

퍼지구의 수렴성

Convergence of Fuzzy Spheres

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요약

원형함수를 사용하여 퍼지구를 정의하고 원형함수의 수렴을 이용하여 퍼지구의 수렴성을 측정하며 하나의 퍼지구는 특정한 일반 구로 수렴함을 보인다.

Abstract

The concept of a circularity function is used in defining fuzzy spheres. The circularity function of a fuzzy sphere converges to one of a crisp sphere as the fuzzy sphere shapes itself more and more like a crisp sphere.

I. Introduction

In this paper, we experiment with developing fuzzy geometry by limiting process of the notion of fuzzy sphere whose degree of circularity function is measured by a fuzzy set. The concept of a circularity function is also used in defining the union, intersection, and complement of fuzzy spheres. The circularity function of a fuzzy sphere converges to one of a crisp sphere as the fuzzy sphere shapes itself like a crisp sphere.

Let X be a nonempty crisp set. A fuzzy subset μ of X is a function from X into the closed unit interval $[0, 1]$, that is, $\mu: X \rightarrow [0, 1]$. In the literature, a fuzzy set may also be written as a set of ordered pairs: $\{(x, \mu(x)): x \in X\}$, where $\mu(x)$ is referred to as the membership function or grade of membership.

II. Fuzzy Spheres

Motivated by the concept of equations of motion we can specify surfaces in the three-dimensional xyz -space by using equations, $x = x(s, t)$, $y = y(s, t)$, $z = z(s, t)$, to express the coordinates of a point (x, y, z) on the surface as functions of auxiliary variables s and t . These are called parametric equations for the surface, and the variables s and t are called parameters. Let S be the surface consisting of all ordered triplets $(x(s, t), y(s, t), z(s, t))$ on the xyz -space, where $x(s, t)$, $y(s, t)$ and $z(s, t)$ are continuous real valued functions defined on a closed two dimensional rectangular region R .

Let $P(s, t) = (x(s, t), y(s, t), z(s, t))$ for $(s, t) \in R$. The surface S is called a closed surface if for any two points on S , there exists a space curve C that connects the two points such that $C \subset S$. If a closed surface S does not intersect itself at any other point on the xyz

-space, then S is called a simple closed surface. Spheres and ellipsoids are typical examples of simple closed surfaces.

Definition 2.1. A function $\mu_{\mathfrak{S}}: R \rightarrow [0, 1]$ is called a circularity function of S if

- (1) there exists a function $f: R \times R \times R \rightarrow [0, 1]$ such that $\mu_{\mathfrak{S}}(s, t) = f(x(s, t), y(s, t), z(s, t))$ for all $(s, t) \in R$,
- (2) $0 \leq \mu_{\mathfrak{S}}(s, t) \leq 1$ for $(s, t) \in R$,
- (3) $\mu_{\mathfrak{S}}(s, t) = 1$ for all $(s, t) \in R$ when S is a sphere.

Clearly, $\mu_{\mathfrak{S}}(s, t)$ is a fuzzy subset of R . Intuitively, the circularity function $\mu_{\mathfrak{S}}(s, t)$ can be thought of as a numerical measure of the degree of circularity for simple closed surface on the xyz -space.

Definition 2.2. Let S be a simple closed surface on the xyz -space defined as above. A fuzzy sphere on the xyz -space is given by

$$\mathfrak{S} = \{((x(s, t), y(s, t), z(s, t)), \mu_{\mathfrak{S}}(s, t)) | (s, t) \in R\}$$

where

- (1) $x(s, t)$, $y(s, t)$, and $z(s, t)$ are continuous parametric functions on R that define S ,
- (2) $\mu_{\mathfrak{S}}(s, t)$ is a circularity function on S .

A fuzzy sphere is formed by a simple closed surface S together with a circularity functions $\mu_{\mathfrak{S}}(s, t)$, $(s, t) \in R$.

If S is a crisp sphere, then the corresponding fuzzy sphere must have the maximum degree of circularity, that is, $\mu_{\mathfrak{S}}(s, t) = 1$, for $(s, t) \in R$. $\mu_{\mathfrak{S}}(s, t)$ can also be used as a measure in comparing two fuzzy spheres.

