

Clusters and Smirnov Compactification of E_0 -proximity Spaces

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I. Introduction

In this paper, we deal with the compactification problem of E_0 -proximity spaces. The concept of a cluster, the analogue in a proximity space of an ultrafilter, was introduced by Leader [8] and provides an alternative approach to many proximity problem. In particular, Leader[8] obtained the compactification of a proximity space X to be the family of all clusters in X . Since the Smirnov compactification is unique, it is evident that a one-to-one correspondence exists between clusters and ends. In this note we try to obtain the Smirnov compactification of the E_0 -proximity space by using cluster.

II. Preliminaries

The theory of proximity spaces was essentially discovered in the early 1950's by Efremovič when he axiomatically characterized the proximity relation A is near B , which is denoted by $A\delta B$, for subsets A and B of any set X . Efremovič's axioms of proximity relation δ are as follows;

- B1. $A\delta B$ implies $B\delta A$
- E2. $(A \cup B)\delta C$ if and only if $A\delta C$ or $B\delta C$
- E3. $A\delta B$ implies $A \neq \phi$, $B \neq \phi$.
- E4. $A\delta B$ implies there exists a subset E such that $A\delta E$ and $(X-E)\delta B$.
- E5. $A \cap B \neq \phi$ implies $A\delta B$.

A binary relation δ satisfying axioms E1-E5 on the power set of X is called a (Efremovič) proximity on X . If δ also satisfies the following;

- E6. $x\delta y$ implies $x=y$

then δ is called the separated proximity relation.

Definition 1. Let δ be a binary relation between a set X and its power set $P(X)$ such that

$E_01.$ $x\delta \{y\}$ implies $y\delta \{x\}$.

$E_02.$ $x\delta (A \cup B)$ if and only if $x\delta A$ or $x\delta B$

$E_03.$ $x \not\delta \phi$ for all $x \in X$.

$E_04.$ $x \in A$ implies $x\delta A$.

$E_05.$ For each subset $E \subset X$ there is a point $x \in X$ such that either $x\delta A$, $x\delta E$ or $x\delta B$, $x\delta (X-E)$, then we have $y\delta A$ and $y\delta B$ for some $y \in X$. The binary relation δ is called the E_0 -proximity on X iff δ satisfies the axioms E_01 - E_05 . The pair (X, δ) is called the E_0 -proximity spaces.

Theorem 1. In an E_0 -proximity spaces (X, δ) let δ_1 be a binary relation on $P(X)$ defined as follows; $A\delta_1 B$ if and only if there is a point $x \in X$ such that $x\delta A$, $x\delta B$, then δ_1 is Efremovič proximity.

Definition 2. If on a set X there is a topology ζ and a E_0 -proximity δ such that $\zeta = \zeta(\delta)$, then ζ and δ are said to be compatible.

Theorem 2. In an E_0 -proximity space (X, δ) , if A^δ is defined to be a set $\{x | x\delta A, x \in A\}$ for each subset A of X , then δ is a Kuratowski closure operator. We consider the relation ultrafilter and cluster in E_0 -proximity spaces. It is well known that a family \mathcal{L} of subsets of a non-empty set X is an ultrafilter if and only if the following conditions are satisfied;

- (i) If A and B belong to \mathcal{L} , then $A \cap B \in \mathcal{L}$.
- (ii) If $A \cap C \in \mathcal{L}$ for every $C \in \mathcal{L}$, then $A \in \mathcal{L}$.
- (iii) If $(A \cup B) \in \mathcal{L}$, then $A \in \mathcal{L}$ or $B \in \mathcal{L}$.

Now we consider the family of sets in an E_0 -proximity space satisfying condition similar to (i), (ii), (iii), with nearness replacing non-empty intersection and we are led to the following definition;

Definition 3. A family σ of subsets of an E_0 -proximity space (X, δ) is called a cluster, iff the following conditions are satisfied;

- (1) If A and B belong to σ , then there is a point $x \in X$ such that $x\delta A$ and $x\delta B$.
- (2) If for every $C \in \sigma$, there is a point $x \in X$ such that $x\delta A$, $x\delta C$, then $A \in \sigma$.
- (3) If $(A \cup B) \in \sigma$, then $A \in \sigma$ or $B \in \sigma$.

Lemma 1. For each x in the E_0 -proximity space (X, δ) , the family $\sigma_x = \{A \subset X | x\delta A\}$ is a cluster.

