

EVOLUTION EQUATION OF TYPE $\frac{du}{dt} + A\beta u \ni 0$
IN $L^\infty(\mathcal{Q})$

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1. Introduction.

Let \mathcal{Q} be a measure space of bounded measure. For $1 \leq p \leq +\infty$, $L^p(\mathcal{Q})$ denotes the Lebesgue space of \mathcal{Q} with norm $\|\cdot\|_p$. Let A be an operator of $L^p(\mathcal{Q})$ and $\beta: \mathcal{Q} \times R \rightarrow \mathcal{P}(R)$ a mapping. Define the operator $A\beta$ of $L^p(\mathcal{Q})$ by

$$A\beta = \{[u, w] \in L^p(\mathcal{Q}) \times L^p(\mathcal{Q}) \mid \text{there exists } v \in L^p(\mathcal{Q}) \text{ such that } [v, w] \in A \text{ and a.e. } x \in \mathcal{Q}, v(x) \in \beta(x, u(x))\}.$$

The purpose of this paper is to study the Cauchy problem

$$\frac{du}{dt} + A\beta u \ni 0, \quad u(0) = u_0$$

in $L^\infty(\mathcal{Q})$.

Suppose that the following conditions are satisfied:

(H1) A is an m -accretive operator of $L^\infty(\mathcal{Q})$ and monotone in $L^2(\mathcal{Q})$,

(H2) a.e. $x \in \mathcal{Q}$, $r \in R \rightarrow \beta(x, r) \in \mathcal{P}(R)$ is maximal monotone in R ,

(H3) for every $r \in R$, there exists $v \in L^\infty(\mathcal{Q})$ such that a.e. $x \in \mathcal{Q}$, $v(x) \in \beta(x, r)$,

(H4) for every $f \in L^\infty(\mathcal{Q})$ and $\lambda > 0$, there exists at most one solution $u \in L^\infty(\mathcal{Q})$ of $u + \lambda A\beta u \ni f$.

THEOREM 1. ([5])

Let (H1)-(H4) be satisfied. Suppose $A\beta \neq \emptyset$. Then $A\beta$ is m -accretive in $L^\infty(\mathcal{Q})$.

2. Solutions of $\frac{du}{dt} + A\beta u \in 0$ in $L^\infty(Q)$.

By [1] and Theorem 1, we have the following theorem on the integral solution in the sense of Bénéilan of the equation:

THEOREM 2. Let (H1)-(H4) be satisfied. Suppose $A\beta \neq \emptyset$. Let $g \in L^1(0, T; L^\infty(Q))$ for $T > 0$. Then for every $u_0 \in \overline{D(A\beta)}$, there exists a unique integral solution u on $[0, T]$ of $du/dt + A\beta u \ni g$, $u(0) = u_0$. Moreover $u(t) \in \overline{D(A\beta)}$ for every $t \in [0, T]$.

Suppose the following condition is satisfied:

(HC) A is m -accretive in $L^\infty(Q)$ and cyclically monotone in $L^2(Q)$ ([2]).

REMARK 3. ([4]).

Let (HC) be satisfied. Then (H1) is satisfied and there exists a proper lower semi-continuous convex function ϕ defined on $L^2(Q)$ into $(-\infty, +\infty]$ with $\partial\phi = A_2$, where A_2 is the closure of A in $L^2(Q)$.

THEOREM 4.

Let (HC), (H2)-(H4) be satisfied. Then for every $u_0 \in D(A\beta)$, there exists $u \in \mathcal{C}([0, T]; L^\infty(Q))$ such that

$$\begin{cases} \frac{du}{dt}(t) \in L^\infty(0, T; \sigma(L^\infty(Q), L^1(Q))) \\ \frac{du}{dt} + A\beta u(t) \ni 0 \text{ a. e. on } (0, T) \\ u(0) = u_0 \end{cases}$$

for $T > 0$.

