

LSV 측정 정보를 이용한 ODS 와 OMA 의 동시분석 방법

How to get Operating Deflection Shape (ODS) and Operational Modal Analysis (OMA) with single measurement using LSV

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Key Words : Operational Modal Analysis(운전 중 동적 특성), Operating Deflection Shape(운전 중 변형 형상),

1.

(, ,) 가
 가
 (ODS)
 Analysis (OMA)
 ODS
 White Noise 가
 ODS
 가
 noise
 OMA
 OMA
 EM4SYS Laser
 Scanning Vibrometer (LSV)
 ODS OMA

2.1 Operating Deflection Shape (ODS) (ODS) 가

ODS FRF [1].

$$\text{ODS FRF} = \frac{G_{y_{ref}y_i}}{|G_{y_{ref}y_i}|} \sqrt{G_{y_iy_i}} \times \frac{1}{M} \sum_{m=1}^M G_{y_{ref}y_{ref}} \quad (1)$$

(1) $G_{y_{ref}y_i}$ i node
 Cross $G_{y_iy_i}$ i node
 Auto M

2.2 Operational Modal Analysis (OMA)

Domain Decomposition(FDD)
 [2,3]. FDD
 (FRF)

Frequency

$$[G_{yy}(\omega)] = [H(\omega)]^H [G_{xx}(\omega)] [H(\omega)]^T \quad (2)$$

$[G_{xx}(\)]$ Input , $[G_{yy}(\)]$
 Output , $[H(\)]$
 (FRF) $[G_{xx}(\)]$ 가
 white noise 가 (2)

$$[G_{yy}(\)] = [V][S][V]^H \quad (3)$$

(3) Output Singular
 Value Decomposition(SVD)

2.

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$$[G_{y_{ref}y_i}(\omega)] = [V][S][V]^H \quad (3)$$

$$[G_{y_{ref}y_i}(\omega)] = [V][S][V]^H \quad (4)$$

$$(4) \quad [G_{Y_{ref}Y_1}(\omega)]$$

i node
Cross

LMS CADA - X

(1) ODS
(4) OMA

	1st Mode	2nd Mode	3rd Mode	4th Mode	5th Mode
Hammering test	22Hz	50Hz	63.5Hz	82Hz	158Hz
OMA	28Hz	50Hz	66Hz	84Hz	158Hz

3. OMA

4. OMA

3.1 OMA

4

OMA 가
가

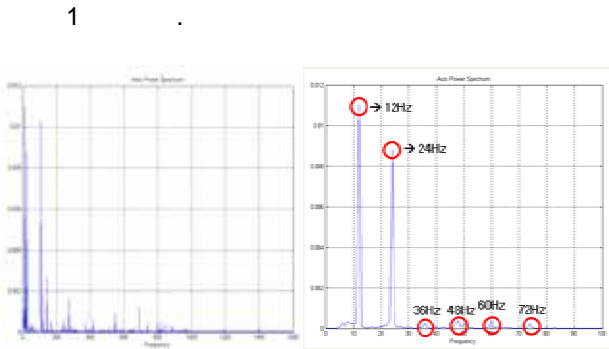
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Modal Assurance Criterion (MAC)

OMA \ CADA-X	$\{\psi\}_1$	$\{\psi\}_2$	$\{\psi\}_3$	$\{\psi\}_4$	$\{\psi\}_5$
$\{\psi\}_1$	0.98273	0.06188	0.041013	0.036478	0.02415
$\{\psi\}_2$	0.02451	0.987455	0.041013	0.032891	0.01541
$\{\psi\}_3$	0.023777	0.08089	0.93237	0.126	0.126
$\{\psi\}_4$	0.0097108	0.019525	0.036478	0.91887	0.057609
$\{\psi\}_5$	0.032891	0.058354	0.10896	0.023777	0.91887

1. Modal Assurance Criterion (MAC) (CADA - X & OMA)

표 1을 통해서 OMA와 해머링 테스트 간의 결과가 거의 일치하는 것을 확인할 수 있다.



1. Power spectrum. (a) 0 - 100Hz. (b) 0 - 1600Hz (b)

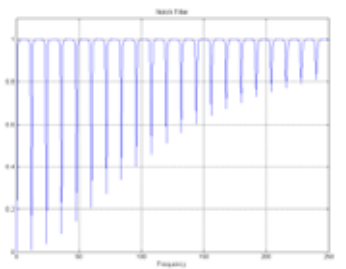
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ODS OMA 가

1.(a) Auto
1.(b) (a)
12Hz 1.(b)

가

OMA
OMA



2. (12Hz)

OMA

5.

2 SVD OMA

3.2

OMA

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