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The Recognition of a Human Arm Gesture for a Game Interface

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HMM(Hidden Markov Model)

1. 가
(Dynamic Time Warping, DTW) , (Conditional
(HMM)
Random Field, CRF) [3-5].
가
1 3
가
[1]. HMM
10 10
가 10 가
2
3
4
5
가

2.

2.1 HMM(Hidden Markov Model)

3 가 HMM 1960 1970 Baum 가
가 Microsoft Kinect RGB, HMM 가
[2]. , DNA
HMM
가 [6].

Notation: $\lambda = (A, B, \Pi)$ (1)

$N = \text{Number of States}$ (2)

$M = \text{Number of symbols observable in States}$
 $V = \{v_1, \dots, v_m\}$ (3)

$A = \text{State transition probability distribution}$
 $A = \{a_{ij}\}, 1 \leq i, j \leq N$ (4)

$B = \text{Observation symbol probability distribution}$
 $B = \{b_i(v_k)\}, 1 \leq i \leq N, 1 \leq k \leq M$ (5)

$\tilde{O} = \text{Initial State distribution}$
 $\pi_i = p(q_1 = i), 1 \leq i \leq N$ (6)

HMM 가 가
 가 () 가

HMM

3.

A, B, \tilde{O}

$$A = |a_{ij}|$$

$$a_{ij} = P(q_{t+1} = s_j | q_t = s_i), 1 \leq i, j \leq N$$

$$\sum_{j=1}^n a_{ij} = 1 \quad (7)$$

$$B = |b_j(v_k)|$$

$$b_j = P(O_t = v_k | q_t = s_j), 1 \leq j \leq N, 1 \leq k \leq M$$

$$\sum_{k=1}^m b_j(v_k) = 1 \quad (8)$$

$$\Pi = |\pi_i|$$

$$\pi_i = P(q_1 = s_i), 1 \leq i \leq N$$

$$\sum_{i=1}^n \pi_i = 1 \quad (9)$$

HMM

2.2 Kinect

가 Kinect
 Fig 1 3

20 가

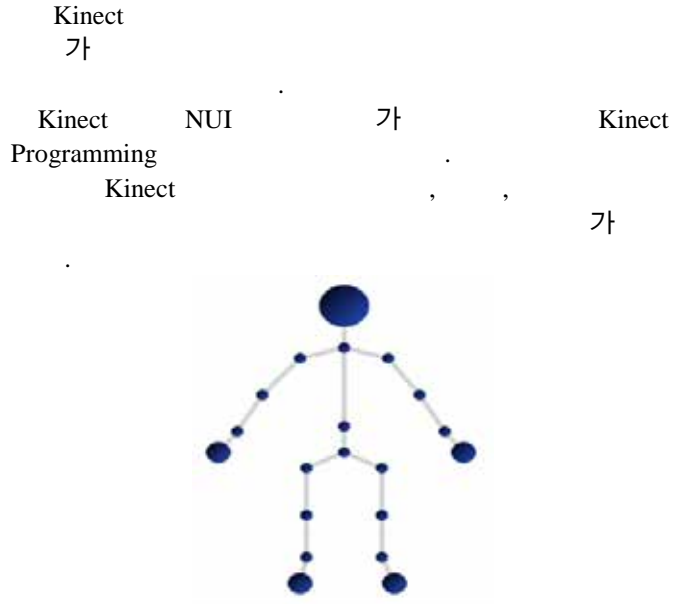


Fig 1. Human Skeleton

Fig 2

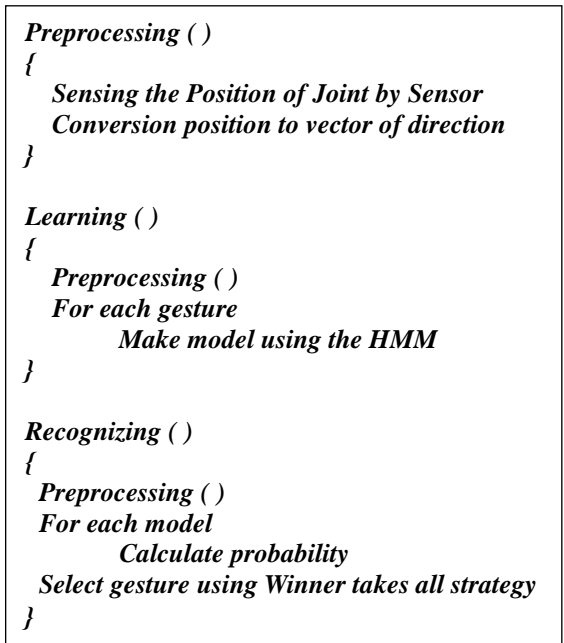


Fig 2. System Process

Fig 3
 3, t, t+1
 가 x, y, z 가 3가
 27 가 3x3x3

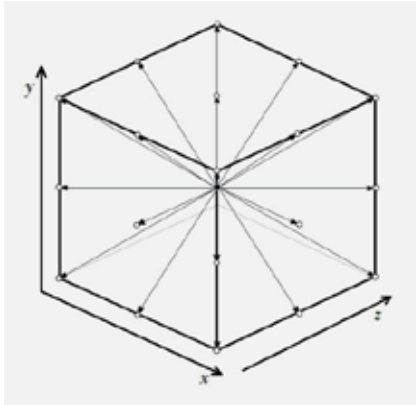


Fig 3. Understandable Direction

4.
 4.1

Windows C/C++
 Microsoft Kinect, SDK 1.7
 10 10
 Fig 4 10

No.	Gesture	No.	Gesture
A		F	
B		G	
C		H	

D		I	
E		J	

Fig 4. Sign Language Motion

100 HMM 50%
 50%
 Fig 5 A
 E False Negative 가 A E A
 Fig 5

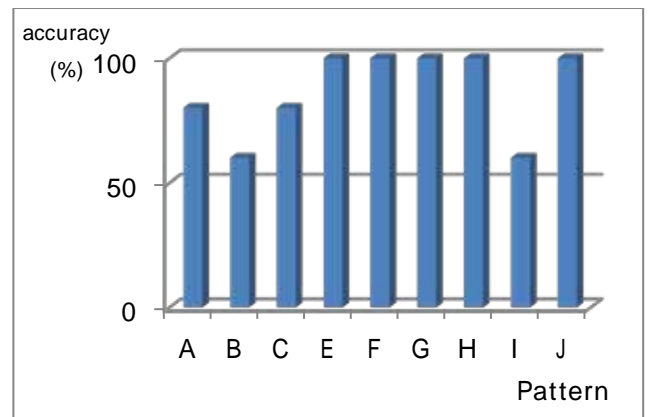


Fig 5. Average accuracy rate (%)

가 88%

Table 1

가

Table 1. Account for error (%)

Pattern	Selected	Rate
A	E	20%
B	G	40%
C	F	20%
I	D	20%
I	C	20%

Table 1 Pattern , Selected
 80% , 20% A
 C 20% I 40% E D

5.

가 ,
 가 HMM
 10 HMM
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 가 ,
 가 .

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 8 9 (2005).
 [2] , “ ” ,
 39 10 , (2012.10)
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