PROOF. By Theorem 1, $A\beta$ is m -accretive in $L^\infty(Q)$. Consider the approximation equation

$$(1) \quad \begin{cases} \frac{u(t) - u_\varepsilon(t-\varepsilon)}{\varepsilon} + A\beta u_\varepsilon(t) \ni 0 & (t > 0) \\ u(t) = u_0 & (t \leq 0) \end{cases}$$

for every $\varepsilon > 0$ in $L^\infty(\Omega)$. The equation (1) is written by

$$\begin{cases} u_\varepsilon(t) = (I + \varepsilon A\beta)^{-1} u_\varepsilon(t-\varepsilon) & (t > 0) \\ u_\varepsilon(t) = u_0 & (t \leq 0) \end{cases}$$

and it has at most one solution

$$u_\varepsilon(t) = (I + \varepsilon A\beta)^{-1} u_0 \text{ for every } t \in ((k-1)\varepsilon, k\varepsilon]$$

or

$$u_\varepsilon(t) = (I + \varepsilon A\beta)^{-\lceil t/\varepsilon \rceil} u_0 \text{ for every } t > 0.$$

By [3], $u_\varepsilon(t)$ converges to $u(t)$ in $L^\infty(\Omega)$ uniformly on every compact interval of $[0, \infty)$ as $\varepsilon \rightarrow 0+$ and if we put $u(t) = S(t)u_0$, then $S(t)$ is a nonlinear semigroup of contraction generated by $A\beta$. By [1], the limit $u(t)$ is the integral solution on $(0, \infty)$ of $\frac{du}{dt} + A\beta u \in 0$, $u(0) = u_0$ and $\|u(t) - u(s)\|_\infty \leq |t - s| \|A\beta u_0\|_\infty$ for every $t, s \geq 0$. Thus *a. e.* $t \in (0, \infty)$, $u(t)$ is weakly differentiable in $L^\infty(\Omega)$. We put

$$w_\varepsilon(t) = \frac{u_\varepsilon(t) - u_\varepsilon(t-\varepsilon)}{\varepsilon}.$$

For every $t \geq 0$,

$$(2) \quad \|w_\varepsilon(t)\|_\infty = \frac{1}{\varepsilon} \|(I + \varepsilon A\beta)^{-\lceil t/\varepsilon \rceil} u_0 - (I + \varepsilon A\beta)^{-\lceil t/\varepsilon \rceil + 1} u_0\|_\infty \\ \leq \|A\beta u_0\|_\infty.$$

Hence w_ε is bounded in $L^\infty((0, \infty) \times \Omega)$. Let $v_\varepsilon(t) \in L^\infty(\Omega)$ such that

$$(3) \quad w_\varepsilon(t) + Av_\varepsilon(t) \ni 0$$

and *a. e.* $x \in \Omega$, $v_\varepsilon(t, x) \in \beta(x, u_\varepsilon(t, x))$. Since u_ε is bounded in

$L^\infty((0, \infty) \times \mathcal{Q})$, by (H3), v_ε is bounded in $L^\infty((0, \infty) \times \mathcal{Q})$. There exists $\{\varepsilon_n\}$, $\varepsilon_n > 0$, $\varepsilon_n \rightarrow 0+$ such that $v_{\varepsilon_n} \rightarrow v$ and $w_{\varepsilon_n} \rightarrow w$ in $L^\infty((0, \infty) \times \mathcal{Q})$. As in the proof of Theorem II.8 in [4], we have

$$\frac{du}{dt} = w \text{ in } \mathcal{D}'(0, \infty; L^2(\mathcal{Q}))$$

and by (2), $\|\frac{du}{dt}(t)\|_\infty \leq \|A\beta u_0\|_\infty$.

Let $j: \mathcal{Q} \times \mathbb{R} \rightarrow (-\infty, \infty]$ be a proper lower semi-continuous convex function such that *a. e. x* $\varepsilon \mathcal{Q}$, $\partial j(x, \cdot) = \beta(x, \cdot)$. We define $J: L^2(\mathcal{Q}) \rightarrow (-\infty, \infty]$ by

$$J(z) = \begin{cases} \int_{\mathcal{Q}} j(z) & \text{if } j(z) \varepsilon L^1(\mathcal{Q}) \\ +\infty & \text{otherwise} \end{cases}$$