Definition 2.3. Let \mathfrak{S}_1 and \mathfrak{S}_2 be two fuzzy spheres with circularity functions $\mu_{\mathfrak{S}_1}(s, t)$ and $\mu_{\mathfrak{S}_2}(s, t)$, respectively. Then

- (1) \mathfrak{S}_1 is called a fuzzy subsphere of \mathfrak{S}_2 , written as $\mathfrak{S}_1 \leq \mathfrak{S}_2$, if $\mu_{\mathfrak{S}_1}(s, t) \leq \mu_{\mathfrak{S}_2}(s, t)$ for all $(s, t) \in R$.
- (2) \mathfrak{S}_1 is said to be equal to \mathfrak{S}_2 , written as $\mathfrak{S}_1 \simeq \mathfrak{S}_2$, if $\mathfrak{S}_1 \leq \mathfrak{S}_2$, $\mathfrak{S}_2 \leq \mathfrak{S}_1$, that is, $\mu_{\mathfrak{S}_1}(s, t) \leq \mu_{\mathfrak{S}_2}(s, t)$ and $\mu_{\mathfrak{S}_2}(s, t) \leq \mu_{\mathfrak{S}_1}(s, t)$ for all $(s, t) \in R$.

We can find that the relation \simeq is an equivalence relation and if S_0 is a crisp sphere in the xyz -space, then $\mathfrak{S} \leq \mathfrak{S}_0$ for any simple closed surface S on the xyz -space. In other words, \mathfrak{S}_0 is the strongest fuzzy sphere.

Let S_1 be a simple closed surface given parametrically in terms of ordered triplets $(x_1(s, t), y_1(s, t), z_1(s, t))$ for $(s, t) \in R$, where $x_1(s, t)$, $y_1(s, t)$, and $z_1(s, t)$ are real valued continuous functions on R , and let \mathfrak{S}_1 be the fuzzy sphere that is formed by S_1 with the circularity function $\mu_{\mathfrak{S}_1}(s, t)$. Likewise, let S_2 be a simple closed surface given parametrically in terms of ordered triplets $(x_2(s, t), y_2(s, t), z_2(s, t))$ for $(s, t) \in R$, where $x_2(s, t)$, $y_2(s, t)$, and $z_2(s, t)$ are real valued continuous functions on R , and let \mathfrak{S}_2 be the fuzzy sphere that is formed by S_2 with the circularity function $\mu_{\mathfrak{S}_2}(s, t)$. Assume that the union and intersection of S_1 and S_2 are also simple closed surfaces.

- (1) The union of \mathfrak{S}_1 and \mathfrak{S}_2 , denoted by $\mathfrak{S}_1 \cup \mathfrak{S}_2$, is defined to be the fuzzy sphere

$$\mathcal{S}_1 \cup \mathcal{S}_2 = \{((x^*(s, t), y^*(s, t), z^*(s, t)), \mu_{\mathcal{S}_1 \cup \mathcal{S}_2}(s, t)) | (s, t) \in R\}$$

where the circularity function $\mu_{\mathcal{S}_1 \cup \mathcal{S}_2}(s, t)$ is given by

$$\begin{aligned} \mu_{\mathcal{S}_1 \cup \mathcal{S}_2}(s, t) &= (\mu_{\mathcal{S}_1} \vee \mu_{\mathcal{S}_2})(s, t) \\ &= \mu_{\mathcal{S}_1}(s, t) \vee \mu_{\mathcal{S}_2}(s, t) \end{aligned}$$

and $(x^*(s, t), y^*(s, t), z^*(s, t))$ denotes the parametric representation of $\mathcal{S}_1 \cup \mathcal{S}_2$.

(2) The intersection of \mathcal{S}_1 and \mathcal{S}_2 , denoted by

$$\begin{aligned} \mathcal{S}_1 \cap \mathcal{S}_2, \text{ is defined to be the fuzzy sphere} \\ \mathcal{S}_1 \cap \mathcal{S}_2 = \{((x_*(s, t), y_*(s, t), z_*(s, t)), \mu_{\mathcal{S}_1 \cap \mathcal{S}_2}(s, t)) | (s, t) \in R\} \end{aligned}$$

where the circularity function $\mu_{\mathcal{S}_1 \cap \mathcal{S}_2}(s, t)$ is given by

$$\begin{aligned} \mu_{\mathcal{S}_1 \cap \mathcal{S}_2}(s, t) &= (\mu_{\mathcal{S}_1} \wedge \mu_{\mathcal{S}_2})(s, t) \\ &= \mu_{\mathcal{S}_1}(s, t) \wedge \mu_{\mathcal{S}_2}(s, t) \end{aligned}$$

and $(x_*(s, t), y_*(s, t), z_*(s, t))$ denotes the parametric representation of $\mathcal{S}_1 \cap \mathcal{S}_2$.

