

가 가

가 ,

[5]

3D model

[6][7][8][9][10]

[11][12]

[13][14]

Cutting simulation

3D

가 가

(i.e.

가)

CAD/CAM

Unigraphics Open API

3D solid model

Table 1 End-milling cutter parameters

\varnothing_1	1'st relief angle	D	Radius of inner circle
γ	Rake angle	\varnothing_2	2'nd relief angle
R	Chamfer length	D_2	Shank Diameter
\varnothing_3	Helix angle	D_1	Cutter Diameter
L_1	Cutter length	L_2	Shank length
L_3	Overall length	Nf	Number of flute

Fig. 1

가 가

(Helical flute shape)

(Neck groove shape)

가

가

가

가

(e.g., setting angle, wheel center point)

Fig. 2

(Section profile)



Fig. 2 Helical groove and neck part of a cutter

Fig. 3

Pw

가 CL data

xw , yw

(a)

2. Dimensional parameters

Fig. 1

, Table 1

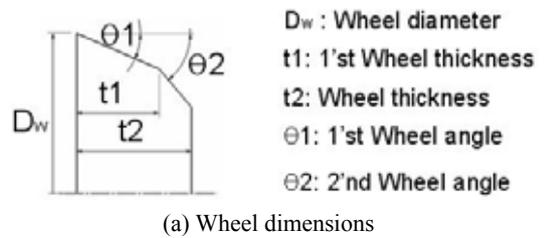
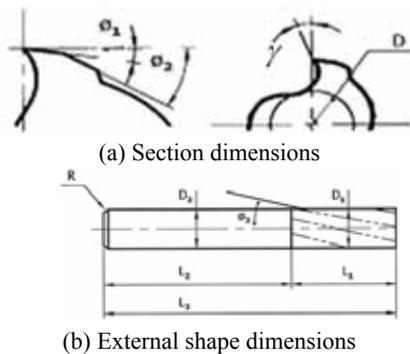


Fig. 1 Basic geometry of end-milling cutter

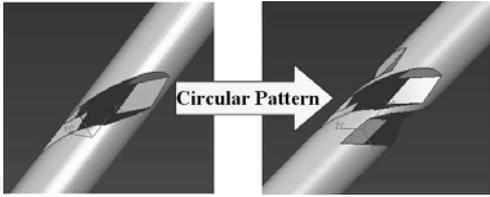


Fig. 6 Neck part model by boolean operation

3.2 Helical flute part modeling

4.1

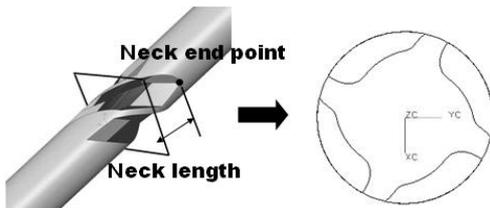


Fig. 7

Fig. 7 Extraction of sectional profile curve

Fig. 8

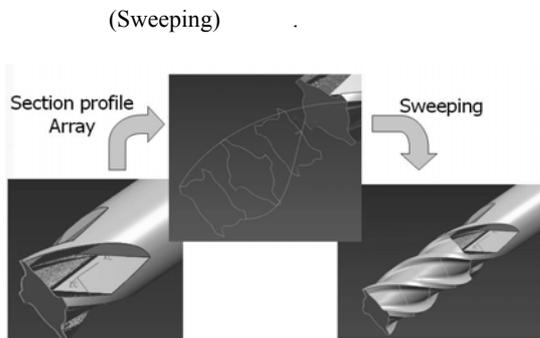


Fig. 8 Helical flute modeling

3.3 Computation of cutter geometry

Fig. 9a

Fig. 9b

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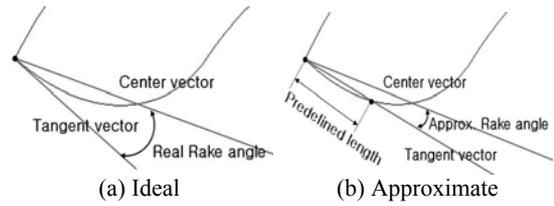


Fig. 9 Definition for rake angle

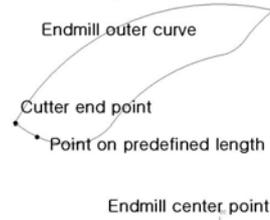


Fig. 10 Points data to calculate rake angle

Cutter end point

Fig. 5

Cutter end point 가

Point on predefined length

(Fig. 10)

bisection method

Cutter end point, Point on predefined length, Endmill center point

bisection

Cutter end

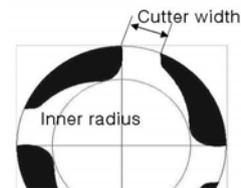


Fig. 11 Inner radius and cutter width

Fig. 11

(Cw)

