

**THE CORRESPONDENCES OF THE FUNDAMENTAL FRAMES
ON THE PARAMETER GROUP MANIFOLDS**

By Jae Koo Ahn

0. Introduction.

We consider the first parameter group manifold $\mathcal{G}^{(+)}$ and the second parameter group manifold $\mathcal{G}^{(-)}$, given (+)-connection $L_{\beta\gamma}^{\alpha}$ and (-)-connection $\bar{L}_{\beta\gamma}^{\alpha}$ by N. Horie respectively[2]. The purpose of this paper is to study on some properties of the correspondence of the fundamental frames in the sense of the operation, so called it the extended exterior differentiation by H. Flanders [1].

Let us take the followings as the equations of the combinations in the continuous transformation group of dimension r :

$$a_3^{\alpha} = \varphi^{\alpha}(a_1, a_2), \quad (\alpha=1, \dots, r).$$

Then we may consider the equations

$$\frac{\partial a_3^{\alpha}}{\partial a_2^{\beta}} = A_b^{\alpha}(a_3)A_{\beta}^b(a_2), \quad \frac{\partial a_3^{\alpha}}{\partial a_1^{\beta}} = \bar{A}_b^{\alpha}(a_3)\bar{A}_{\beta}^b(a_1)$$

as the fundamental equations of the parameter groups $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$ respectively, where determinant $|A_b^{\alpha}|$ is not zero and $||A_{\alpha}^b||$ is the inverse matrix of $||A_b^{\alpha}||$, and \bar{A} 's are similar to A 's.

Let the *fundamental frames* $A_{\alpha}, \bar{A}_{\alpha}$ ($\alpha=1, \dots, r$) is $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$ are defined by the pairs $(A_{\alpha}^1, \dots, A_{\alpha}^r)$ and $(\bar{A}_{\alpha}^1, \dots, \bar{A}_{\alpha}^r)$ in the same local coordinate neighborhood U respectively, then we may consider the *dual bases* D^{α} and \bar{D}^{α} ($\alpha=1, \dots, r$) and define the extended exterior differentiation as H. Flanders [1], [3].

Using the matrix notations, we shall set

$$A = \begin{pmatrix} A_1 \\ \vdots \\ A_r \end{pmatrix}, \quad D = (D^1, \dots, D^r).$$

Denoting the *fundamental displacement*, the *connection form*, the *torsion form* and the *curvature form* by dP, Ω, T and Θ on $\mathcal{G}^{(+)}$ respectively, then we may refer to be defined by the following equations [3]:

- (0. 1) $dP = DA,$
(0. 2) $dA = \Omega A, \quad \Omega = ||w_{\beta}^{\alpha}||, \quad (w_{\beta}^{\alpha} \text{ are 1-forms}),$
(0. 3) $d^2P = d(dP) = TA, \quad T = dD - D\Omega, \quad (T \text{ are 2-forms}),$

$$(0. 4) \quad dT = D\Theta - T\Omega, \quad \Theta = d\Omega - \Omega^2 \quad (\Theta \text{ are 2-forms}).$$

And on $\mathcal{G}^{(-)}$, they are defined by the same manner.

Now, we can awake that the both curvature forms on $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$ vanish, since the curvature tensor fields $L_{\beta\gamma\delta}^\alpha$ and $\bar{L}_{\beta\gamma\delta}^\alpha$ vanish, and hence, on $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$, Θ and $\bar{\Theta}$ are zero matrices, and thus, (0. 4) are reduced to (0. 5)

$$(0. 5) \quad dT = -T\Omega, \quad d\Omega = \Omega^2.$$

1. The linear correspondences of the fundamental frames between $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$

Let A and \bar{A} be two fundamental frames of $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$ defined in the same local coordinate neighborhood U , and we suppose that there exists a linear correspondence

$$(1. 1) \quad \bar{A} = sA$$

between the parameter group manifolds $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$, where s is a nonsingular matrix everywhere on U , whose elements are s_β^α ($\alpha, \beta = 1, \dots, r$). Then the

bases D and \bar{D} of the given frames are related by

$$(1. 2) \quad \bar{D} = Ds^{-1},$$

being a consequence of $dP = DA = \bar{D}\bar{A}$. And from $d^2P = TA = \bar{T}\bar{A}$, the torsion forms T and \bar{T} are also related by

$$(1. 3) \quad \bar{T} = Ts^{-1}.$$

If we differentiate (1. 1), we have

$$d\bar{A} = \bar{\Omega}\bar{A} = dsA + s\Omega A,$$

and hence,

$$(1. 4) \quad \bar{\Omega}s = ds + s\Omega \text{ or } \bar{\Omega} = dss^{-1} + s\Omega s^{-1}.$$