for every $z \varepsilon L^2(\mathcal{Q})$. Then J is a proper lower semi-continuous convex function on $L^2(\mathcal{Q})$ into $(-\infty, \infty]$ and the subdifferential ∂J of J is the prolongation of β to $L^2(\mathcal{Q})$ ([2]). Since $u_{\varepsilon_n} \rightarrow u$, $v_{\varepsilon_n} \rightarrow v$ in $L^\infty((0, \infty) \times \mathcal{Q})$ and

$$(4) \quad v_{\varepsilon_n}(t) \varepsilon \partial J u_{\varepsilon_n}(t),$$

it follows that $u(t) \varepsilon D(\partial J)$ and $v(t) \varepsilon \partial J u(t)$ *a. e. t* $\varepsilon (0, \infty)$.

Thus

$$(5) \quad v(t) \varepsilon \beta u(t) \text{ a. e. } t \varepsilon (0, \infty).$$

By (4), we have

$$(6) \quad \int_{\mathcal{Q}} v_{\varepsilon_n}(u_{\varepsilon_n}(t) - u_{\varepsilon_n}(t - \varepsilon_n)) \geq J(u_{\varepsilon_n}(t)) - J(u_{\varepsilon_n}(t - \varepsilon_n)).$$

By Remark 3, there exists a proper lower semi-continuous convex function ϕ defined on $L^2(\mathcal{Q})$ into $(-\infty, \infty]$ with $\partial \phi = A_2$. Let $T > 0$. We define $\Phi: L^2((0, T) \times \mathcal{Q}) \rightarrow (-\infty, \infty)$ by

$$\Phi(z) = \begin{cases} \int_0^T \int_{\mathcal{Q}} \phi(z) & \text{if } \phi(z) \varepsilon L^1((0, T) \times \mathcal{Q}) \\ +\infty & \text{otherwise} \end{cases}$$

for every $z \in L^2((0, T) \times \Omega)$. Then ϕ is a proper lower semi-continuous convex function on $L^2((0, T) \times \Omega)$ into $(-\infty, \infty]$ and the subdifferential $\partial\phi$ of ϕ is the prolongation of $\partial\phi$ to $L^2((0, T) \times \Omega)$. By (3), $w_{\varepsilon_n}(t) + A_2 v_{\varepsilon_n}(t) \geq 0$ and thus $w_{\varepsilon_n} + \partial\phi v_{\varepsilon_n} \geq 0$. For every $z \in L^2((0, T) \times \Omega)$,

$$\begin{aligned} \phi(z) - \phi(v_{\varepsilon_n}) &\geq \int_0^T \int_{\Omega} (-w_{\varepsilon_n}) (z - v_{\varepsilon_n}) \\ &= \int_0^T \int_{\Omega} (-w_{\varepsilon_n}) z + \int_0^T \int_{\Omega} w_{\varepsilon_n} v_{\varepsilon_n}. \end{aligned}$$

By (6),

$$\begin{aligned} \int_0^T w_{\varepsilon_n} v_{\varepsilon_n} &= \int_0^T \frac{u_{\varepsilon_n}(t) - u_{\varepsilon_n}(t - \varepsilon_n)}{\varepsilon_n} v_{\varepsilon_n} \\ &= \int_0^T \frac{J(u_{\varepsilon_n}(t)) - J(u_{\varepsilon_n}(t + \varepsilon_n))}{\varepsilon_n} \\ &= \frac{1}{\varepsilon_n} \sum_{i=1}^k \int_{(i-1)\varepsilon_n}^{i\varepsilon_n} (J(u_{\varepsilon_n}(t)) - J(u_{\varepsilon_n}(t - \varepsilon_n))) \\ &= \frac{1}{\varepsilon_n} \left(\int_{(k-1)\varepsilon_n}^{k\varepsilon_n} J(u_{\varepsilon_n}(T)) - \int_0^{\varepsilon_n} J(u_0) \right) \\ (7) \quad &= J(u_{\varepsilon_n}(T)) - J(u_0), \end{aligned}$$

where $T = k\varepsilon_n$. By [2], $t \rightarrow J(u(t))$ is absolutely continuous and *a. e. t* $\varepsilon(0, T)$,

$$(8) \quad \frac{d}{dt} J(u(t)) = \int_{\Omega} v(t) \frac{du}{dt}(t).$$

By (8),

$$\begin{aligned} \int_0^T \int_{\Omega} v(t) \frac{du}{dt}(t) &= \int_0^T \frac{d}{dt} (J(u(t))) = J(u(T)) - J(u_0) \\ (9) \quad &= J(u(T)) - J(u_{\varepsilon_n}(T)) + J(u_{\varepsilon_n}(T)) - J(u_0). \end{aligned}$$