Lemma 2. If σ is any cluster in (X, δ) , then $A \in \sigma$ if and only if $\bar{A} \in \sigma$.

Lemma 3. If a cluster σ in an E_0 -proximity space (X, δ) is determined by an ultrafilter \mathcal{L} then σ is a point cluster σ_x if and only if \mathcal{L} converges to x . E_0 -proximity mapping $f: (X, \delta_1) \rightarrow (Y, \delta_2)$ can be defined similar to the Efremovič proximity mapping, that is, f is an E_0 -proximity mapping iff $x\delta_1 A$ implies $f(x)\delta_2 f(A)$. It can be easily shown that E_0 proximity mapping is continuous.

Theorem 3. If f is an E_0 -proximity mapping from (X, δ_1) to (Y, δ_2) , then to each cluster σ_1 in X , there corresponds a cluster σ_2 in Y such that $\sigma_2 = \{B \subset Y | \text{for each } A \in \sigma_1, \text{ there is a point } y \in Y \text{ with } y\delta_2 B, y\delta_2 f(A)\}$.

III. The main theorem

Using cluster, we shall now construct the Smirnov compactification of a separated E_0 -proximity space. Let (X, δ) be a separated E_0 -proximity space and let \mathcal{X} denote the set of all clusters in X . For $A \subset X$, let $\bar{A} = \{\sigma \in \mathcal{X} | A \in \sigma\}$. For $x \in X$, let $f(x) = \sigma_x$ (the point cluster). Then it is easy to see that (i) f is a one-to-one mapping, and (ii) $f(A) \subset \bar{A}$. It is to obtain property (i) that we insist on the E_0 -proximity δ being separated, for we are then assured that each point $x \in X$ is a member of one and only one cluster in X .

Definition 4. For $P \subset \mathcal{X}$, we say that a subset A of X absorbs P iff $A \in \sigma$ for every $\sigma \in P$, that is, $P \subset \bar{A}$, denoted $A \vdash P$.

Lemma 4. The binary relation δ^* on the power set of \mathcal{X} defined by $P\delta^*Q$ iff A absorbs P and

B absorbs \mathcal{L} implies that there is a point $x \in X$ such that $x\delta A, x\delta B$, is a separated proximity on \mathfrak{X} .
proof. E1. is clear.

E2. Suppose that $(P \cup \mathcal{L})\delta^*\mathcal{L}$ and that $P\delta^*\mathcal{L}$. Let $B \mapsto \mathcal{L}$ and $C \mapsto \mathcal{L}$, then we must show that there is some $x \in X$ with $x\delta B, x\delta C$. Since $P\delta^*\mathcal{L}$, there are sets A and D absorbing P and \mathcal{L} respectively such that for each point $x \in X$, $x\delta A$ or $x\delta D$. By definition 1-(E₀5) there is a subset $E \subset X$ such that for each point $x \in X$ neither $x\delta A, x\delta E$ nor $x\delta D, x\delta(X-E)$. Since $D \mapsto \mathcal{L}$ and $x\delta D$ or $x\delta(X-E)$ for each $x \in X$, $(X-E)$ belongs to no cluster in \mathcal{L} . Consequently, $(C-E)$ belongs to no cluster in \mathcal{L} . But $C = (C-E) \cup (C \cap E) \mapsto \mathcal{L}$ implies that $(C \cap E) \mapsto \mathcal{L}$. Now $(A \cup B) \mapsto (P \cup \mathcal{L})$ implies that there is some $x \in X$ with $x\delta(A \cup B), x\delta(C \cap E)$. Since for each $y \in X$ $y\delta A$ or $y\delta E$, we also have for each $y \in X$ $y\delta A$ or $y\delta(C \cap E)$. Hence we have for some $x \in X$ $x\delta B$ and $x\delta(C \cap E)$, that is, $x\delta B$ and $x\delta C$. Conversely suppose that $\mathcal{L}\delta^*\mathcal{L}, D \mapsto (P \cup \mathcal{L})$ and $C \mapsto \mathcal{L}$. Then $D \mapsto \mathcal{L}$ and we have for some $x \in X$ $x\delta D$ and $x\delta C$. Thus $(P \cup \mathcal{L})\delta^*\mathcal{L}$.

E3. That $P\delta^*\mathcal{L}$ implies P and \mathcal{L} are nonempty in clear.