Writting this by the element form, it is

$$(1. 5) \quad \bar{w}_\beta^\alpha = ds_\tau^\alpha {}^1s_\beta^\tau + s_\tau^\alpha w_\sigma^\tau {}^1s_\beta^\sigma$$

where 1s 's are defined by

$${}^1s_\beta^\alpha = (\text{cofactor of } s_\alpha^\beta \text{ in } s) / |s|,$$

and consequently,

$$(1. 6) \quad s_\tau^\alpha {}^1s_\beta^\tau = \delta_\beta^\alpha,$$

On account of $w_\beta^\alpha = L_{\beta\tau}^\alpha D^\tau$ and $\bar{L}_{\beta\gamma}^\alpha = L_{\gamma\beta}^\alpha$ on $\mathcal{G}^{(+)}$ and $\mathcal{G}^{(-)}$ [2], using of (1. 2)

and contracting s_σ^β with respect to β , we get

$$(1.7) \quad \frac{\partial s_\beta^\alpha}{\partial a^\gamma} = L_{\sigma\tau}^\alpha |s_\gamma^\sigma s_\beta^\tau - L_{\beta\gamma}^\tau s_\tau^\alpha.$$

Differentiating (1.6) by a^γ and using of (1.7), we have

$$(1.8) \quad \frac{\partial s_\beta^\alpha}{\partial a^\gamma} = -L_{\sigma\beta}^\tau |s_\gamma^\sigma s_\tau^\alpha + L_{\tau\gamma}^\alpha |s_\beta^\tau.$$

If we differentiate (1.7) and (1.8) by a^δ , interchange γ and δ , and subtract each other, since the curvature tensor of $\mathcal{Q}^{(+)}$ vanishes, we obtain the followings as the conditions of the complete integrability of (1.7) and (1.8) respectively:

$$(1.9) \quad \left[\frac{\partial L_{\sigma\tau}^\alpha}{\partial a^{[\gamma}} |s_{\delta]}^\sigma + L_{[\lambda|\sigma|}^\alpha L_{\mu\tau]}^\sigma |s_\gamma^\lambda |s_\sigma^\mu - (L_{\sigma\tau}^\alpha s_\lambda^\sigma + L_{\lambda\tau}^\alpha) L_{\mu[\gamma}^\lambda |s_{\delta]}^\mu \right] s_\beta^\tau + 2L_{\sigma[\gamma}^\tau L_{\sigma|\beta|\delta]} s_\tau^\alpha = 0^{(*)},$$

$$(1.10) \quad \left[\frac{\partial L_{\sigma\beta}^\tau}{\partial a^{[\gamma}} |s_{\delta]}^\sigma + (L_{\lambda\beta}^\tau + L_{\sigma\beta}^\tau |s_\lambda^\sigma) L_{\mu[\gamma}^\lambda |s_{\delta]}^\mu - L_{\sigma\beta}^\lambda L_{[\lambda\mu]}^\tau |s_\gamma^\sigma |s_\delta^\mu \right] s_\tau^\alpha + 2L_{\lambda[\gamma}^\alpha L_{|\tau|\delta]}^\lambda |s_\tau^\beta = 0.$$

Thus, we may assert that, for the linear correspondence from $\mathcal{Q}^{(+)}$ to $\mathcal{Q}^{(-)}$ and its inverse to exist, it is necessary and sufficient that (1.9) and (1.10) hold respectively.

On the other hand, it is well known that the existence of the linear correspondence (1.1) from $\mathcal{Q}^{(+)}$ to $\mathcal{Q}^{(-)}$ is equivalent to the one of the solutions of the (1.4), and consequently, it must hold $d^2s=0$. If we differentiate (1.4), we have

$$(1.11) \quad d^2s = d\bar{\Omega}s - \Omega ds - ds\Omega - sd\Omega.$$

In consequence of $\bar{L}_{\beta\gamma\delta}^\alpha = 0$, it is shown by matrix form that

$$(1.12) \quad d\bar{\Omega} = \bar{\Omega}^2,$$

and hence, (1.11) is reduced to

$$d^2s = \bar{\Omega}^2 s - \bar{\Omega} (\bar{\Omega}s - s\Omega) - (\bar{\Omega}s - s\Omega)\Omega - s\Omega^2 = 0.$$

Thus, it obtains that there exist the solutions of (1.4) always, and consequently, (1.9) holds identically.