By (7)-(9),

$$\phi(z) \geq \phi(v_{\varepsilon_n}) + \int_0^T \int_{\Omega} (-w_{\varepsilon_n}) z$$

$$+\int_0^T \int_{\Omega} v(t) \frac{du}{dt}(t) + J(u_{\varepsilon_n}(T)) - J(u(T)).$$

Since $\phi(v) \leq \lim_{\varepsilon_n \rightarrow 0^+} \phi(v_{\varepsilon_n})$ and $J(u(t)) \leq \lim_{\varepsilon_n \rightarrow 0^+} J(u_{\varepsilon_n}(T))$,

$$\phi(z) \geq \phi(v) + \int_0^T \int_{\Omega} \left(-\frac{du}{dt}\right) z + \int_0^T \int_{\Omega} v \frac{du}{dt}.$$

Hence for every $z \in L^2((0, T) \times \Omega)$,

$$\phi(z) - \phi(v) \geq \int_0^T \int_{\Omega} \left(-\frac{du}{dt}\right) (z - v).$$

Thus $-\frac{du}{dt} \varepsilon \partial \phi(v)$, that is $\frac{du}{dt}(t) + A_2 v(t) \geq 0$ a. e. $t \in (0,$

$T)$. Since $v(t) \in L^\infty(\Omega)$, $\frac{du}{dt}(t) + Av(t) \geq 0$ a. e. $t \in (0, T)$.

By (5), $\frac{du}{dt}(t) + A\beta u(t) \geq 0$ a. e. $t \in (0, T)$.

3. Example.

Let $\phi: L^2(\Omega) \rightarrow [0, \infty]$ be a function with $\phi(0) = 0$ satisfying:

$$(10) \quad \begin{aligned} \phi(u_1 - p(u_1 - u_2)) + \phi(u_2 + p(u_1 - u_2)) \\ \leq \phi(u_1) + \phi(u_2) \end{aligned}$$

for every $u_1, u_2 \in L^2(\Omega)$ and $p \in C^1(R)$ with $0 < p' < 1$, $p(0) = 0$.

If $\phi: L^2(\Omega) \rightarrow [0, \infty]$ is a lower semi-continuous convex function with $\phi(0) = 0$ satisfying (10), then $A = \partial \phi \cap L^\infty(\Omega) \times L^\infty(\Omega)$ satisfies (HC) ([4]).

Let Ω be a bounded open subset of R^N with smooth bord Γ . Let $j: R \rightarrow [0, \infty]$ be a lower semi-continuous convex function with $j(0) = 0$ and $r = \partial j$. We define a function ϕ on $L^2(\Omega)$ by

$$(11) \quad \phi(u) = \begin{cases} \int_{\Omega} \frac{1}{2} |\text{grad} u|^2 + \int_{\Gamma} j(u) & \text{if } u \in H^1(\Omega) \\ +\infty & \text{otherwise.} \end{cases}$$

Then $\phi: L^2(\Omega) \rightarrow [0, \infty]$ is a lower semi-continuous convex function with $\phi(0) = 0$ and the subdifferential $\partial\phi$ of ϕ :

$$(12) \quad \partial\phi = \{(u, v) \in L^2(\Omega) \times L^2(\Omega) \mid u \in H^2(\Omega), v = -\Delta u \text{ a. e. on } \Omega \\ \text{and } \frac{\partial u}{\partial n} + \gamma(u) = 0 \text{ a. e. on } \Gamma\},$$

where $\frac{\partial u}{\partial n}$ is the exterior normal derivative ([4]).

By [4], ϕ of (11) satisfies (10). Thus $A = \partial\phi \cap L^\infty(\Omega) \times L^\infty(\Omega)$ for $\partial\phi$ of (12) satisfies (HC) ([4]).

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