PL INVOLUTIONS OF 3-MANIFOLDS

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1. Introduction

My general purpose here is to present recent developments in the theory of *PL* involutions of 3-manifolds. Later, I will point out drastic deviations in high dimensional case. The presentation will be necessarily limited and incomplete but I will try to make it coherent.

2. PL involutions of the 3-sphere and 3-space

- 2.0. If h is an involution of a space X, the fixed point set of h will be denoted by F(X, h) or simply by F(h). Suppose h is a PL involution of a finite complex K. Then it is not difficult to show that h is simplicial on some subdivision of K. If h is a PL involution of a 3-manifold M, likewise there exists a triangulation of M with respect to which h is simplicial.
- 2.1. Now let h be a PL involution of S^3 . If F(h) is a 2-sphere, it is easy to see that h is equivalent to the reflection of S^3 through its equator. It is known [30] that F(h) is an r-sphere, r=-1,0,1, or 2. Case r=-1,0,1 had been unsolved until Livesay [24,25] solved cases r=-1 and 0 in 1963. In each of the cases r=-1 and 0, h is equivalent to the standard one. The remaining case r=1 was finally solved by Waldhausen [37] in 1969.
- 2.2. Now let h be a PL involution of 3-space. The reason why this case is not a corollary to the case of S^3 is that the one point compactification of h need not be PL even though h is. According to Smith [30], of course F(h) is an r-space, r=0,1 or 2. The case r=0 was solved by Livesay. The case r=2 was solved by Harrold and Moise [4] who showed that if a 2-sphere in S^3 is locally tame except at a point, then at least one complementary domain has a 3-cell as closure. The case r=1 was finally solved by Kwun and Tollefson [20] in 1973 who in fact show that if X is a closed 3-manifold

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and h is an involution of X such that h|X-a is equivalent to a PL involution, where $a \in F(h)$, then h itself is equivalent to a PL one. Thus there are exactly three non-equivalent PL involutions of 3-space.

3. PL involutions of 3-manifolds

PL involutions of 3-manifolds in general had not been studied in depth until recently mainly because there weren't enough tools or techniques. By this time, we have a proof of Dehn's lemma [28], sphere theorem [38], the fibering theorem [31] of Stallings, the product theorem [3] of E. Brown, the uniqueness of connected sum [26], and Waldhausen theory [36].

Using results like these and/or others. *PL* involutions of many individual 3-manifolds have been studied. For example, see [5, 6, 7, 8, 10, 27, 29, 13, 14, 15, 16, 32, 33, 34].

More recently, Tollefson [35] introduced a new technique which was refined and extended by himself and others, brought a new depth in analysing *PL* involutions of 3-manifolds. I particularly mention the following two results.

PRODUCT THEOREM (Kim and Tollefson [11]) Let S be a compact connected and h a PL involution of $S \times [0,1]$ such that $h(S \times \{0,1\}) = S \times \{0,1\}$. Then h is equivalent to some $\alpha \times \beta$, where α is an involution or the identity of S and $\beta(t) = 1 - t$ or t.

EXTENTION THEOREM (Kwun and Tollefson [22]) Let X be a compact 3-manifold and h a PL involution of the interior X of X. Then there exists one and only one equivalent class of PL involutions of X whose restriction to X is equivalent to h.

The first theorem is clearly useful in studying PL involutions of $S \times [0, 1]$ and $S \times S^1$, for example, [11, 21, 22]. The second theorem is also very useful. Until the extension theorem, PL involutions of such simple space as $R^2 \times S^1$ could not be classified. Now we know there exists exactly seven non-equivalent PL involutions. (Also see the next sections.)

4. Tame fixed point sets

Now that PL involutions of many 3-manifolds can be completely analysed, it would be nice to know when a given involution of a 3-manifold is equi-

valent to a PL one. This is answered by Kwun [19] for closed 3-manifolds. The necessary and sufficient condition is that F(h) be tame. This result was just recently extended to a quite general case by Kwun and Tollefson [23]. The last result implies that (1) if A is the set of points where F(h) fails to be locally tame, then A has no isolated point and (2) an involution h of a 3-manifold (with or without boundary, compact or not) is equivalent to a PL one if and only if F(h) is tame.

Then it follows that Bing's examples [1, 2] of bad involutions of S^3 are simplest possible.

5. Involutions of high dimensional manifolds

Involutions of high dimensional manifolds behave quite differently. For example, for a closed n-manifold M, $n \ge 5$, there are infinitely many non-equivalent PL involutions h of $M \times [0,1]$ such that $h(M \times 0) = M \times 0$ and no h is equivalent to a product involution. (See [18]). Also using [18, 19]. it was shown [22] that the extension theorem in Section 3 also fails in two ways. Some PL involution h of \mathring{X} (for a suitable h and X) is not equivalent to the restriction of any PL involution of X and also for suitable h and X, it is possible to find infinitely many non-equivalent PL involutions $h_1, h_2, ...$ of X such that $h_i \mid \mathring{X}$ are all equivalent to h.

Regarding Section 4, it is easy to have an isolated bad point in F(h) in high dimensions.

6. Final remarks

There has been a question whether every closed 3-manifold admits an involution. Tollefson first came up with a closed 3-manifold which admit no *PL* homeomorphism of a finite period. Just recently, Raymond and Tollefson showed that the same manifold has no homeomorphism of a finite period of any kind.

Kim and Tollefson found [12] a way to reduce involutions of many 3-manifolds to involutions of simpler 3-manifolds.

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