(3) The complement of \mathcal{S} , denoted by \mathcal{S}^c , is defined to be the fuzzy sphere

$$\mathcal{S}^c = \{((x(s, t), y(s, t), z(s, t)), \mu_{\mathcal{S}^c}(s, t)) | (s, t) \in R\}$$

with the circularity function $\mu_{\mathcal{S}^c}(s, t)$ given by $\mu_{\mathcal{S}^c}(s, t) = 1 - \mu_{\mathcal{S}}(s, t)$

For $n = 1, 2, \dots$, let \mathcal{S}_n be a simple closed surface given parametrically in terms of ordered triplets $(x_n(s, t), y_n(s, t), z_n(s, t))$ for $(s, t) \in R$, where $x_n(s, t), y_n(s, t)$, and $z_n(s, t)$ are real valued continuous functions on R , and let \mathcal{S}_n be the fuzzy sphere that is formed by \mathcal{S}_n with the

circularity function $\mu_{\mathcal{S}_n}(s, t)$. Assume that the union and intersection of \mathcal{S}_n is also simple closed surfaces. Then the union of a sequence $\{\mathcal{S}_n\}$ of fuzzy spheres, denoted by $\bigcup_{n=1}^{\infty} \mathcal{S}_n$, is defined as the fuzzy sphere

$$\begin{aligned} \bigcup_{n=1}^{\infty} \mathcal{S}_n = \{((x^*(s, t), y^*(s, t), z^*(s, t)), \mu_{\bigcup_{n=1}^{\infty} \mathcal{S}_n}(s, t)) | (s, t) \in R\} \end{aligned}$$

where the circularity function $\mu_{\bigcup_{n=1}^{\infty} \mathcal{S}_n}(s, t)$ is given by

$$\mu_{\bigcup_{n=1}^{\infty} \mathcal{S}_n}(s, t) = (\bigvee_{n=1}^{\infty} \mu_{\mathcal{S}_n})(s, t) = \bigvee_{n=1}^{\infty} \mu_{\mathcal{S}_n}(s, t)$$

and $(x^*(s, t), y^*(s, t), z^*(s, t))$ denotes the parametric representation of $\bigcup_{n=1}^{\infty} \mathcal{S}_n$. Also, the intersection of a sequence $\{\mathcal{S}_n\}$ of fuzzy spheres, denoted by $\bigcap_{n=1}^{\infty} \mathcal{S}_n$, is defined as the fuzzy sphere

$$\begin{aligned} \bigcap_{n=1}^{\infty} \mathcal{S}_n = \{((x_*(s, t), y_*(s, t), z_*(s, t)), \mu_{\bigcap_{n=1}^{\infty} \mathcal{S}_n}(s, t)) | (s, t) \in R\} \end{aligned}$$

with the circularity function $\mu_{\bigcap_{n=1}^{\infty} \mathcal{S}_n}(s, t)$ given by

$$\mu_{\bigcap_{n=1}^{\infty} \mathcal{S}_n}(s, t) = (\bigwedge_{n=1}^{\infty} \mu_{\mathcal{S}_n})(s, t) = \bigwedge_{n=1}^{\infty} \mu_{\mathcal{S}_n}(s, t)$$

and $(x_*(s, t), y_*(s, t), z_*(s, t))$ denotes the parametric representation of $\bigcap_{n=1}^{\infty} \mathcal{S}_n$.

Theorem 2.4. [8] Let $\mathcal{S}_1, \mathcal{S}_2$ and \mathcal{S}_3 be fuzzy spheres with circularity functions $\mu_{\mathcal{S}_1}(s, t), \mu_{\mathcal{S}_2}(s, t)$, and $\mu_{\mathcal{S}_3}(s, t)$, respectively. Then

- (1) $\mathcal{S}_1 \cap \mathcal{S}_2 \leq \mathcal{S}_1 \cup \mathcal{S}_2$
- (2) $(\mathcal{S}_1 \cup \mathcal{S}_2) \cup \mathcal{S}_3 \approx \mathcal{S}_1 \cup (\mathcal{S}_2 \cup \mathcal{S}_3)$
- (3) $(\mathcal{S}_1 \cap \mathcal{S}_2) \cap \mathcal{S}_3 \approx \mathcal{S}_1 \cap (\mathcal{S}_2 \cap \mathcal{S}_3)$

- (4) $\mathfrak{S}_1 \cup (\mathfrak{S}_2 \cap \mathfrak{S}_3) \simeq (\mathfrak{S}_1 \cup \mathfrak{S}_2) \cap (\mathfrak{S}_1 \cup \mathfrak{S}_3)$
- (5) $\mathfrak{S}_1 \cap (\mathfrak{S}_2 \cup \mathfrak{S}_3) \simeq (\mathfrak{S}_1 \cap \mathfrak{S}_2) \cup (\mathfrak{S}_1 \cap \mathfrak{S}_3)$
- (6) $\mathfrak{S}_1 \leq \mathfrak{S}_2 \Rightarrow \mathfrak{S}_2^c \leq \mathfrak{S}_1^c$
- (7) $\mathfrak{S}_1^c \cup \mathfrak{S}_2^c \simeq (\mathfrak{S}_1 \cap \mathfrak{S}_2)^c$
- (8) $\mathfrak{S}_1^c \cap \mathfrak{S}_2^c \simeq (\mathfrak{S}_1 \cup \mathfrak{S}_2)^c$