가

Cutter end point

4. Prediction of wheel geometry and positioning data

4 Fig. 3a

Fig. 3b

CL

(wheel setting angle, center point, offset value)

cutting simulation

3D

5. Illustrated example

4 cutting simulation

Boolean

가

CAD/CAM

Unigraphics Open API

(intersection body)

6.1 Shape modeling

Fig. 15 Fig. 16

GUI

3D

Table 3

4

6Ø

Fig. 16

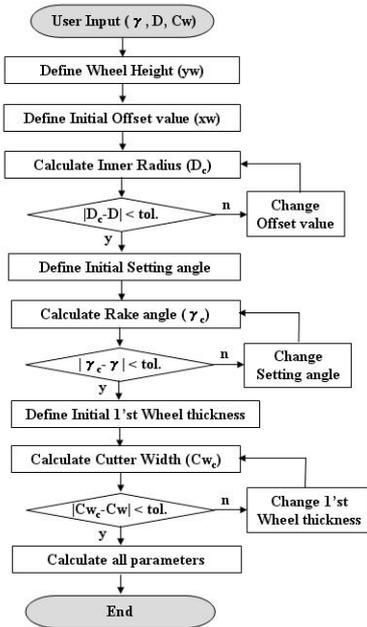


Fig. 14 Prediction of wheel geometry and position

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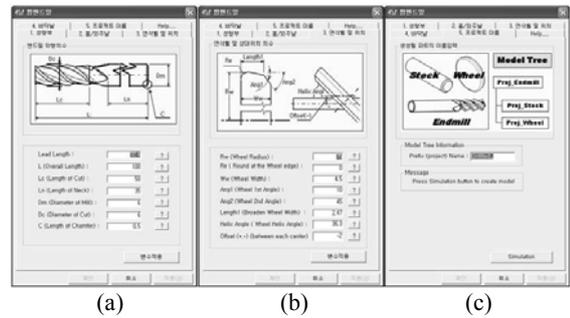


Fig. 15 User Interface: (a) End-mill dimensions, (b) Wheel dimensions and position (c) Auxiliary Input data

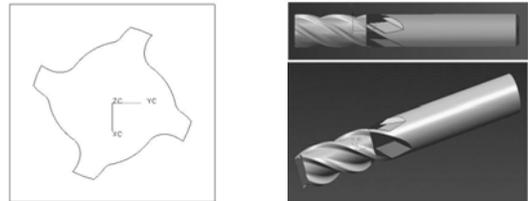


Fig. 16 Section profile curve and solid model

0.1~0.2mm

1

가

(t2, θ1, θ2)

(e.g., t2 = 1.8 t1, θ1 = 10°, θ2 = 45°).

Table 2

Table 3 Design and machining parameters

Dim.	value	Dim.	value	Dim.	value
Ø3	30.03	D	1.89	R	0.5
D2	6.0	α	36.3	D1	6.0
L1	35	L _{neck}	15	L2	50
Dw	150	t1	2.47	t2	4.5
θ1	10	θ2	45	Do	-2.0
Pw	Xw=-2.0, Yw=76.09, Zw=0.0				

method)

3~4

가

(false position

simulation

5.914°, 1.991mm

(6°, 1.89mm)

가

6.2 Prediction of wheel geometry and position

Fig. 17



Fig. 17 Wheel geometry simulation window

Table 4 Fig. 14

Table 5

4 2.8GHz CPU

20

Fig. 18

RP machine

Table 4 Input parameters for wheel geometry

Dim.	Value	Dim.	value	Dim.	value
Di	6.0	Ø3	30.03	Nf	4
γ	6.0	D	1.89	Cw	0.9
$\theta 1$	10.0	$\theta 2$	45.0	Tol.	0.01

Table 5 Search result

Dim.	Value	Dim.	value	Dim.	value
Pw(yw)	1.79	Pw(xw)	-2.093	α	37.641
t1	2.135	t2	3.843	γ	6.01
D	1.884	Cw	0.90		

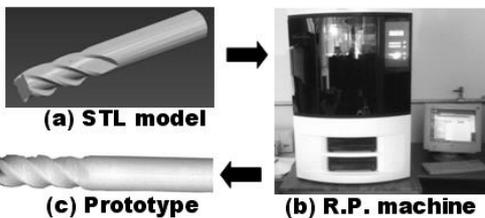


Fig. 18 Rapid Prototyping of the end-milling cutter

7. Conclusions

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cutting simulation

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