

RMQC

* . *

Simulation Program for Advanced RMQC

Suk-Hwan Hwang and Jae-Seung Choi

Key Words : RMQC (), Critical path (), Hoist (),
Trolley ()

Abstract

RMQC, rail mounted quay crane, lifts and moves large container by means of hoist and trolley motion on the dock. Our company is trying to develop advanced RMQC applying the concepts of elevator hoist and container conveyer for the automation and high efficiency in handling the boxes. Prior to the development of new products, it is necessary to check the capacity of the new systems using simulation program. The program simulates container-handling rates and gives some design factors for the new-type cranes.

1.

RMQC Rail Mounted Quay Crane

(Container)

RMQC

. RMQC

가

RMQC

2. Crane Motion

(1,2)

가 . Fig. 1

RMQC

Fig. 2

(3-5)

가

가 , ,

RMQC

가

Path,

Critical

RMQC

(Critical Path)

*

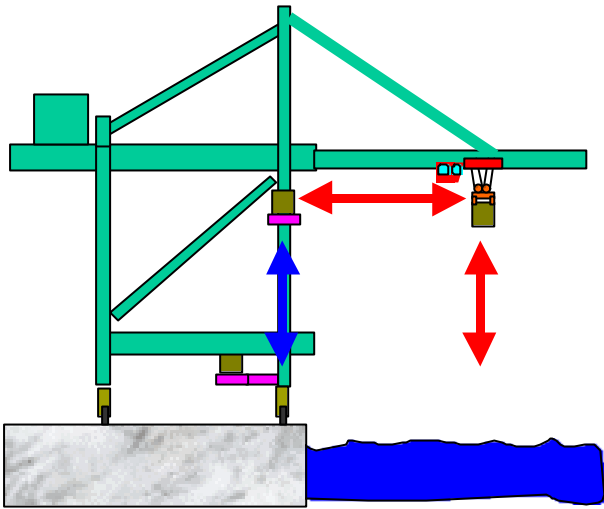
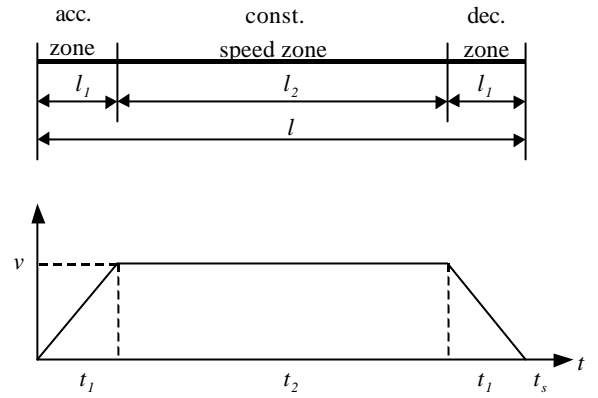
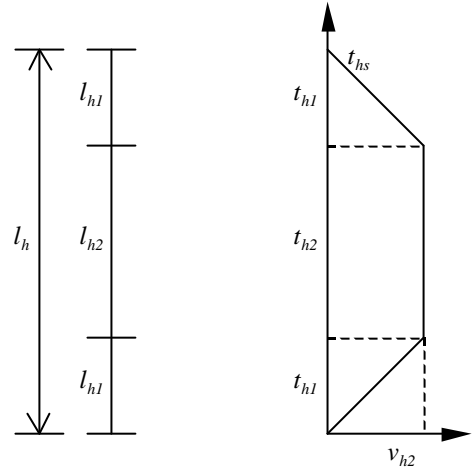


Fig. 1 Advanced RMQC system



(a) Trolley motion



(b) Hoist motion

Fig. 2 Crane motion

Critical Path
RMQC
(Deck) 2
Critical Path

RMQC

가

3.

$$T = \sum(T_1 + T_2 + T_3) \quad (1)$$

where, T_1 = time (hoist and trolley) for one cycle
 T_2 = time (elevator) for one cycle
 T_3 = delay time for one cycle

RMQC

$$H = \frac{N}{T} \times 3600 \quad (2)$$

where, N = number of container box (ea.)
 T = total handling time (sec.)

