

Fig.1 CIP MRE

$$\Delta G \quad (21)$$

$$\Delta G = 12\mu_0\phi_p\mu_m\left(\frac{R}{d}\right)H_0^2 \times \frac{(\mu_p - \mu_m)^2}{\sqrt{1 + \varepsilon^2} [3\sqrt{1 + \varepsilon^2}(\mu_p + \mu_m) - 4\frac{R}{d}(\mu_p - \mu_m)]^2} \quad (1)$$

μ_0 가 (1)

(2) MRE MRE Fig. 2

$$k^* = \frac{G_{MRE}A}{h} \quad (2)$$

h MRE 가 Oscillator 가

$$G_{MRE} = 2\pi^2 f_n^2 \frac{mh}{A} \quad (3)$$

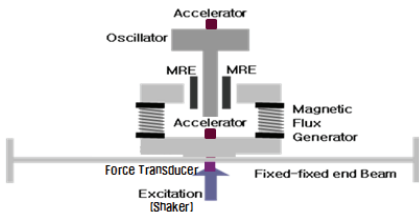


Fig. 2. The Shear Modulus Measurement system.

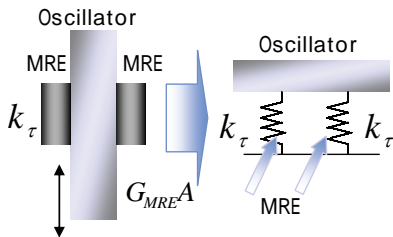


Fig. 3. Mathematical modeling of MRE and oscillator

3.

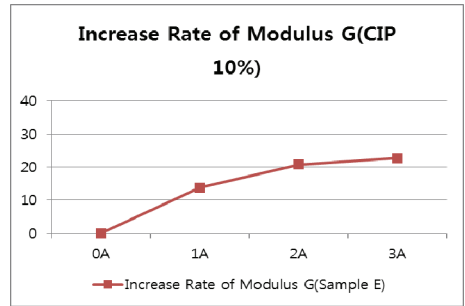


Fig. 4. Increase Ratio of Shear modulus(CIP10%)

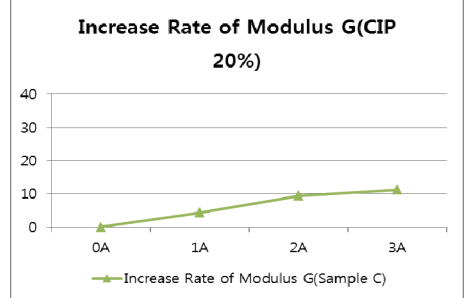


Fig 5. Increase Ratio of Shear modulus(CIP20%)

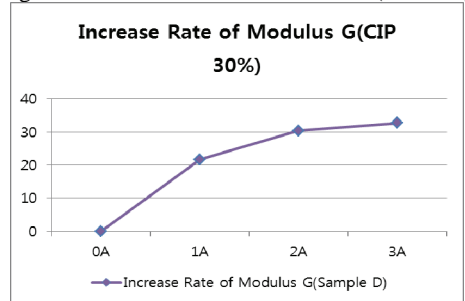


Fig. 6. Increase Ratio of Shear modulus(CIP30%)

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CIP 10%,CIP20%,CIP30% 가

CIP30% 3A

가 가

4.

MRE

MRE

CIP 30%

CIP

3A