E4. If $P\delta^*\mathcal{L}$, there are sets A and B absorbing P and \mathcal{L} respectively such that for each $x \in X$, $x\delta A$ or $x\delta B$. By definition 1-(E₀5), there is a subset $E \subset X$ such that for each $x \in X$, $x\delta A$ or $x\delta E$ and $x\delta B$ and $x\delta(X-E)$. Since for each $x \in X$ $x\delta B$ or $x\delta(X-E)$, and $B \mapsto \mathcal{L}$, $(X-E)$ belongs to no cluster in \mathcal{L} . Thus $E \mapsto \mathcal{L}$. Now let $\mathcal{L} = \bar{\mathcal{L}}$. Then $P\delta^*\mathcal{L}$ because $A \mapsto P, E \mapsto \mathcal{L}$ and for each $x \in X$ $x\delta A$ or $x\delta E$. Since E belongs to no cluster in $(\mathfrak{X} - \mathcal{L})$, $(X-E) \mapsto (\mathfrak{X} - \mathcal{L})$. Therefore $(\mathfrak{X} - \mathcal{L})\delta^*\mathcal{L}$ since for each $x \in X$ $x\delta B$ or $x\delta(X-E)$.

E5. Suppose that $P \cap \mathcal{L} \neq \emptyset$ and $A \mapsto P, B \mapsto \mathcal{L}$. Then both A and B absorbs $P \cap \mathcal{L}$, so that there is some $x \in X$ with $x\delta A$ and $x\delta B$. Hence $P\delta^*\mathcal{L}$.

E6. $A \mapsto \{\sigma\}$ where $\sigma \in \mathfrak{X}$ iff $A \in \sigma$. Hence $\sigma_1\delta^*\sigma_2$ iff $\sigma_1 = \sigma_2$. Thus δ^* is separated. Now let ζ^* be the induced topology on \mathfrak{X} by δ^* , then ζ^* is a completely regular topology.

Theorem 4. (X, δ) is homeomorphic to $f(X)$ with the subspace proximity induced by δ^* , and $f(X)$ is dense in \mathfrak{X} .

proof. We first note that $\mapsto f(B)$ iff $B \subset A^\delta$. Hence for each $\sigma \in \mathfrak{X}$, $\sigma\delta^*f(A)$ iff $C \in \sigma$ and $B \mapsto f(A)$ imply that there is some $x \in X$ with $x\delta C$ and $x\delta B$, iff $C \in \sigma$ and $A \subset B^\delta$ imply that there is some $x \in X$ with $x\delta C$ and $x\delta B$ iff $A \in \sigma$. That is, \bar{A} is the ζ^* closure of $f(A)$. Since X belongs to each cluster in X , $f(X)$ is dense in \mathfrak{X} . No $\sigma_x\delta^*f(A)$ iff $A \in \sigma_x$ iff $x\delta A$. Thus X is homeomorphic to $f(X)$.

Theorem 5. (\mathfrak{X}, ζ^*) is compact.

proof. By lemma 3, it suffices to prove that each cluster ζ in \mathfrak{X} is a point cluster. Since $f(X)$ is dense in \mathfrak{X} , lemma 2 implies that $f(X) \in \zeta$. From theorem 2, there is a unique cluster \mathcal{T}' in $f(X)$ such that $\mathcal{T}' \subset \mathcal{T}$. But X is E_0 -proximally isomorphic to $f(X)$, so that there is a cluster σ in X which corresponds to \mathcal{T}' . Now from the proof of theorem 4, we know that $\sigma\delta^*f(A)$ iff $A \in \sigma$. Applying the theorem 3, we obtain $\{\sigma\} \in \mathcal{T} \subset \mathcal{T}$ showing that \mathcal{T} is indeed a point cluster in \mathfrak{X} . Since \mathfrak{X} is a compact Hausdorff completely regular space, we know that $P\delta^*\mathcal{L}$ iff there is some $\sigma \in \mathfrak{X}$ with $\sigma\delta^*P$ and $\sigma\delta^*\mathcal{L}$. Hence the restriction of δ^* to $\mathfrak{X}XP(\mathfrak{X})$ is the E_0 -proximity on \mathfrak{X} . From this combining the above sequence of the theorem we obtain the main result of this paper.

Theorem 6. *Every separated E_0 -proximity space is a dense subspace of a compact separated E_0 -proximity space. Since \mathcal{X} has a unique compatible separated proximity, subsets A and B of X are near iff their closures in \mathcal{X} intersect (\mathcal{X} is called the Smirnov compactification of X).*

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