Next, since $|s| \neq 0$, we have $A = s^{-1}\bar{A}$ from (1.1), and differentiating it, we have

(*) $K_{[\alpha\beta]}$ denotes $K_{\alpha\beta} - K_{\beta\alpha}$.

$$\Omega A = ds^{-1}sA + s^{-1}\Omega sA$$

or

$$(1.13) \quad ds^{-1} = \Omega s^{-1} - s^{-1}\Omega.$$

And differentiating (1.13) too, we have from (1.12) and (1.3) $d^2s^{-1} = 0$, and hence, there exist the solutions of (1.13), and consequently, we obtain that (1.10) holds identically. From the above result, we obtain the following:

THEOREM 1 *There exists always the linear correspondence between the frames A and \bar{A} from $\mathcal{G}^{(+)}$ to $\mathcal{G}^{(-)}$ and its inverse, (1.9) and (1.10) are satisfied identically.*

If we differentiate (1.3), using of (1.3), then we have

$$(1.14) \quad d\bar{T} = -\bar{T}\bar{\Omega}$$

and

$$(1.15) \quad d^2\bar{T} = 0$$

And from (1.12), we have

$$(1.16) \quad d\bar{\Omega}^{2k} = 0, \quad d\bar{\Omega}^{2k+1} = \bar{\Omega}^{2k+2}, \quad (k \geq 0).$$

From (1.12), (1.14), (1.15), (1.16) and the results of the previous paper [3], we have the following:

THEOREM 2. *For the linear correspondence between the frames A and \bar{A} from $\mathcal{G}^{(+)}$ to $\mathcal{G}^{(-)}$, the identities (1.12), (1.14), (1.15) and (1.16) are preserved.*

2. The linear correspondence of the fundamental frames on $\mathcal{G}^{(0)}$.

We are well known that the parameter group manifold $\mathcal{G}^{(0)}$ is defined by the connection [2]

$$(2.1) \quad w_{\beta}^{\alpha} = \Gamma_{\beta\gamma}^{\alpha} D^{\gamma},$$

where

$$\Gamma_{\beta\gamma}^{\alpha} = \frac{1}{2}(L_{\beta\gamma}^{\alpha} + \bar{L}_{\beta\gamma}^{\alpha}), \quad \bar{L}_{\beta\gamma}^{\alpha} = L_{\gamma\beta}^{\alpha}.$$

Then, on $\mathcal{G}^{(0)}$, it may assert that

$$(2.2) \quad \Gamma_{\beta\gamma}^{\alpha} = \Gamma_{\gamma\beta}^{\alpha},$$

and the frames on $\mathcal{G}^{(0)}$ are A or \bar{A} . In this section, we shall investigate the linear correspondence between two frames.

Let us suppose that their frames A and \bar{A} are the related by (1. 1), and then, their dual bases D and \bar{D} are (1. 2). From (1. 1), we have (1. 4). Since $\bar{w}_\beta^\alpha = \Gamma_{\beta\gamma}^\alpha {}^1s_\tau^\gamma D^\tau$ from (2. 1) and (2. 2), writting (1. 4) by element form, we have

$$ds_\beta^\alpha = \bar{w}_\sigma^\alpha s_\beta^\sigma - s_\sigma^\alpha w_\beta^\sigma,$$

and thus,

$$(2. 3) \quad \frac{\partial s_\beta^\alpha}{\partial a^\gamma} = \Gamma_{\sigma\tau}^\alpha s_\beta^\sigma {}^1s_\gamma^\tau - \Gamma_{\beta\gamma}^\sigma s_\sigma^\alpha.$$

Differentiating (1. 6) by a^γ , we obtain

$$(2. 4) \quad \frac{\partial {}^1s_\beta^\alpha}{\partial a^\gamma} = -\Gamma_{\beta\tau}^\sigma s_\gamma^\tau {}^1s_\sigma^\alpha + \Gamma_{\tau\gamma}^\alpha {}^1s_\beta^\tau.$$

If we differentiate (2. 3) and (2. 4) by a^δ , interchange γ and δ , and subtract each other, we obtain the followings as the conditions of the complete integrability of (2. 3) and (2. 4) respectively:

$$(2. 5) \quad \left(\frac{\partial \Gamma_{\sigma\tau}^\alpha}{\partial a^{[\gamma}} + \Gamma_{\sigma\lambda}^\alpha \Gamma_{\tau] \gamma}^\lambda \right) {}^1s_\delta^\tau s_\beta^\sigma + \Gamma_{\mu[\sigma}^\lambda \Gamma_{\tau]\lambda}^\alpha s_\beta^\mu {}^1s_\gamma^\sigma {}^1s_\delta^\tau \\ + \Gamma_{\sigma\tau}^\alpha \Gamma_{\mu[\gamma}^\lambda s_\delta^\mu s_\beta^\sigma {}^1s_\lambda^\tau - 2\Gamma_{\beta[\gamma}^\lambda \Gamma_{\delta]\lambda}^\sigma s_\sigma^\alpha + \Gamma_{\beta\gamma\delta}^\sigma s_\sigma^\alpha = 0.$$