RMQC

MS Visual Basic 6.0

(8), 9

Flow

Chart Fig. 3
가

, Feedback

(), () 3

RMQC

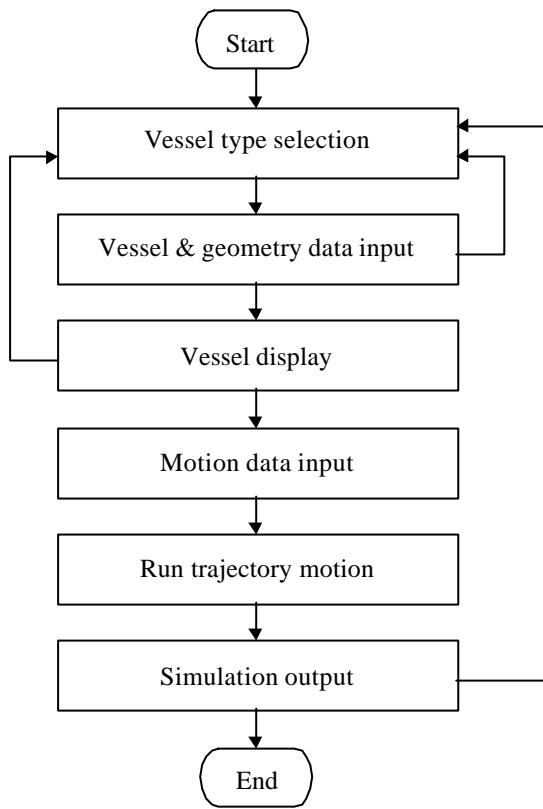


Fig. 3 Flow chart of simulation program

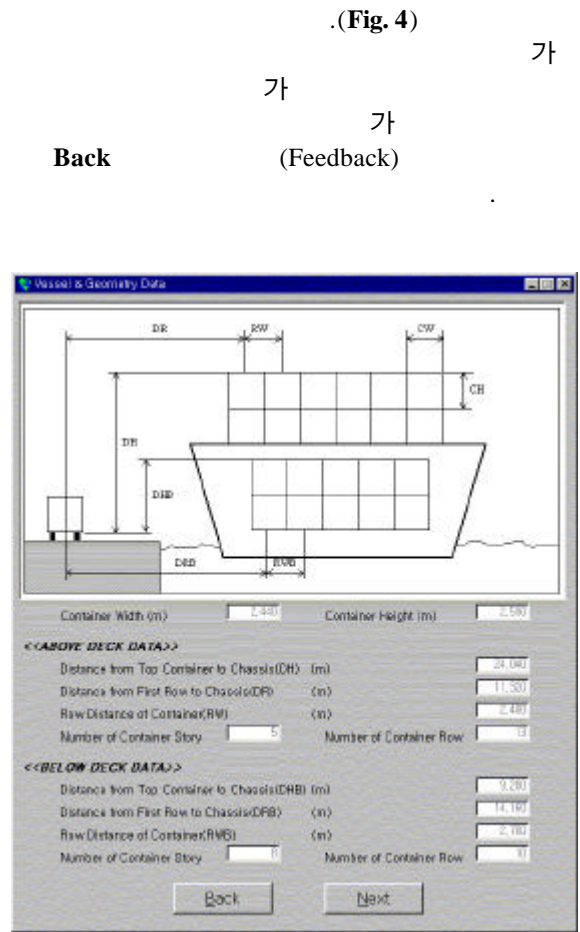


Fig. 4 Vessel and geometry data window

3.1 가 Scroll

a) 가 , , Critical Path

b) 가 , , 가

c) , , 가

(Manual Input) 가

3 가 , 가

가 , 가

Pana-Max 가 Meter



Fig. 5 Motion data window



Fig. 6 Trajectory motion window

가 . Critical Path, Delay Time,

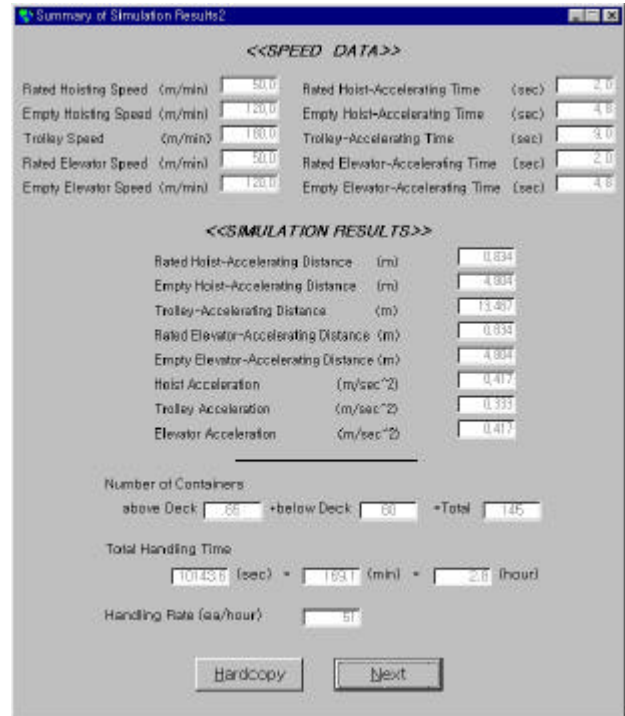


Fig. 7 Summary of simulation results

(Second) (m/min) (Pre-Processing)

3.2 Trajectory Motion

Fig. 6

Run

1 가 (1 Cycle Time),

가

Next

가

3.3

3

가

(Geometry, Critical Cycle Path, Delay Time)

, Hardcopy

가

Fig. 7

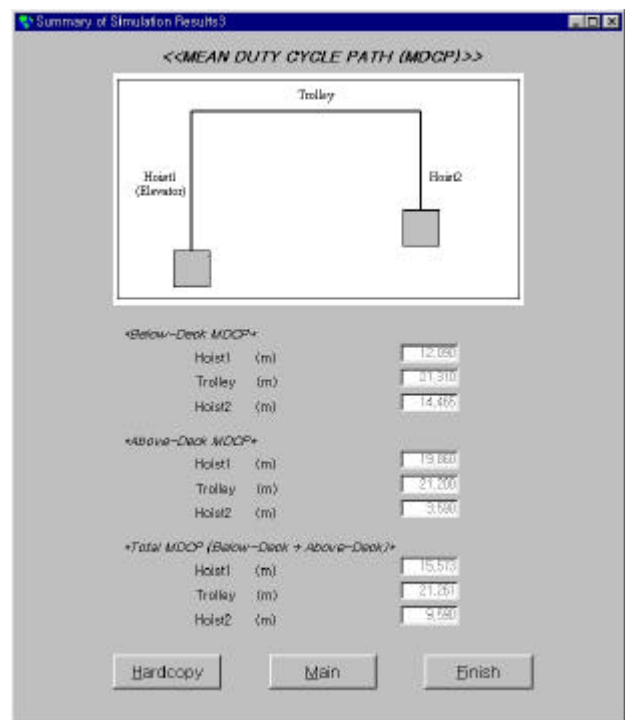


Fig. 8 Mean duty cycle path

, Mean Duty Cycle Path
 . Mean Duty Cycle Path
 , Above-Deck, Below-Deck, Total
 가
 (Hoist1),
 (Hoist2) (Mean Duty Cycle Path)
 Mean
 Duty Cycle Path .(Fig. 8)
Main

4.

RMQC

5.

RMQC
 가

- (6) Doosan, 2002, *Development of Advanced RMQC Simulation Program*, Doosan Heavy Industries and Constructions.
- (7) Choi, J. S., and Hwang, S. H., 2003, "Development of RMQC Simulation Program," KSPE, Spring Conference, pp. 1622 ~ 1625.
- (8) MS, 1998, *Mastering Microsoft Visual Basic 6.0 Development*, Microsoft.

- (1) Gerstel, Arnold, 2001, "Container Cranes for 8000 TEU & Larger Vessels," TOC Asia Conference Documentation, Session Six, pp. 1 ~ 9.
- (2) Franke, Klaus-Peter, 2000, "Improving Inland Terminal Productivity through Intelligent Crane Operations," TOC 2000 Conference Documentation, Track Two, pp. 1 ~ 8.
- (3) Park, C. H., Kim, D. H., and Park, K. T., 2001, "Anti-Sway System for Automated Crane," KSPE, Fall Conference, pp. 446~449.
- (4) Samsung, 1994, *Development of Advanced Container Crane Product*, 903C-364G, Samsung Heavy Industries.
- (5) Samsung, 1994, *Development of Advanced Container Crane Product*, 903C-364F, Samsung Heavy Industries.