

멀티레벨 PWM ac/dc 컨버터의 향상된 단락보호기법 해석

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Analysis of An Improved Short-circuit Protection for Multilevel PWM ac/dc Converter

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ABSTRACT

This paper describes an improved short-circuit protection for a multilevel ac/dc power converter. The output dc power of the proposed converter can be disconnected from the load within several hundred microseconds at the instant of short-circuit fault. Once the fault has been cleared the dc power is reapplied to the load. The rising time of the dc load voltage is as small as several hundred microseconds, and there is no overshoot of the dc voltage because the dc output capacitors hold undischarged state. Therefore, the proposed converter can be used for a power supply, which requires a rapid disconnection of the load from the power supply in the case of a short circuit, as well as a rapid connection the load to the power supply after the clearance of the short circuit condition.

1. Introduction

An ac/dc power converter with special load such as an ion source requires excellent protective function at the time of load fault besides a precise regulation performance. The converter is different from the conventional power supply, its load - ion source will experience frequent spark downs. To protect both the ion source and the converter from the source short-circuit current, some methods of diverting current from the source and disconnecting the source from the accel power supply are necessary.

Many efforts have been made to satisfy the

above requirements. At first, to obtain a high speed switching and protective function at the time of load fault, a tetrode was used as a switching element. GTO thyristors were used as a dc side switching element to overcome some problems of a tetrode. High voltage power supplies without dc side GTO switch were proposed to improve the performance [1,2].

Recently, multilevel PWM converters have been proposed as one of the practical solutions in high voltage and high power applications [3]. To obtain a high speed switching performance at the time of load fault, modified boost type multilevel converter was proposed [4,5].

This paper describes a new PWM rectifier suitable for a load with frequent short-circuit to improve the performance of the output short-circuit protection. The proposed circuit operation and characteristics are described, analysed, and simulated.

2. Operating Principle of the Proposed Circuit

2.1 Proposed circuit diagram

Fig. 1 shows the generalized multilevel ac/dc converter of the proposed scheme. The circuit diagram is basically similar to that of the conventional multilevel converter. Switches Sa, Sb, and Sc are inserted in the ac input side. Each filter capacitor of the conventional multilevel converter is replaced with a series connected switch (Sol~Son) and capacitor (C1~Cn), and one switch Sdc is inserted in the positive dc side. A resistor Rdc is connected to

the terminals of collector and emitter of the switches Sdc and So1, respectively.

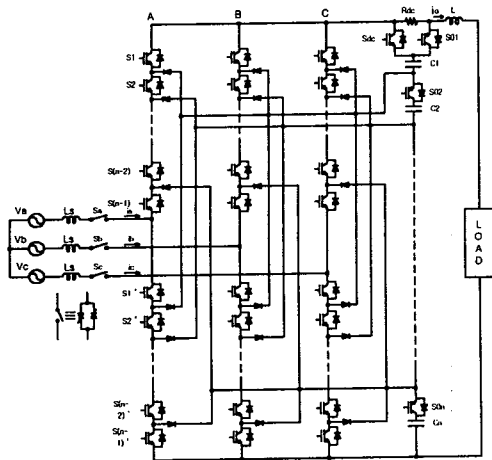


Fig. 1 Multilevel ac/dc converter of the proposed scheme

2.2 Operating principle

To simplify the explanation of the proposed circuit operation 2-level ac/dc converter is shown in Fig. 2. The basic operating principle of the converter in Fig. 2 is the same as that in Fig. 1. In normal operating mode, all the auxiliary switches of Sa, Sb, Sc, Sdc, and So keep on state while the main switches are turned on/off according to the generated PWM signals from a controller. The switching state of the switching devices following a sudden dc output short-circuit changes as shown in Fig. 3. The switching state of each device, load voltage, and output dc current waveform in each time interval are described as follows.

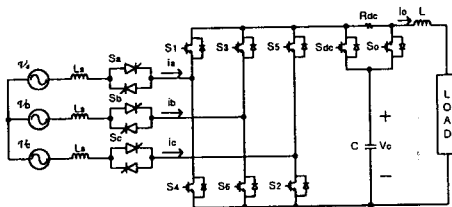


Fig. 2 2-level ac/dc converter of the proposed scheme

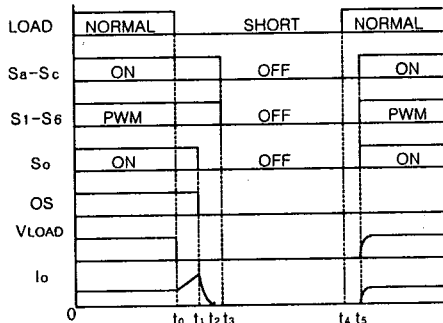


Fig. 3 Switching state, output voltage and current waveform

1) $t_0 \leq t < t_1$

During this mode, the output dc current i_o increases linearly as follows.