$$(2. 6) \quad \left(\frac{\partial \Gamma_{\beta\tau}^\sigma}{\partial a^{[\gamma}} s_\delta^\tau + \Gamma_{\beta\tau}^\sigma \Gamma_{\lambda\mu}^\tau s_{[\gamma}^\mu s_{\delta]}^\lambda + \Gamma_{\beta[\lambda}^\tau \Gamma_{\mu]\tau}^\sigma s_\gamma^\lambda s_\delta^\mu \right) {}^1s_\sigma^\alpha \\ - 2\Gamma_{\tau[\gamma}^\lambda \Gamma_{\delta]\lambda}^\alpha {}^1s_\beta^\tau - \Gamma_{\tau\gamma\delta}^\alpha {}^1s_\beta^\tau = 0.$$

Thus we may assert that, for the linear correspondence from $\mathcal{Q}^{(+)}$ and $\mathcal{Q}^{(-)}$ and its inverse to exist, it is necessary and sufficient that (2. 5) and (2. 6) hold respectively.

On the other hand, if we differentiate (1. 4), we have by using of (0. 4) and (1. 4), (1.13), since they are satisfied on $\mathcal{Q}^{(0)}$,

$$d\bar{\Omega} = \bar{\Omega}^2 + s\Theta s^{-1} + d^2 s s^{-1}.$$

In consequence of $\bar{\Theta} = s\Theta s^{-1}$ [1], this is reduced to

$$d\bar{\Omega} = \bar{\Omega}^2 + \bar{\Theta} + d^2 s s^{-1}.$$

Then, we obtain that $d^2 s = 0$ is equivalent to

$$(2. 7) \quad d\bar{\Omega} = \bar{\Omega}^2 + \bar{\Theta}.$$

Differentiating $ss^{-1} = E$ repeatedly twice, E being identity matrix, then we have

$$d^2 s s^{-1} + s d^2 s^{-1} = 0,$$

and consequently, that $d^2s=0$ is equivalent to $d^2s^{-1}=0$. Hence we have the followings

THEOREM 3. *There exists the linear correspondence between the frames A and \bar{A} on $\mathcal{G}^{(0)}$ and its inverse, if, and only if, the curvature form (2.7) is preserved. Therefore (2. 5) and (2. 6) are equivalent to (2.7).*

Next, since $T=0$ in $\mathcal{G}^{(0)}$, we have

$$(2, 8) \quad dD = D\Omega.$$

From this, we obtain the followings:

$$(2, 6) \quad \begin{aligned} d^{2m}D &= (-1)^m D\Theta^m, \\ d^{2m+1}D &= (-1)^m D\Theta^m\Omega. \end{aligned} \quad (m \geq 1)$$

In fact, for $m=1$, it is satisfied by differentiation of (2, 8) to use of (0, 4), for the general case it can be shown by induction on using of the Bianchi identities [3]. And we may compute

$$\begin{aligned} d\bar{\Theta} &= d(s\Theta s^{-1}) = \bar{\Omega}s\Theta s^{-1} - s\Theta s^{-1}\bar{\Omega} \\ &= \bar{\Omega}\bar{\Theta} - \bar{\Theta}\bar{\Omega}, \end{aligned}$$

and generally,

$$(2.10) \quad d\bar{\Theta}^m = \bar{\Omega}\bar{\Theta}^m - \bar{\Theta}^m\bar{\Omega}. \quad (m \geq 1).$$

Differentiating (1. 2), we have

$$dD = dDs^{-1} - D(\Omega s^{-1} - s^{-1}\bar{\Omega}) = \bar{D}\bar{\Omega},$$

and using of (2. 10), then we have that (2. 9) is preserved by (1. 1). Hence we obtain the following:

THEOREM 4. *For the linear correspondence between the frames A and \bar{A} on $\mathcal{G}^{(0)}$, the Bianchi identities (2.10), (2. 7), (2. 8) and (2. 9) are preserved.*

Dec. 1960

Mathematical Department

Kyungpook University

REFEERENCES

- [1] H. Flanders: *Developement of an extended exterior different calculus*. Trans. Amer. Math. Soci. vol. 75 (1953). pp. 311-326.
- [2] N. Horie: *On the group space of the continuous-transformation group with Riemannian metric*. Memo. Coll. Scie. Univ. Kyoto. vol. XXX, No. 1 (1956).
- [3] J. K. Ahn: *On the parameter group manifolds*. Kyungpook Math. Jour. vol. 2. No. 2 (1959).