

A Study On the Beat-To-Beat QT Interval Measurement

T. S. Jung, J. M. Lee, *K. S. Park

Interdisciplinary program, Medical and biological Engineering major, Seoul Nat'l University

*Department of Biomedical Engineering, College of Medicine, Seoul National University

Abstract

ECG analysis is main techniques for diagnosing heart disease. In recent, some studies have been performed about detection of QT interval. But, it's difficult to detect QT interval because T wave is evasive. In this paper, we have detected peak point and end point of T wave and calculated QT interval. And the result has been compared with the other algorithm after detection of QT interval.

Introduction

Q point and T point must be detected accurately to calculate QT interval. Because the frequency of R wave is mainly high, R peak detection is not difficult even with noise. Therefore there are many algorithms about R wave detection. But T wave detection with noise is difficult because it has low frequency component and therefore there are not accurate detection algorithms. Further more, detection of T end point is very difficult in Holter ECG data, not in resting state data.

In this paper, we show an algorithm that use derivative and low-pass filtered ECG signal and morphology of each T-wave, and compare its performance with that of other algorithms

Method

Generally detection points in T wave are peak point(T_p) and end point(T_e). We detect two point and calculate two QT intervals(QT_p , QT_e). The procedure of calculating QT interval is as follows.

1. R peak point detection

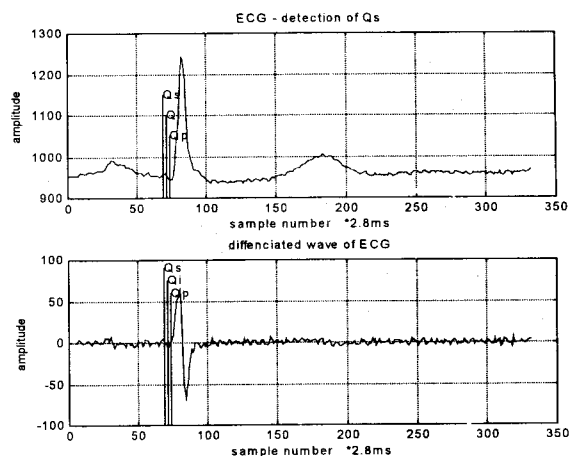
First, we use the R peak detection algorithm(by Pan and Tompkins, 1985) to detect R peak. This algorithm has 6 steps as follows:

low-pass filtering, differentiation, squaring, moving window, integral(140ms), adaptive threshold.

2. Q peak point(Q_p) and QRS starting point(Q_s)

Second, we search Q_p backwards from R_p . In the differentiated ECG signal $d(k)$, Q_p is defined at first backward zero-crossing point from R_p . But, we think that the Q wave is not present when the distance between Q_p and R_p exceeds 80ms.

Q_s (QRS starting point) is defined as the beginning of Q wave or R wave(if Q wave is not present). (by P. Laguna, 1990) We search Q_i that is defined as the point has maximum slope using backward searching from Q_p in $d(k)$. Then, Q_s is defined as the point that meets threshold H_q , $d(Q_i)/2$, backward. Similarly, we search R_i has maximum slope in $d(k)$ when Q wave is not present. And in that case, threshold, H_q , is applied as $d(R_i)/5$.



<Figure.1> Detection of Q_p, Q_i, Q_s

3. T wave detection

T wave has 4 different kinds in differentiated signal:

- 1) normal T-wave(upward-downward),
- 2) inverted T-wave(downward-upward),
- 3) only-downward T-wave,
- 4) only-upward T-wave

We search maximum(T_{max}) and minimum(T_{min}) point in $f(k)$ preprocessed from $d(k)$ by low-pass filter at cut-off frequency, 20Hz, using window has two limits(start, end point) forward from R_p . It has several steps as follows to detect T_p , T_e .

- a. If $d(T_{max}) < d(T_{min})$, then 1) or 4).
- a-1. If $|T_{max}| > 4|T_{min}|$, then 4)
- a-2. Else 1).
- b. If $d(T_{max}) > d(T_{min})$, then search T_{mina} is defined as minimum point in $d(k)$ backward from $d(T_{max})$.
- b-1. If $|T_{max}| < 4|T_{mina}|$, then 1).
- b-2. If $|T_{min}| > 4|T_{max}|$, then 3).
- b-3. Else 2).