Corollary 2.5. [8] Let \mathfrak{S} be a fuzzy spheres with circularity function $\mu_{\mathfrak{S}}(s, t)$, and let $\mathfrak{S}_n (n = 1, 2; \dots)$ be a sequence of fuzzy spheres with circularity functions $\mu_{\mathfrak{S}_n}(s, t) (n = 1, 2, \dots)$, respectively. Then

- (1) $\bigcap_{n=1}^{\infty} \mathfrak{S}_n \leq \bigcup_{n=1}^{\infty} \mathfrak{S}_n$
- (2) $\mathfrak{S} \cup (\bigcap_{n=1}^{\infty} \mathfrak{S}_n) \simeq \bigcap_{n=1}^{\infty} (\mathfrak{S} \cup \mathfrak{S}_n)$
- (3) $\mathfrak{S} \cap (\bigcup_{n=1}^{\infty} \mathfrak{S}_n) \simeq \bigcup_{n=1}^{\infty} (\mathfrak{S} \cap \mathfrak{S}_n)$
- (4) $\bigcup_{n=1}^{\infty} \mathfrak{S}_n^c \simeq (\bigcap_{n=1}^{\infty} \mathfrak{S}_n)^c$
- (5) $\bigcap_{n=1}^{\infty} \mathfrak{S}_n^c \simeq (\bigcup_{n=1}^{\infty} \mathfrak{S}_n)^c$

III. Convergence of Fuzzy Spheres

For each $n = 1, 2, \dots$, let

$$\mathfrak{S}_n = \{ ((x_n(s, t), y_n(s, t), z_n(s, t)), \mu_{\mathfrak{S}_n}(s, t)) | (s, t) \in R \}$$

be a fuzzy sphere with the circularity functions $\mu_{\mathfrak{S}_n}(s, t)$. Also, let

$$\mathfrak{S} = \{ ((x(s, t), y(s, t), z(s, t)), \mu_{\mathfrak{S}}(s, t)) | (s, t) \in R \}$$

be a fuzzy sphere with the circularity function $\mu_{\mathfrak{S}}(s, t)$.

Definition 3.1. The sequence $\{\mathfrak{S}_n\}$ of fuzzy spheres is said to converge in the sense of

circularity to the fuzzy sphere \mathfrak{S} if $\mu_{\mathfrak{S}_n}(s, t)$ converges to $\mu_{\mathfrak{S}}(s, t)$ for all $(s, t) \in R$.

Theorem 3.2. Let $\mathfrak{S}_1 \leq \mathfrak{S}_2 \leq \dots \leq \mathfrak{S}_n \leq \dots$ be a non-decreasing sequence of fuzzy spheres. Then $\{\mathfrak{S}_n\}$ converges in the sense of circularity to the fuzzy sphere $\bigcup_{n=1}^{\infty} \mathfrak{S}_n$.

Lemma 3.3. Let R is a two-dimensional rectangular region, and $\{f_n\}, \{g_n\}$ are sequences of real-valued functions defined on R . Let f, g are real-valued functions such that $f_n \rightarrow f$ and $g_n \rightarrow g$ on R . Then $f_n \vee g_n$ converges to $f \vee g$ on R .

Theorem 3.4. Let $\{\mathfrak{S}_n\}$ and $\{\mathfrak{T}_n\}$ converge in the sense of circularity to the fuzzy sphere $\mathfrak{S}, \mathfrak{T}$ respectively. Then $\{\mathfrak{S}_n \cup \mathfrak{T}_n\}$ converges in the sense of circularity to the fuzzy sphere $\mathfrak{S} \cup \mathfrak{T}$.

Definition 3.5. The scalar multiple of \mathfrak{S} , denote by $\alpha\mathfrak{S}$, is defined to be the fuzzy sphere

$$\alpha\mathfrak{S} = \{ ((x(s, t), y(s, t), z(s, t)), \mu_{\alpha\mathfrak{S}}(s, t)) | (s, t) \in R \}$$

with the circularity function $\mu_{\alpha\mathfrak{S}}(s, t) = (\alpha, \mu_{\mathfrak{S}})(s, t) = \alpha \cdot \mu_{\mathfrak{S}}(s, t)$ and $0 \leq \alpha \leq 1$.

Theorem 3.6. Let $\{\mathfrak{S}_n\}$ be a sequence of fuzzy spheres, and $\{\mathfrak{S}_n\}$ converges in the sense of circularity to the fuzzy sphere \mathfrak{S} . Then $\{\alpha\mathfrak{S}_n\}$ converges in the sense of circularity to the fuzzy sphere $\alpha\mathfrak{S}$.

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