Sxy(s-t+g) Sxy(s-t-h) \}$$

Applying Lemma 6.2.1 (Fuller, 1976), we have

$$\lim_{n \to \infty} (n - k - g) \quad Cov \mid \widetilde{\gamma}_X(h), \quad \widetilde{\gamma}_Y(g) \mid$$

$$= (\eta - 3)\sigma^4 \sum_{m = -\infty}^{\infty} \sum_{t = -\infty}^{\infty} \mid \theta_m^{j(i)} \theta_{m+h}^{j(i)} \theta_{m+t}^{1(k)} \theta_{m+t+g}^{1(k)} \mid$$

$$+ \sum_{t = -\infty}^{\infty} \mid SxY(t) SxY(t - h + g) + SxY(t + g) SxY(t - h) \mid$$

For ARMA (p, q) time series, $\gamma_X(h)$, $\gamma_Y(g)$ and $S_{XY}(t)$, t > q + k, t < -q - i are zero. If we let jl = |j - l|, then

$$\sum_{t=-\infty}^{\infty} Sxy(t) Sxy(t-h-q) = \sum_{t=-q-i}^{q+k-j\ell} Sxy(t) Sxy(t+j\ell)$$

$$\sum_{t=-\infty}^{\infty} Sxy(t+g) Sxy(t-h) = 0$$

Appendix 2. (Proof of Theorem 2)

Let \overline{X} is artithmatic mean of $X_t^{(i,j)}$ series, then the estimated covariance is

and the last two terms, when multiplied by $n^{1/2}$ converges in probability to zero. Therefore in investigating the limiting distribution of $n^{1/2}$ $\widehat{\gamma}_{q+j(p+i)}$ we need only consider the first term. Let

$$S_{n} = n^{1/2} \sum_{i=0}^{I} \sum_{j=i+1}^{J} \lambda_{ij} \left[\frac{1}{n-p-i} \sum_{i=1}^{n-p-q-i-j} X_{t}^{(i, j)} X_{t+q+j}^{(i, j)} \right]$$

$$= n^{1/2} \sum_{i=0}^{I} \sum_{j=i+1}^{J} \lambda_{ij} \left[\frac{1}{n-p-i} \sum_{t=1}^{n-p-q-i-j} Z_{t}^{(i, j)} \right]$$

where the λ_{ij} are arbitrary real numbers (not all zero) and $Z_t^{(i,j)} = X_t^{(i,j)} X_{t+q+j}^{(i,j)}$

Now $Z_t^{(i,j)}$ is an (2q+i+j)-dependent covariance stationary time series with mean $\gamma_{q+j(p+i)}$ and covariance function

$$= (\eta - 3) \sigma^{4} \sum_{m=-\infty}^{\infty} \{ \theta_{m}^{j(i)} \theta_{m+q+j}^{j(i)} \theta_{m+h}^{k(l)} \theta_{m+h+l}^{k(l)} \}$$

+
$$\gamma_{q+j(p+i)} \gamma_{q+l(p+k)} S(h) S(h-j+l) + S(h-q-j) S(h+q+l)$$

where
$$S(t) = H_i^{(i)}(B) H_1^{(k)}(F) \gamma_W(t)$$

 $E[Z_t^{(i, j)} Z_{t+h}^{(k, l)}]$

and it is understood that $\theta_m^{j(i)} = 0$ for m > q + i and m < 0.

Thus, the weighted average of the $Z_t^{(i, j)}$'s

$$Y_{t} = \sum_{i=1}^{I} \sum_{j=i+1}^{J} \lambda_{ij} Z_{t}^{(i, j)} = \sum_{j=0}^{I} \sum_{j=i+1}^{J} \lambda_{ij} X_{t}^{(i, j)} X_{t+q+j}^{(i, j)}$$

is a stationary time series. Furthermore, the time series Y_t is (2q+I+J)-dependent and has finite third moment.

Therefore, S_n converges in distribution to a normal random variable. Since λ_{ij} were arbitrary, the vector random variable $\mathbf{n}^{1/2}(\alpha_1, \alpha_2, \dots, \alpha_T)$ converges in distribution to a multivariate normal by Theorem 5.3.3 (Fuller, 1976).

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