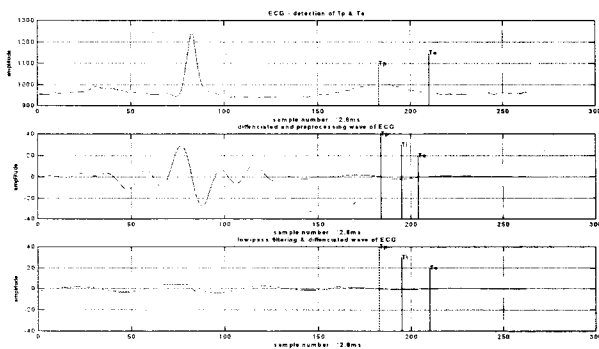
Now, we search T_p and T_e using T_{max} , T_{min} and the shape of T wave(case 1-4). In each case, we define T_i as the last sufficiently large point(T_{min} or T_{max} or T_{mina}). From T_i , T_p is defined as the first zero crossing point in $f(k)$ backward. Next, T_e is defined as the point meets threshold H_t , $f(T_i)/4$ forward from T_i .

Modified Processing

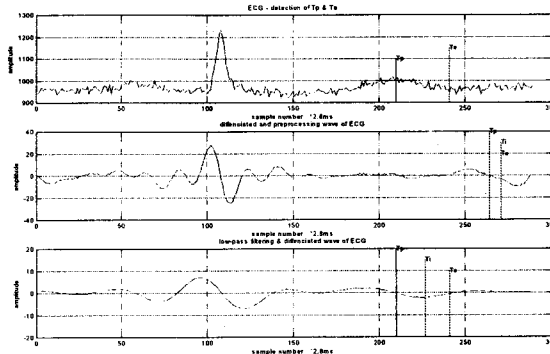
This method is not correct if noise is added. We cannot find T_p and T_e from T_{max} , T_{min} or T_{mina} in $f(k)$ in noisy signal. There are many zero-crossing and T_{max} (or T_{min} , T_{mina}) is not helpful because noise has high frequency component but T wave has only low frequency component. Therefore, we must remove high frequency noise to search correct T wave.

Of course, we have filtered $d(k)$ using low-pass filter before R peak detection($f(k)$, cut-off frequency: 20Hz). But, the noise between T wave frequency (5Hz) and QRS complex frequency (20Hz), isn't removed.

Therefore, we filter original signal using low-pass filter has cut-off frequency at 5-10Hz. After Q wave is detected using original signal, the filter is used before T wave detection. This filter removes QRS complex. And this signal is used to detect T_p and T_e . This method is compared with before method in Figure.2(without noise) and in Figure 3(with noise).



<Figure.2> T detection comparison without noise



<Figure.3> T detection comparison with noise

4. QT interval calculation

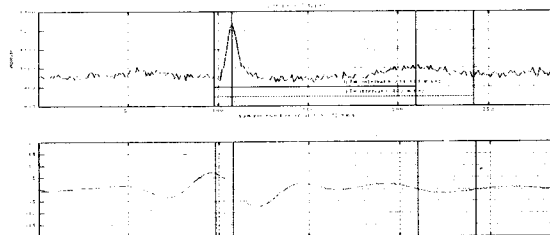
Now, we can calculate QT interval with T_p, T_e and Q_s . We define QTP as an interval between Q_s and T_p . And we also define QTE as an interval between Q_s and T_e . We can calculate QTE and QTP using

$$QTE = T_e - Q_s$$

$$QTP = T_p - Q_s$$

Result and Discussion

To calculate QT interval, we used MIT/BIH Database. Figure 3 plots ECG signal and two differentiated signal of MIT/BIH 101st. And also show the QT interval.



<Figure.3> QT interval detection

The result has been compared with the other algorithm. (Threshold, Differential Threshold, Slope Intercept, Peak Slope Intercept) And the result also has been compared with the result of manual measurements.

Reference

- 1] P.Laguna: New Algorithm for QT interval analysis in 24-hour Holter ECG: performance and applications, Med. & Bio. Eng. & Comput, 1990,28, 67-73
- 2] Algra A, le Brun H: An algorithm for computer measurement of QT interval in the 24 hour ECG. Computers in cardiology 1986.IEEE Computer Society Press, 117-119
- 3] Critelli, G: QT interval measurements of long-term ECG recordings. Application to an automatic Holter analysis system. In Computers in Cardiology,IEEE Computer Society Press, 481-480.