$$i_o(t) = i_o(t_0) + \frac{V_c}{L}(t - t_0), \quad t_0 \leq t \leq t_1 \quad (1)$$

2) $t_1 \leq t < t_2$

At time t_1 , the dc current i_o reaches a previously set up output short-circuit current level of I_{os} . As soon as the OS signal becomes low gating signals for thyristors. Sa, Sb, and Sc are turned off and the power flow direction of the PWM converter is reversed. The magnitudes of ac line currents of i_a , i_b , and i_c , under regeneration mode, decrease as follows.

$$i_a(t) = -(i_b(t) + i_c(t)) \quad (2)$$

$$i_b(t) = i_b(t_1) - \frac{1}{2LS} \int_{t_1}^t (V_c - v_{ab}) dt \quad (3)$$

$$i_c(t) = i_c(t_1) - \frac{1}{2LS} \int_{t_1}^t (V_c - v_{ac}) dt \quad (4)$$

During this mode the output current through inductor L decreases as follows.

$$i_o(t) = i_o(t_2) e^{-\frac{t-t_2}{\tau_l}}, \quad t_2 \leq t \leq t_3 \quad (5)$$

where $\tau_l = \frac{L}{R_{dc}}$ and the diode voltage drops of the main switches are neglected.

3) $t_2 \leq t < t_3$

In this mode, the decrease of the three phase ac line currents of i_a , i_b , and i_c continues until the magnitudes of the currents become zero.

4) $t_3 \leq t < t_4$

There is no need of PWM switching in the main switches S1~S6. Thus, there is no current flow from ac or dc source to the load under the condition where the load keeps short-circuit.

5) $t_4 \leq t < t_5$

The short-circuit condition is cleared at time t_4 , and thus, the load becomes normal state. It is necessary to connect the dc source to the load again. The output dc current increases as

follows after the dc source is applied to the load.

$$i_o(t) = \frac{V_c}{R_L} (1 - e^{-\frac{t}{\tau_2}}) \quad (6)$$

where $\tau_2 = \frac{L}{R_L}$ and R_L is a load resistance.

3. Input and Output Current Analysis

3.1 AC input line current

The fundamental component of input current i_a is

$$i_a(t) = \sqrt{2} I_a \sin(\omega t) \quad (7)$$

The line current vanishing mechanism following an output short-circuit repeats with the same pattern every 60 degrees in one cycle of $i_a(t)$. The specific values of i_a , i_b , and i_c are now introduced for 60 degrees.

1) $60^\circ \leq \omega t < 90^\circ$

In (3) and (4), let

$$V_1 = V_c - v_{ab} \quad (8)$$

$$V_2 = V_c - v_{ac} \quad (9)$$

In this phase angle interval, V_1 and i_c are smaller than V_2 and i_b , respectively. As a result, the first line current to be vanished among three phase currents is i_c . A required time for the i_c to be zero can be calculated from (4). In (4),

$$v_{ac}(t) = \sqrt{2} V \sin(\omega t - \frac{\pi}{6}) \quad (10)$$

Fig. 4 shows the required time t_{co} with the variation of L_s under full load condition. AC input line voltage, line current, and output dc voltage are 220V, 10.5A, and 400V, respectively. As soon as the line current i_c reduces to zero, the magnitude of the other two line currents i_a and i_b become equal as follows.

$$i_a(t) = -i_b(t) = -i_b(t'_{co}) + \frac{1}{2L_s} \int_{t'_{co}}^t (V_c - v_{ab}) dt \quad (11)$$

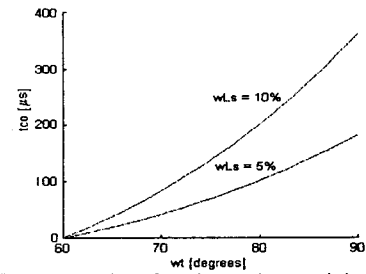


Fig. 4 Required time for i_c to be vanished ($60^\circ \leq \omega t < 90^\circ$)

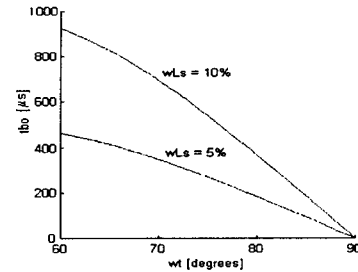


Fig. 5 Required time for i_a and i_b to be vanished after i_c becomes zero ($60^\circ \leq \omega t < 90^\circ$)

where a time instant of t'_{co} corresponds to a time t_{co} . Fig. 5 shows the time duration under the same condition as is used in Fig. 4.

2) $90^\circ \leq \omega t < 120^\circ$

In this interval, the magnitude of V_2 and i_b is smaller than that of V_1 and i_c , respectively. Accordingly, the i_b becomes zero first. Through a similar calculating procedure that used in the interval of $60^\circ \leq \omega t < 90^\circ$ t_{co} and t_{bo} are calculated.

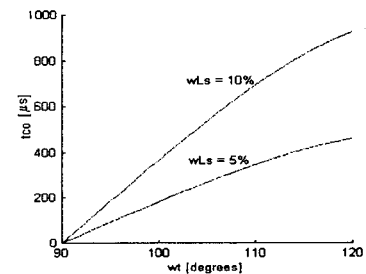


Fig. 6 Required vanishing time of i_b ($90^\circ \leq \omega t < 120^\circ$)

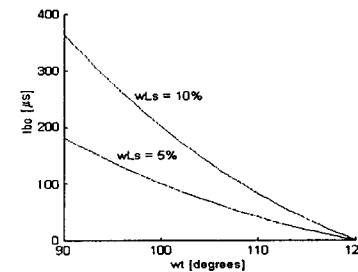


Fig. 7 Required time for i_a and i_c to be vanished after i_b becomes zero ($90^\circ \leq \omega t < 120^\circ$)

Fig. 6 and 7 show the resulting values.

3.2 DC output current

The dc output current begins to increase after the instant of a short-circuit as in (1). As soon as the switch S_o is turned off, the output current begins to decrease through an altered path, which comprises L, load, diodes which are anti-parallel connected to the IGBTs, and R_{dc} .

4. Simulation Results

The output switching characteristic of the proposed power converter is simulated with the following parameters. The ac input line-to-line voltage = 220 V, $L_s = 2$ mH, $R_{dc} = 300 \Omega$, C_1 , $C_2 = 2,200 \mu F$, $L = 2$ mH, output dc voltage = 400 V, and load resistance = 40Ω . Fig. 8(a) shows the load current I_o . Fig. 8(b) shows the detailed output current waveform around 20ms. The increasing time interval is $25 \mu s$ and the discharging time interval is almost $30 \mu s$.

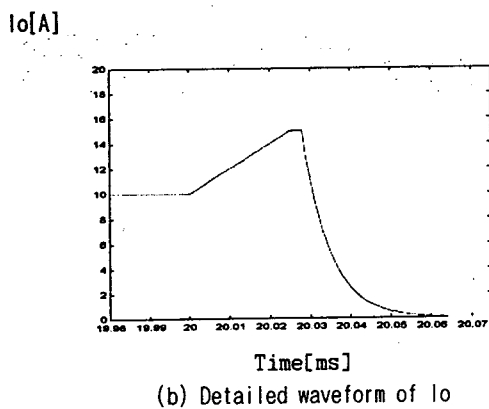
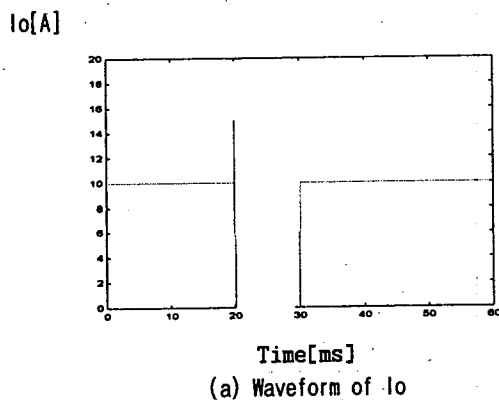


Fig. 8 Waveforms of I_o in the case of a load short-circuit

5. Conclusion

A new multilevel ac/dc converter suitable for a short-circuit protection is described. The major features of the proposed scheme are summarized as follows:

- 1) Simplified structure compared with the conventional inverter type power supply.
- 2) High speed disconnection a dc source from a short-circuit load without damage.
- 3) Rapid connection of a dc source to a normal load with reduced load voltage build up time.
- 4) Negligible switching losses of the auxiliary switches.
- 5) Reasonable input and output current magnitude.

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